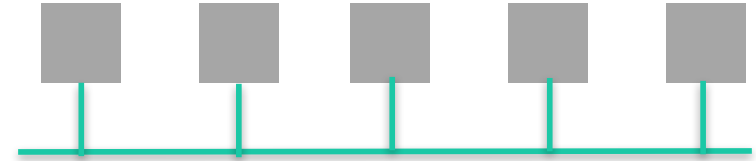


# Ethernet, AVB, and TSN introduction

# Ethernet (CSMA/CD)



- Created in the mid 70s
- Ethernet bus: shared media access
- 46 to 1500 byte payloads; 10 Mbps to 10 Gbps
- Node transmits as soon as medium is free
- Collisions can occur during the interval of one slot after start of transmission (512 bits)
- Jamming signal (32 bits) is sent in case of collisions
- Retransmission after random amount of time
- Outdated
- Not appropriate for real-time systems

# Switched Ethernet

- IEEE 802.1D and 802.1p. Now all in 802.1Q with Virtual LANs (VLANs) and priority queues
- Better but still gaps for real-time and safety-critical systems:
  - Priority inversions in FIFO queues
  - Interference through shared memory
  - Additional forwarding delay with address learning and flooding
  - Delays vary with switch technology
  - “Plug and Play” has been the mindset: lots of protocols that are not appropriate for real-time (long delays and nondeterminism)

# Ethernet frame format

## 802.3 Ethernet packet and frame structure

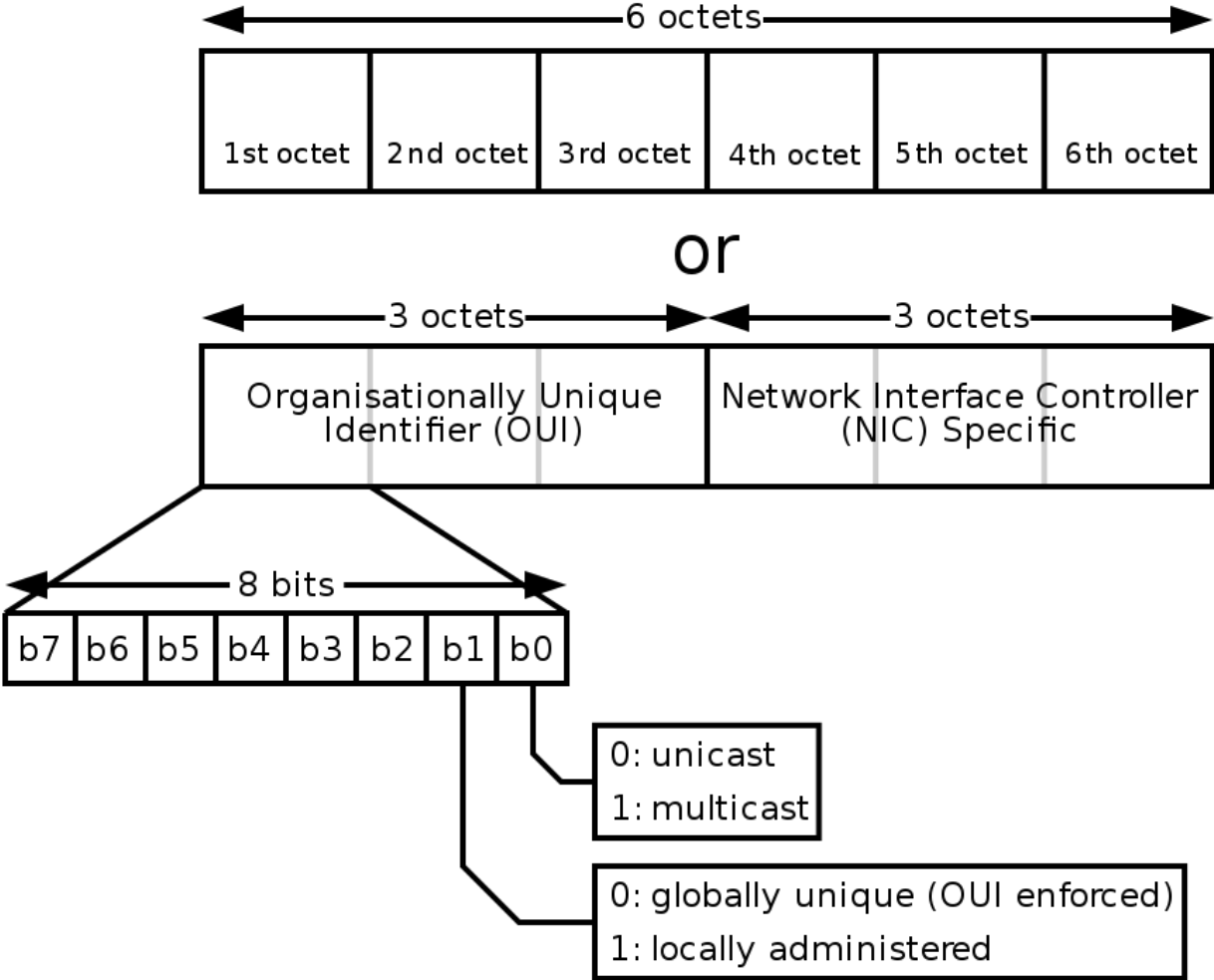
Layer	Preamble	Start of frame delimiter	MAC destination	MAC source	802.1Q tag (optional)	Ethertype (Ethernet II) or length (IEEE 802.3)	Payload	Frame check sequence (32-bit CRC)	Interpacket gap
	7 octets	1 octet	6 octets	6 octets	(4 octets)	2 octets	46-1500 octets	4 octets	12 octets
Layer 2 Ethernet frame			← 64–1522 octets →						
Layer 1 Ethernet packet & IPG	← 72–1530 octets →								← 12 octets →

## 802.1Q tag format

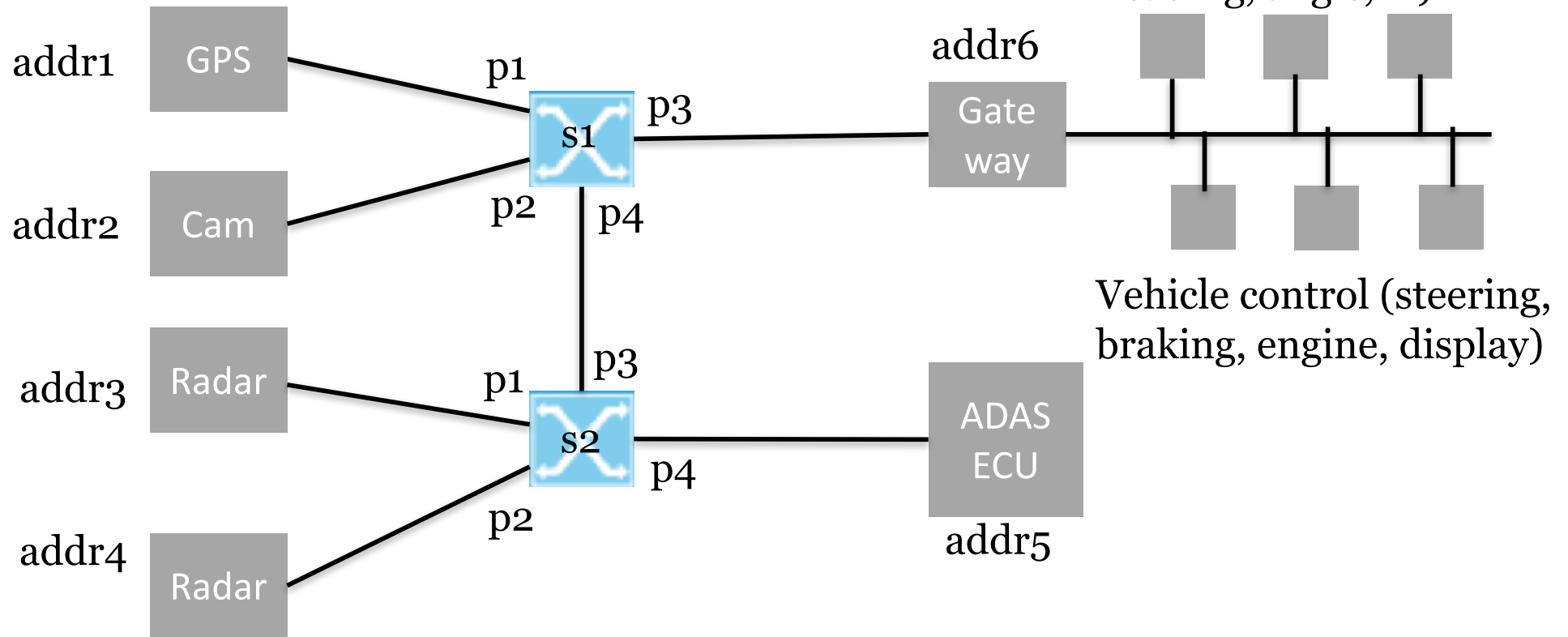
16 bits	3 bits	1 bit	12 bits
TPID	TCI		
	PCP	DEI	VID

- Unicast frames (Direct addressing of the (only) receiver)
- Multicast frames (when there are multiple receivers)
  - Some reserved for Layer 2 protocols (e.g., Spanning Tree Protocol and Precision Time Protocol)
  - AVB and TSN streams are typically multicast
- Broadcast frames (FF:FF:FF:FF:FF:FF)
  - Flood frame on all ports

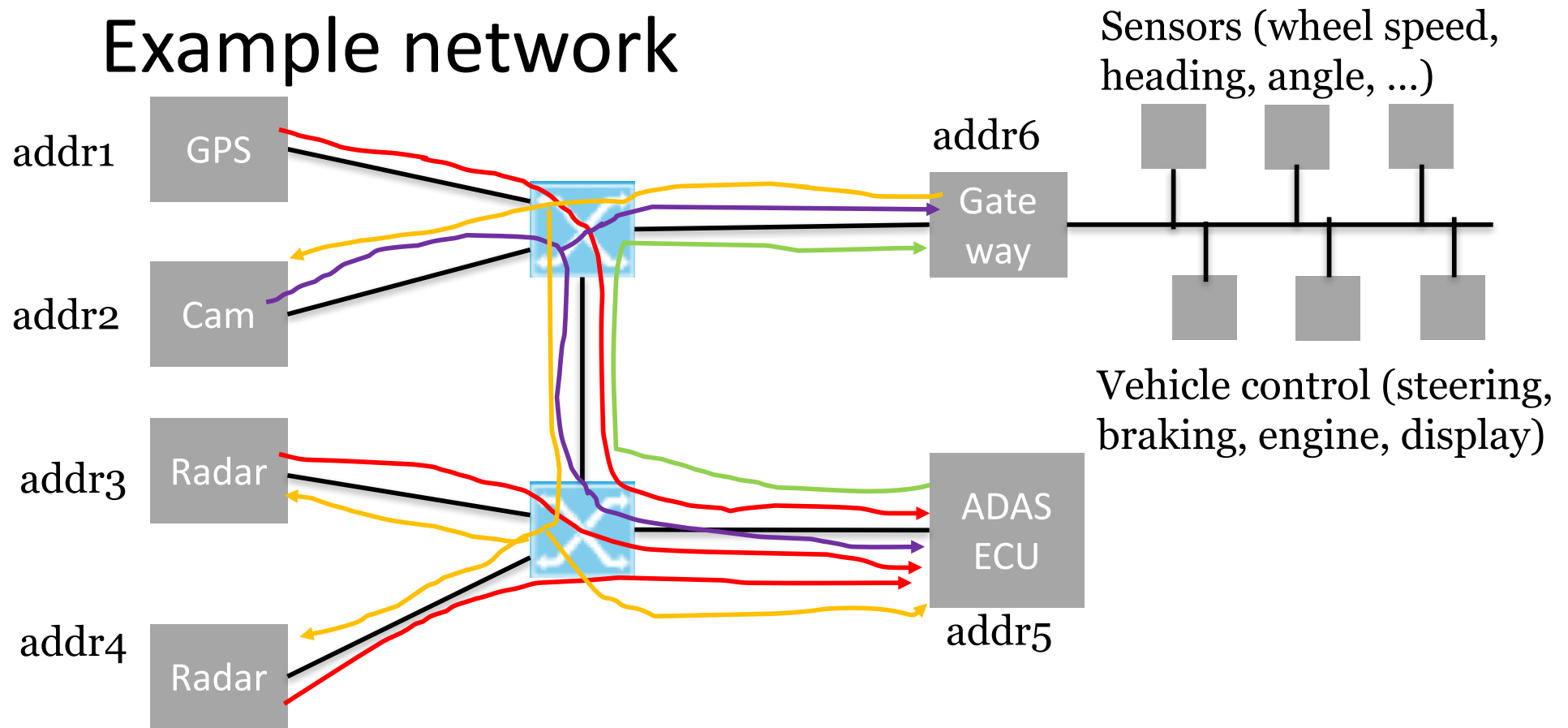
# MAC address



# Example network



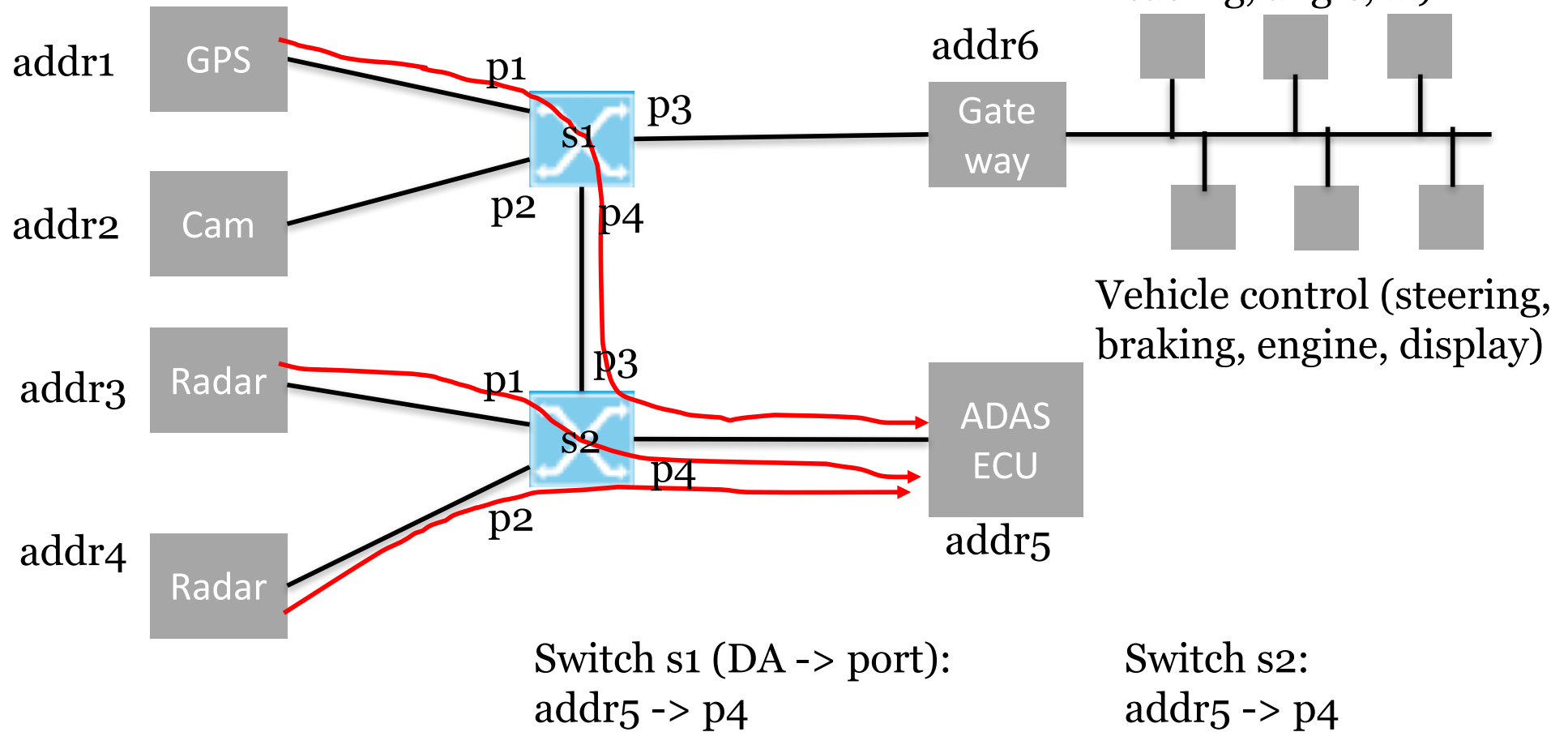
# Example network



Streams:

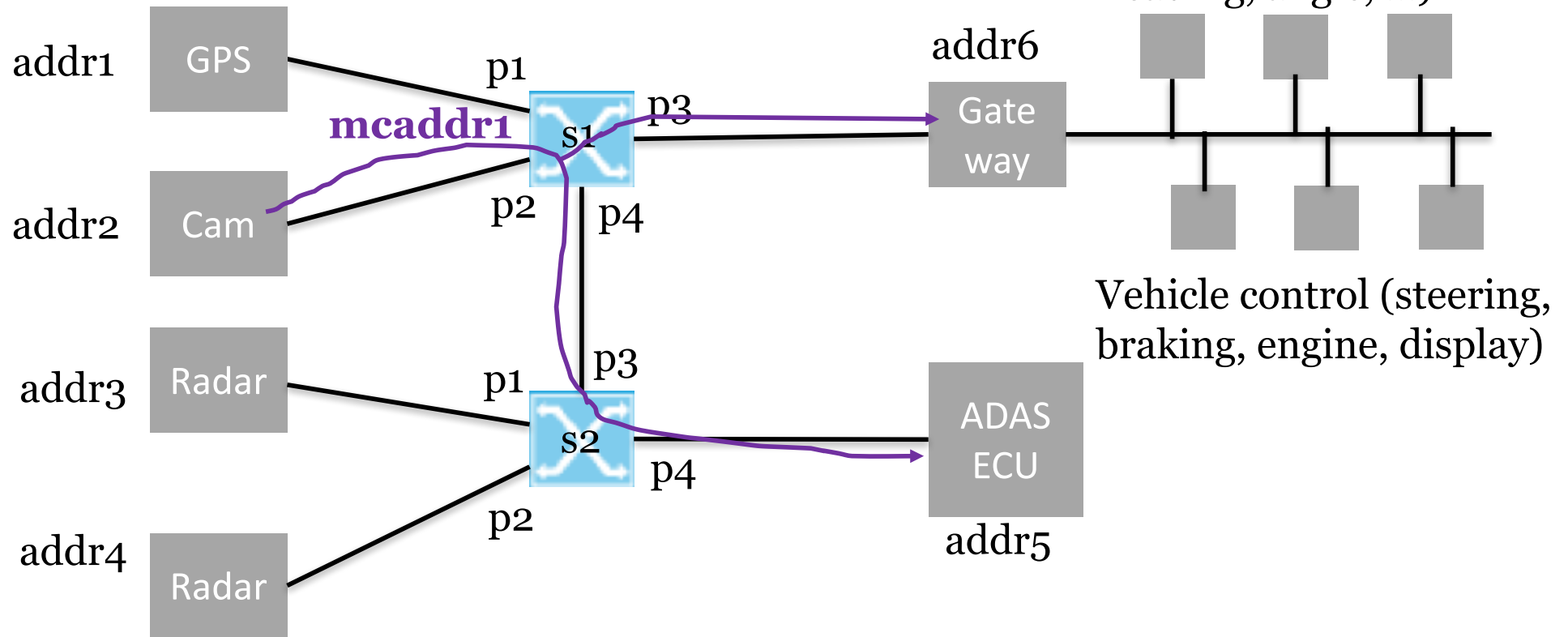
- **GPS and Radars to ADAS ECU**
- **Cam to ADAS ECU and Vehicle domain**
- **Vehicle sensors to Cam, Radars, and ADAS ECU**
- **ADAS ECU to Vehicle domain (actuation and corrected GPS)**

# Forwarding tables





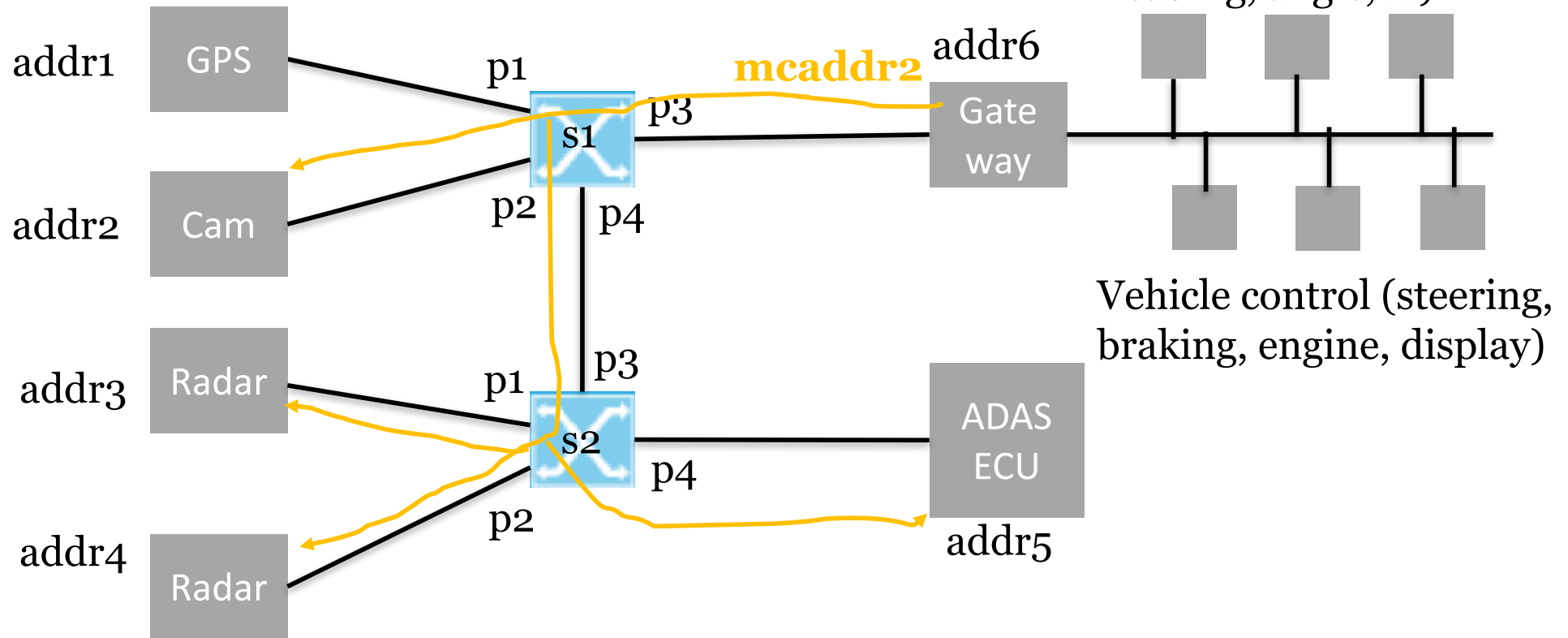
# Forwarding tables



Switch s1 (DA -> port):  
 addr5 -> p4  
 mcaddr1 -> p3, p4

Switch s2:  
 addr5 -> p4  
 mcaddr1 -> p4

# Forwarding tables



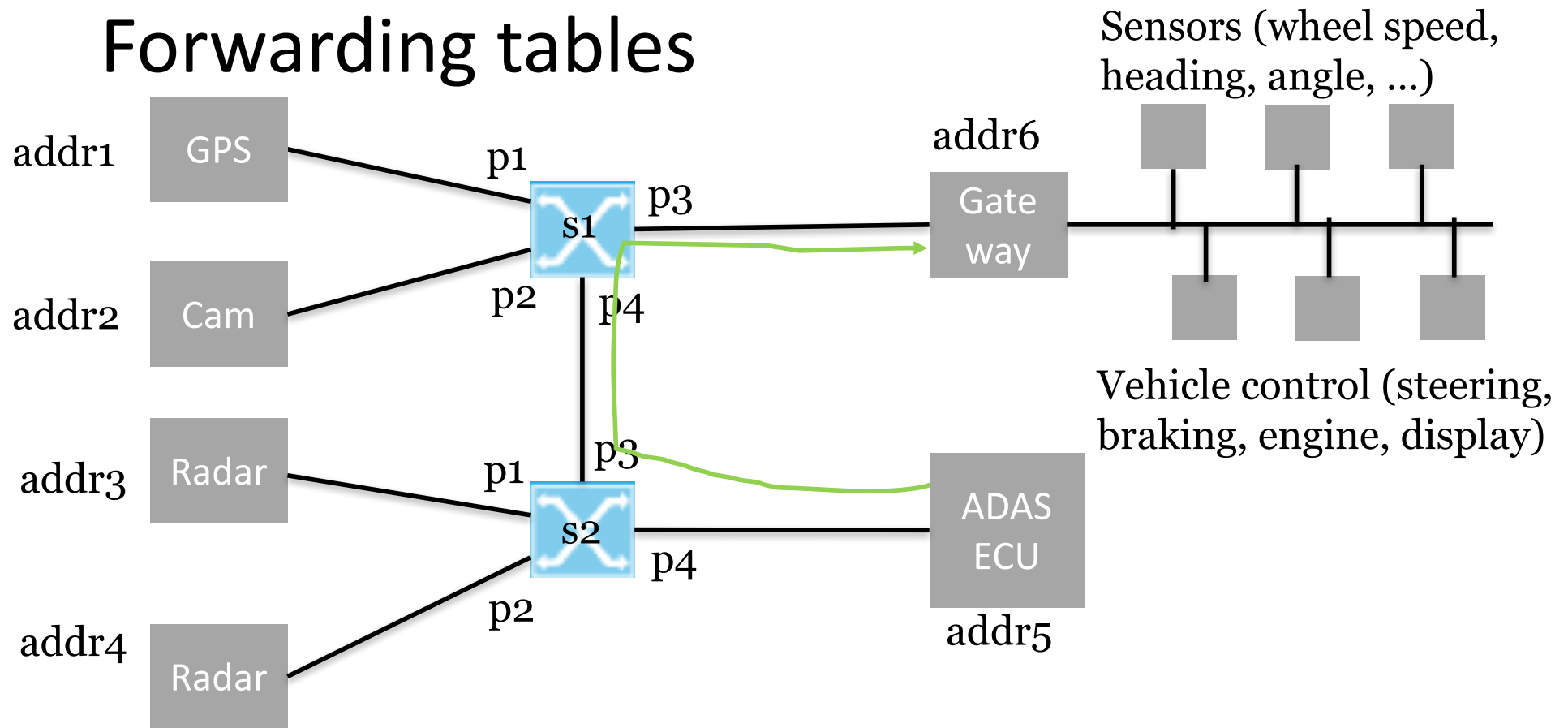
Sensors (wheel speed, heading, angle, ...)

Vehicle control (steering, braking, engine, display)

Switch s1 (DA -> port):  
 addr5 -> p4  
 mcaddr1 -> p3, p4  
 mcaddr2 -> p2, p4

Switch s2:  
 addr5 -> p4  
 mcaddr1 -> p4  
 mcaddr2 -> p1, p2, p4

# Forwarding tables



Switch s1 (DA -> port):  
 addr5 -> p4  
 mcaddr1 -> p3, p4  
 mcaddr2 -> p2, p4  
 addr6 -> p3

Switch s2:  
 addr5 -> p4  
 mcaddr1 -> p4  
 mcaddr2 -> p1, p2, p4  
 addr6 -> p3

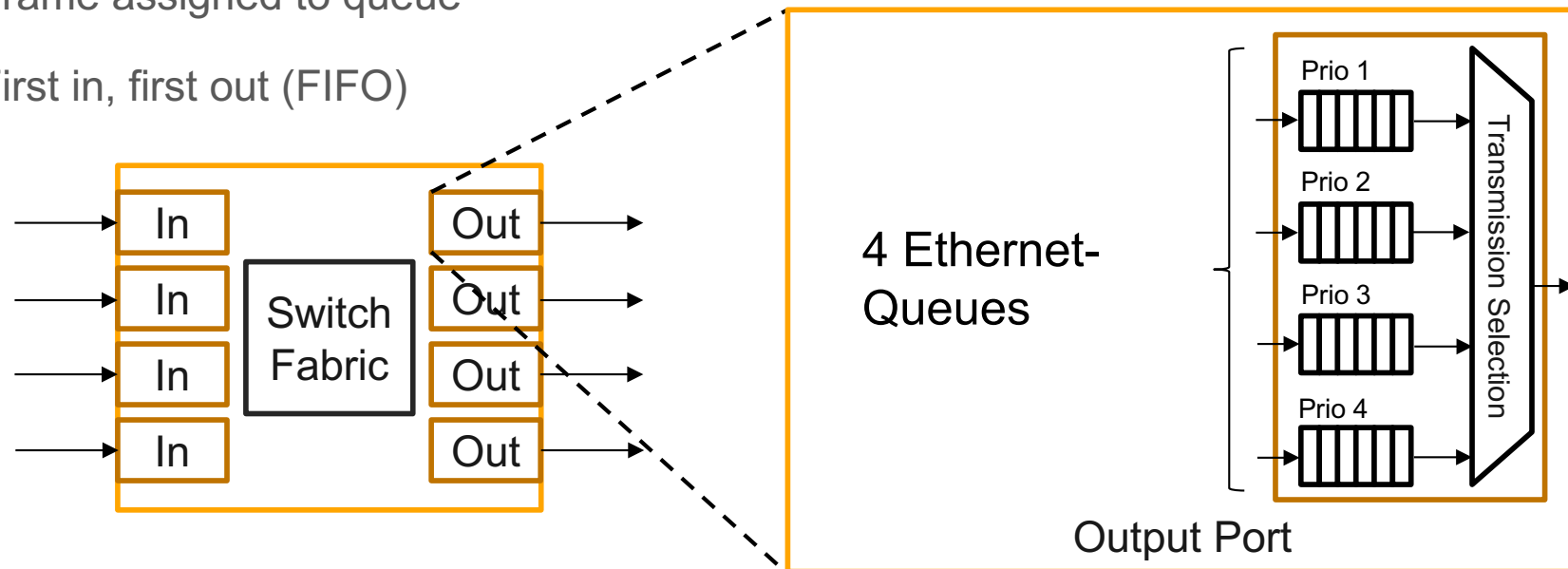
Table can also be a mapping from DA and VLAN ID to ports

# Configuration of forwarding tables

- For plug & play networks:
  - Flooding
  - Learning based on mapping ingress ports to source addresses (unicast)
  - Multiple stream registration protocol (multicast)
- Engineered networks (e.g., automotive, avionics)
  - Static configuration of forwarding tables
  - Protocols for learning are switched off (also helps to reduce risks for cybersecurity attacks)

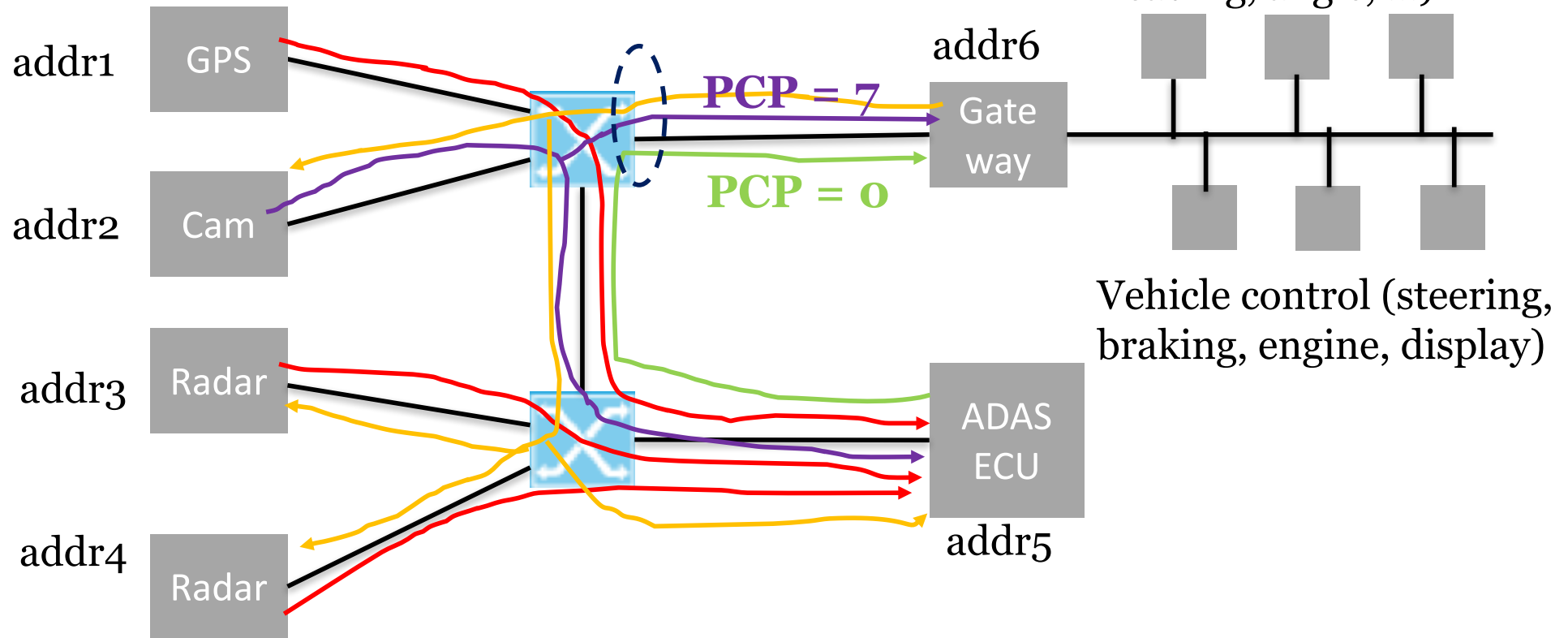
# Ethernet Switch

- › Priority assigned to frame
- › Priorities are mapped to queues
- › Frame assigned to queue
- › First in, first out (FIFO)



**Classification of frames, thus different treatment is possible**

# Prioritization

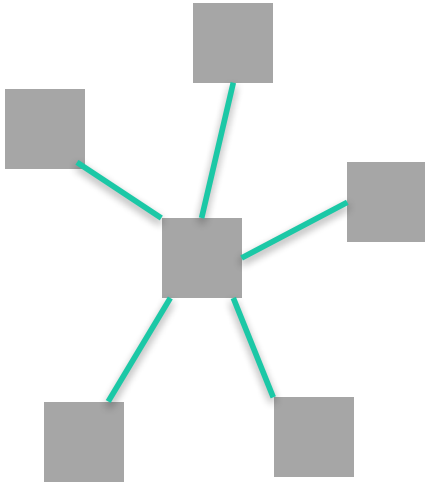


## Streams:

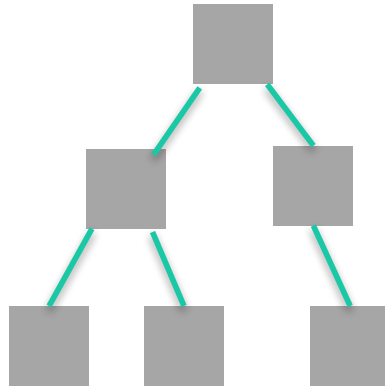
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- **Vehicle sensors to Cam, Radars, and ADAS ECU**
- **ADAS ECU to Vehicle domain (actuation and corrected GPS)**

# Different topologies

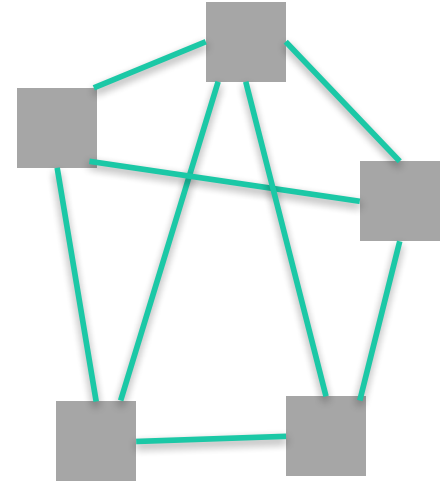
Star



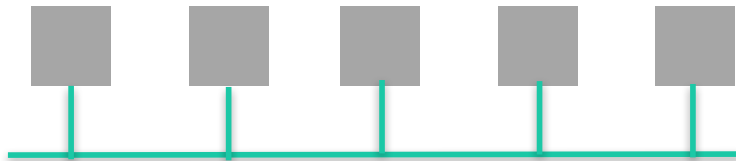
Tree



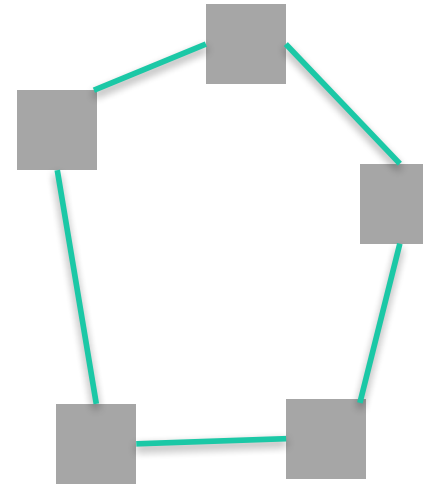
Mesh



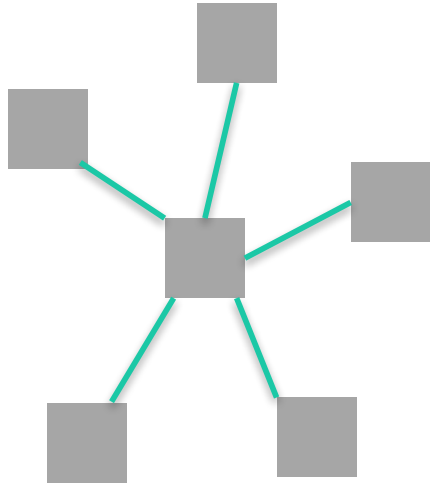
Bus



Ring

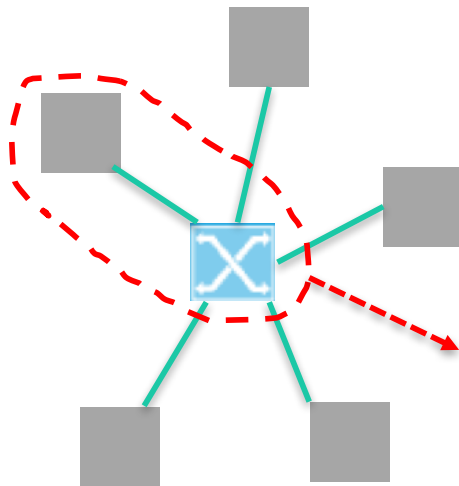


# Star topology



Some observations:

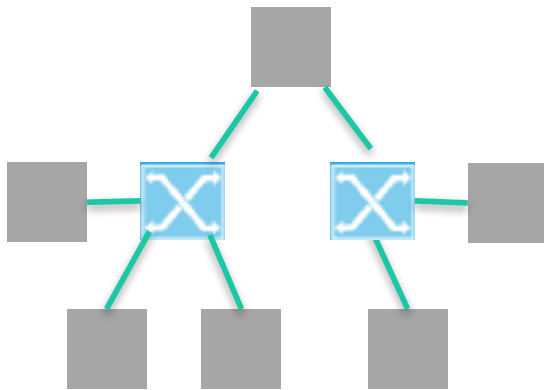
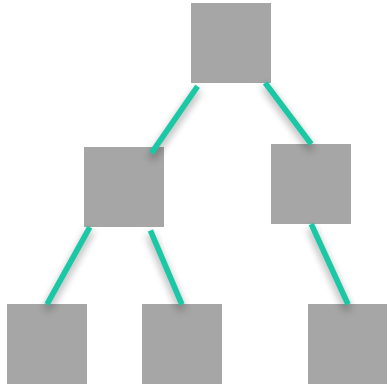
- One hop communication to all (low latency)
- Low cost
- Switch failure disconnects all communication
- Long wires, depending on physical location of endpoints



- Can be integrated in one module with MII, no PHY
- Integration is product and topology dependent



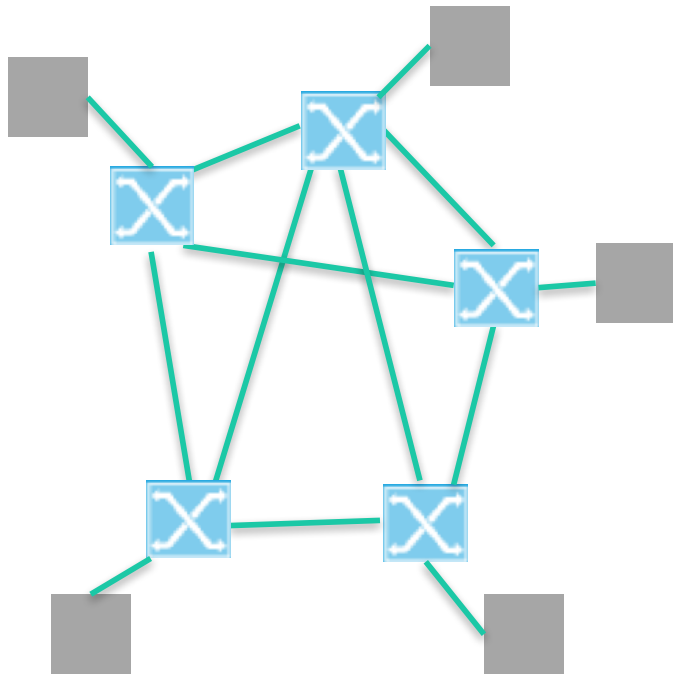
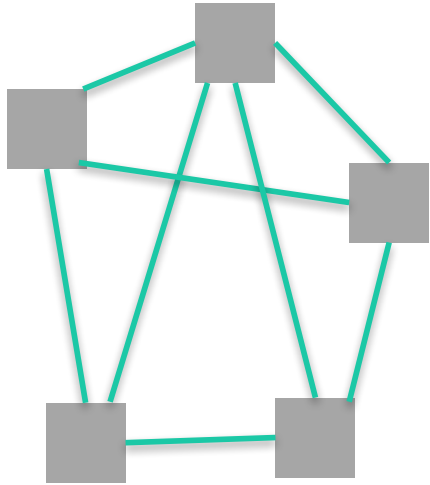
# Tree topology



Some observations:

- Multiple hops between some nodes
- Switch failure disconnects several nodes
- Good for networks where communication mainly goes in one direction
- Segmented left and right side

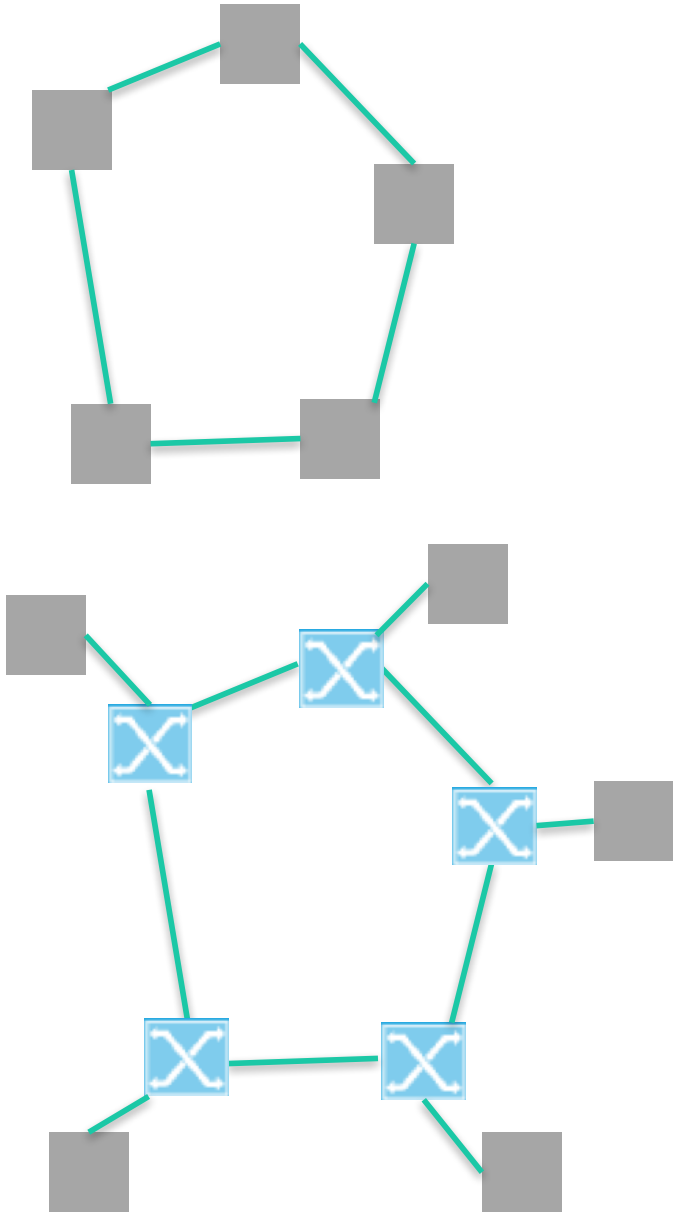
# Mesh topology



Some observations:

- Multiple hops between some nodes
- Reduced impact of one switch failure
- Multiple communication paths (easier to meet timing and redundancy needs)
- High cost due to many switches

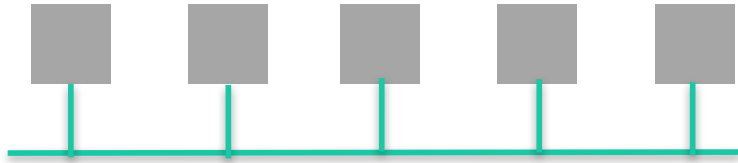
# Ring topology



Some observations:

- Latency does not scale well with number of nodes
- Redundancy at lower cost than mesh solution
- Still many switches, but of lower port count
- Switch failure “only” disconnects one node

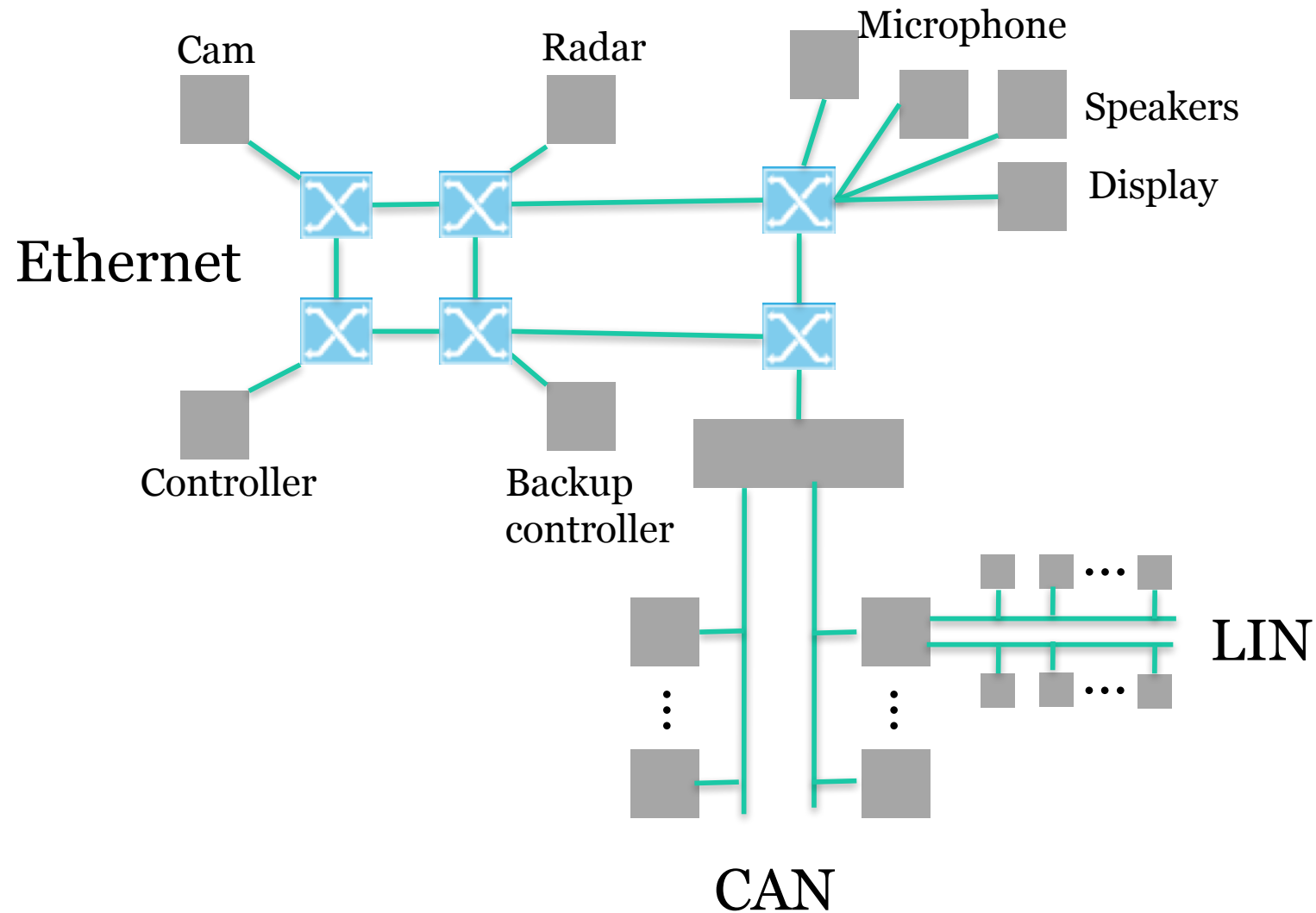
# Bus topology



Some observations:

- Low cost (no switches)
- Single broadcast domain
- Shared media access
- Requires non-IEEE 802 mechanisms to handle (or avoid) collisions for real-time applications

# Network is usually a mix of different topologies, as well as, technologies



# Ethernet PHYs

- Several standards have been created in IEEE 802.3
  - Full-duplex 100 Mbps and 1 Gbps Ethernet on single UTP (unshielded twisted pair) cable
  - Full-duplex 1+ Gbps is under development (e.g., we may end up with 2.5 Gbps and 10 Gbps)
  - 10 Mbps is under development too
    - “Multi-drop” (i.e., half-duplex, bus topology)
    - Some companies are looking at this as a replacement of CAN and FlexRay for the “All Ethernet car”

# Adding bandwidth is not enough

- Support for real-time and safety-critical applications
- Several industries with similar communication requirements at OSI Layer 2 and above
  - Professional audio/video
  - Industrial automation
  - Automotive
  - Telecom
- Standardization development in IEEE 802.1
  - First, AVB. Now, TSN
  - Multi-hop, switched topologies make certain problems more complicated bus-based RT communication

# AVB (Audio/Video Bridging)

- Main drivers:
  - synchronized audio and video applications on Ethernet
  - Plug and play
- IEEE 802.1AS: Plug and play Clock synchronization
- Amendments to IEEE 802.1Q:
  - Stream reservation protocol (admission control)
  - Credit-based traffic shaping (guaranteed bandwidth across priority levels; no starvation; zero congestion loss / no dropped packets)
- IEEE 802.1BA: Umbrella document



# What was missing?

- Guaranteed lower latencies; searching for the lowest possible latency
- Error detection and isolation
- Redundant communication
- Redundant clock synchronization

# New TSN standards

- TSN: Group renamed itself from “Audio/Video Bridging” to “Time Sensitive Networking”
- Guaranteed lower latencies; searching for the lowest possible latency
  - 802.1Qbv: A priori defined, pre-scheduled communication
  - 802.1Qbu: Frame preemption
  - 802.3br: Preemption required changes in MAC
  - P802.1Qcr: Asynchronous traffic shaping

# New TSN standards

- Error detection and containment
  - 802.Qci: Monitoring of pre-defined “contract” between a data flow and the network
  - Meaning of “Contract” depends on the scheduling policy
- Redundant communication
  - 802.1CB: Frame replication and elimination
- Redundant clock synchronization
  - P802.1AS-REV: updates to the clock synchronization standard to support backup masters and multiple time domains

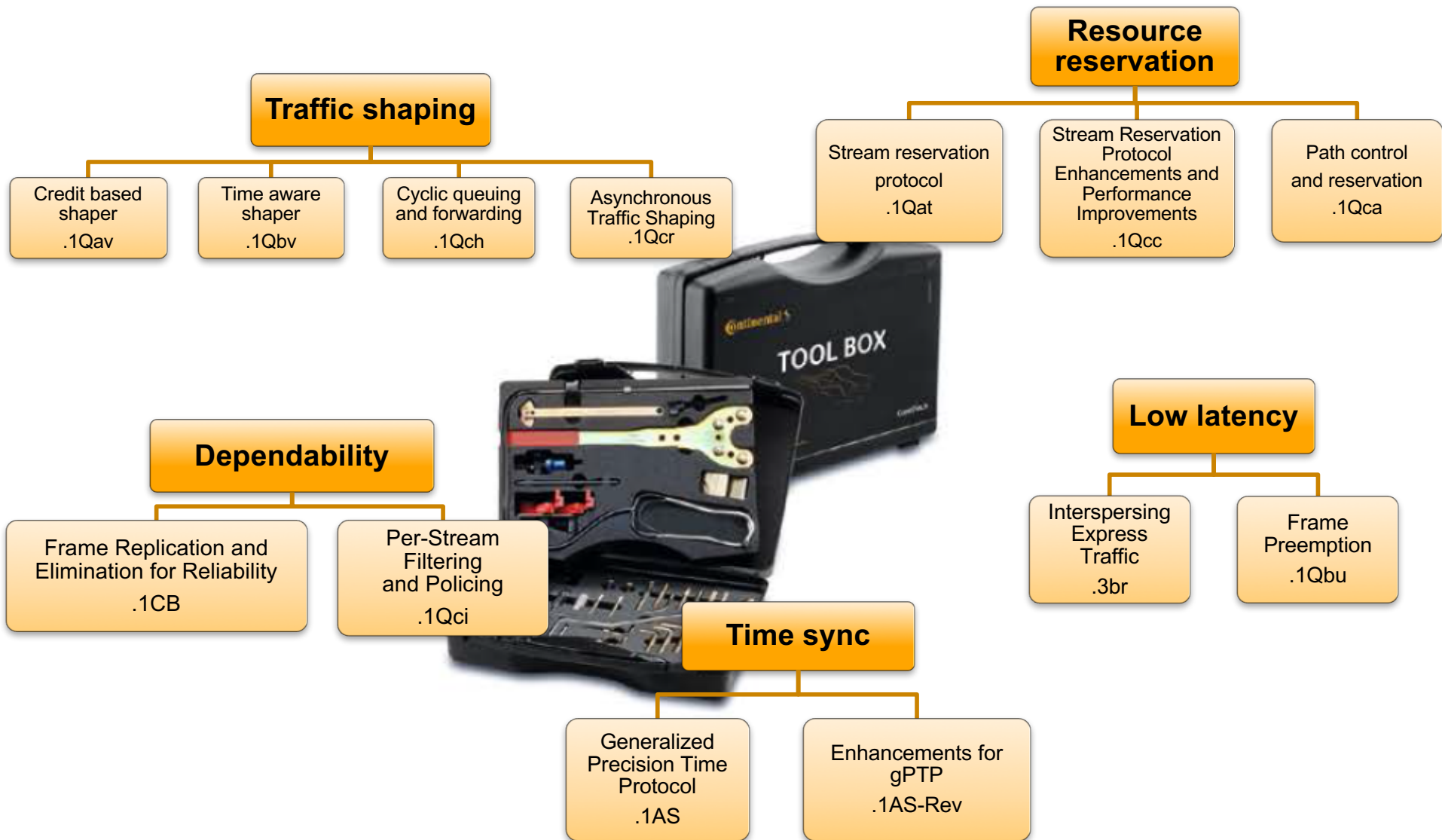
# Security standards

- 802.1 has developed three main standards for secure Ethernet communication
- 802.1AE (“MACsec”): integrity and, optionally, privacy, is ensured by symmetric key crypto (128 and 256 bit keys are supported)
- 802.1X:
  - Port authentication
  - Key agreement protocol

# Security standards

- 802.1AR (Secure Device Identity):
  - Device identity based on public key crypto (elliptic curves)
  - Public Key Infrastructure and certificates
- These standards, in particular MACsec and Secure Device Identity, require parallel crypto logic on chip
  - Challenging in terms of cost, power, and size
  - Automotive industry has started to look at how to secure Ethernet communication and which portions of the 802.1 security standards apply

# TSN toolbox



# TSN application areas

- Industrial control
- Avionics
- Automotive
- Telecom
- Aerospace
- Edge computing (a.k.a. “Fog” computing)
  - Industrial automation
  - Intelligent transport systems (road-side units)

# Many non-standard solutions

- Ethernet POWERLINK (Master/Slave protocol; open source)
- EtherCAT (2-port switch in each node; cut-through forwarding
  - Beckhoff automation (IEC 61158)
- PROFINET (TDMA)
  - Siemens
- AFDX (static configuration, traffic shaping) (Airbus)
- TTEthernet by TTEch (TDMA at message level, and rate-constrained traffic class).



# Summary

- Ethernet is a point-to-point network
- Direct addressing with unicast and multicast
- Switches forward frames towards the destination(s)
- Ports have multiple queues assigned to different priority levels
- Many different Ethernet topologies
- AVB and TSN standards added real-time capabilities
- There are also nonstandard solutions deployed