

## Outline

- Introduction to SSA
- Construction, Destruction
- Representation of analysis values
- Representation of analysis values
- Optimizations
  - Classic analyses and optimizations on SSA representations
  - Heap analyses and optimizations

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## Analyses and Optimizations

- Analyses in Compiler Construction allow to safely perform optimizations
- Cost model: runtime of a program
  - Statically only conservative approximations
    - Loop iterations
    - Conditional code
  - Even for linear code not known in advance:
    - Instruction scheduling
    - Cache access is data dependent
    - Instruction pipelining: execution time is not the sum of individual operations costs
- Alternative cost models:
  - memory size, power consumptions
  - Same non-decidability problem as for execution time
- Caution:** cost of a program  $\neq$  sum of costs of its elements

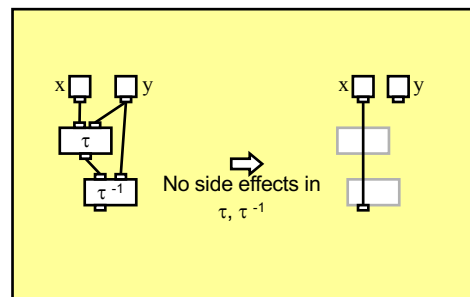
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## Optimization: Implementation

- Legal transformations in SSA-Graphs:
  - Simplifying transformations reduce the costs of a program
  - Preparative transformations allow the application of simplifying transformations
- Using
  - Algebraic Identities (e.g. Associative / Distributive law for certain operations)
  - Moving of operations
  - Reduction of dependencies
- Optimization is a sequence of **goal directed, legal simplifying and legal preparative** transformations
- Legibility proven
  - Locally by checking preconditions
  - Due to static data-flow analyses

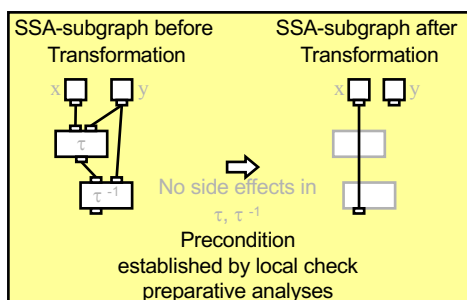
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## Algebraic Identity: Elimination of Operations and its Inverse



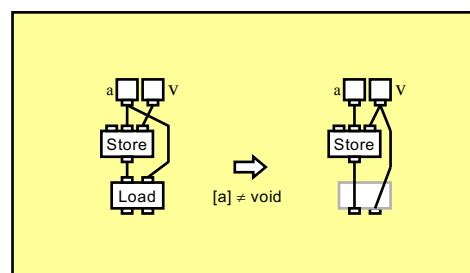
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## Graph Rewrite Schema



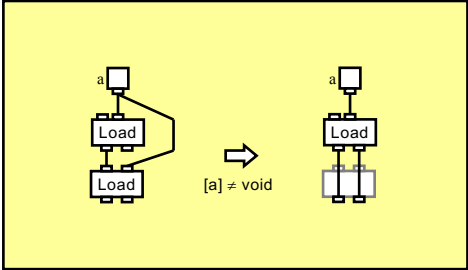
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## Elimination of Memory Operation and its Inverse



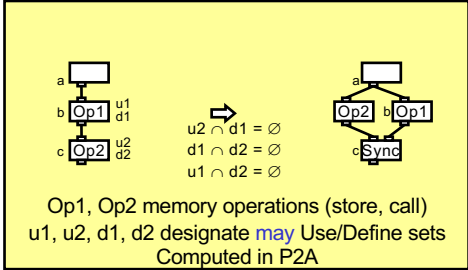
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### Elimination of Duplicated Memory Operations



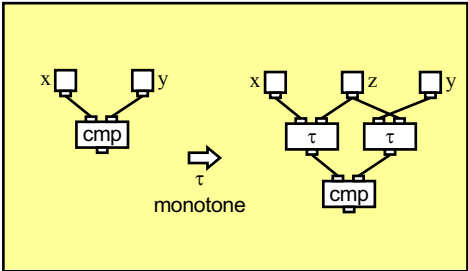
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### Elimination of non-essential dependencies



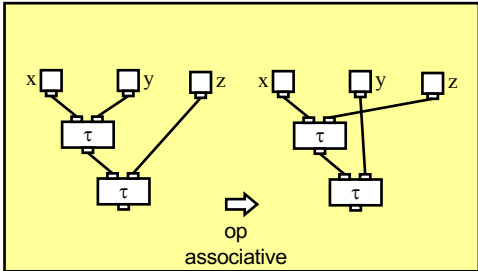
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### Algebraic Identity: Invariant Compares



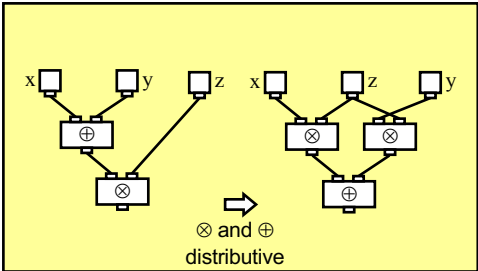
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### Associative Law



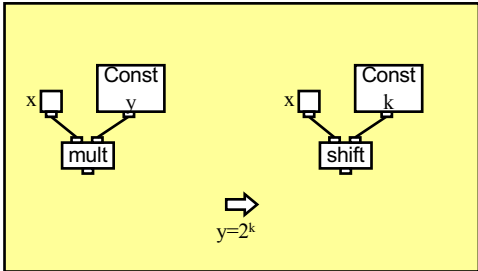
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### Distributive Law



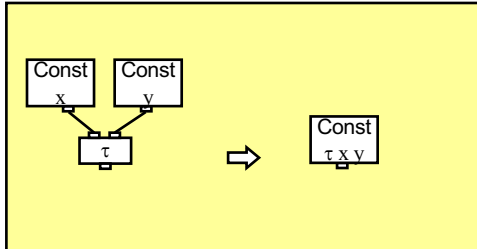
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### Operator Simplification



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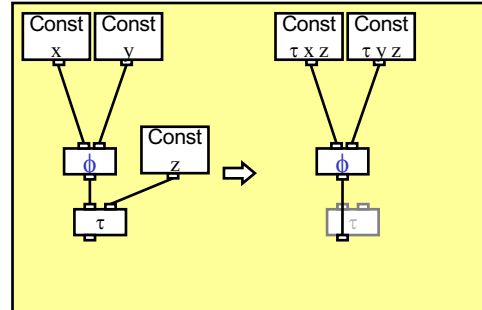
## Constant Folding



Evaluation using source algebra  
or target algebra (if allowed by source language)

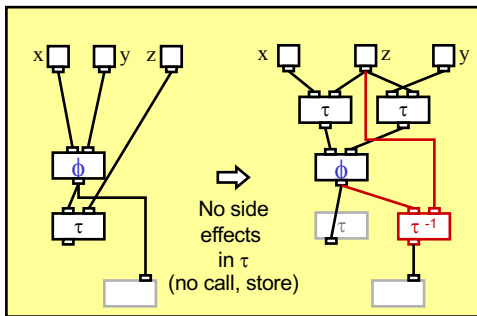
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## Constant folding over $\phi$ -functions



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## General: Moving arithmetic operations over $\phi$ -functions



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## Optimizations

- Strength reduction:
  - Bauer & Samelson 1959
  - Replace expensive by cheap operations
    - Loops contain multiplications with iteration variable,
    - These operations could be replaced by add operations (Induction analysis)
  - One of the oldest optimizations: already in Fortran I-compiler (1954/55) and Algol 58/60- compiler
- Partial redundancy elimination (PRE):
  - Morel & Renvoise 1978
  - Eliminate partially redundant computations
    - SSA eliminates all static but not dynamic redundancies
    - Problem on SSA: which is the best block to perform the computation
    - Move loop invariant computations out of loops, into conditionals
  - subsumes a number of simpler optimization

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## Example: Strength reduction

```

for (i=0; i<n; i++){
  for (j=0; j<n; j++){
    b[i, j]=a[i, j];
  }
}

//Original loop body:
ao = i*n*d + j*d
aij = >a[0, 0]<+ao
bij = >b[0, 0]<+bo
<bij> = <aij>

adda=>a[0, 0]<
addb=>b[0, 0]<
d=4
addend=adda+n*n*d;
LOOP: jump (addend==adda) END
<addb>=<adda>
adda=adda+d
addb=addb+d
jump LOOP
END: exit
    
```

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## Induction Analysis Idea

- Find **Induction variable**  $i$  for a loop using DFA
  - $i$  is **induction variable** if in loop only assignments of form  $i := i+c$  with loop constant  $c$  or, recursively,  $i := c' * i' + c''$  with  $i'$  induction variable and loop constants  $c', c''$
  - $c$  is a **loop constant** iff  $c$  does not change value in loop, i.e.
    - $c$  is static constant,
    - $c$  computed in enclosing loop
- Example (cont' d), consider the inner loop:
 

```
for (j=0; j<n; j++){...}
```

  - Direct induction variable:  $j$ , implicit  $j = j+1$  ( $c=1$ )
  - Indirect induction variable:  $ao = i*n*d+j*d$  ( $c'=d, c''=i*n*d$ )
  - Note that  $i*n*d$  and  $d$  a loop constants for the inner loop

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## Induction Transformation Idea

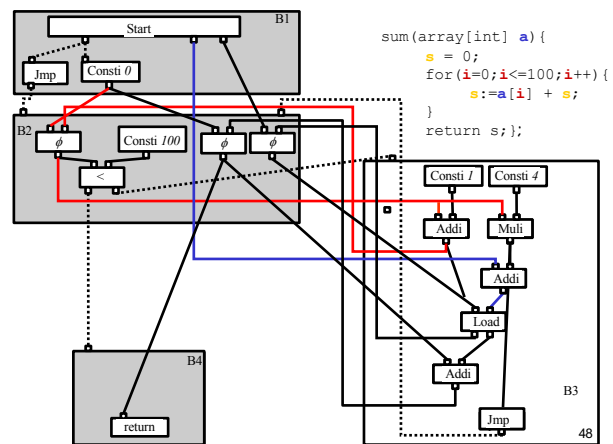
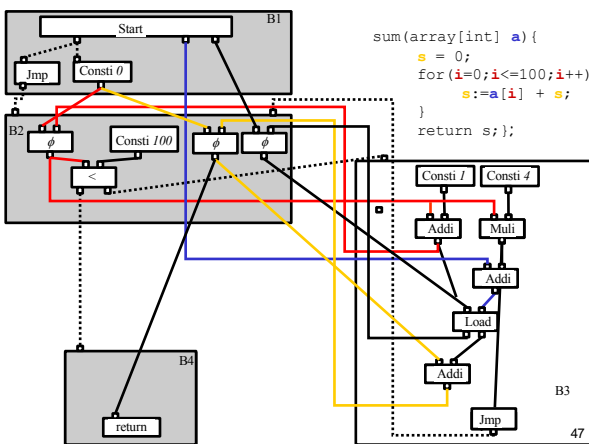
- Transformation goal: values of induction variables should grow linearly with iteration; add operations replace mul t operations
- Transformation:
  - Let  $i_0$  initialization of  $i$  and induction variables,  $i := i+c$  and  $i' := c'*i+c''$
  - New variable  $ia$  initialized  $ia := c' * i_0 + c''$
  - At loop end insert  $ia = ia + c' * c$
  - Replace consistently operands  $i'$  by  $ia$
  - Remove all assignments to  $i, i'$  and  $i, i'$  themselves if  $i$  is not used elsewhere (DFA)
- Example:
  - Before: loop  $ao = i*n*d+j*d \dots j++$  end loop
  - After:  $aoa = i*n*d$  loop  $\dots aoa = aoa + d$  end Loop

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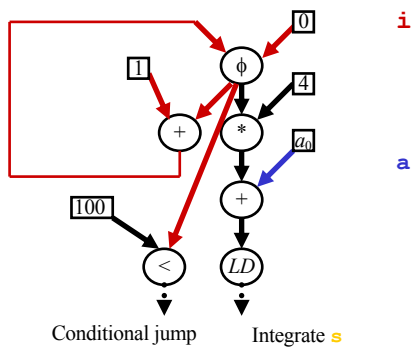
## Induction Analysis: Implementation

- Assume initially optimistically: all variables are induction variables
- Finding induction variable  $i$  for a loop follows definition
- Iteratively until fix point:  $i$  is not induction variable if **not**:
  - $i := i+c$  with loop constants  $c$  (direct induction variable)
  - $i := c'*i'+c''$  with  $i'$  induction variable and loop constants  $c', c''$  (indirect induction variable)
- On SSA, simplifications of that analysis are possible
  - Any direct loop variable corresponds to a cyclic subgraph over  $i := \phi(i_1 \dots i_n)$
  - Find Strongly Connected Component (SCC) and check those subgraphs for the direct induction variable condition first
  - Then find the indirect induction variables

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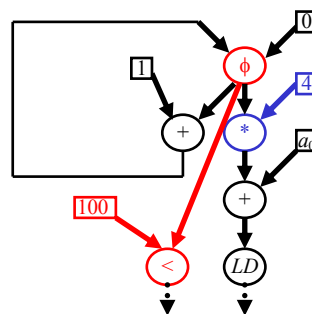


## Induction Variables (Schematic)



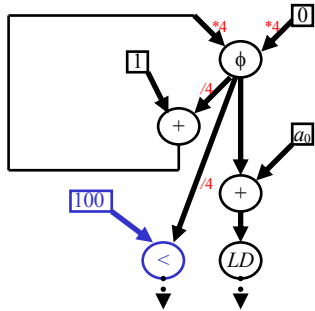
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## Move \* over phi-function



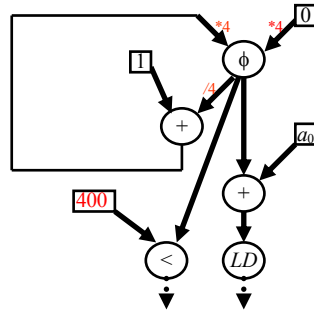
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### Move Multiplication



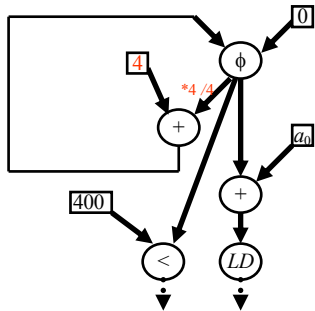
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### Invariant Compare



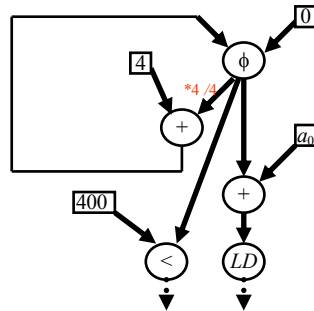
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### Distributive Law



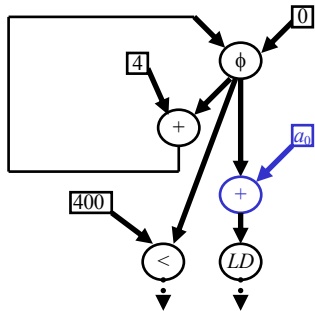
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### Operation and its Inverse



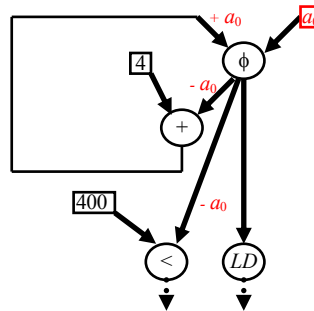
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### Move Addition



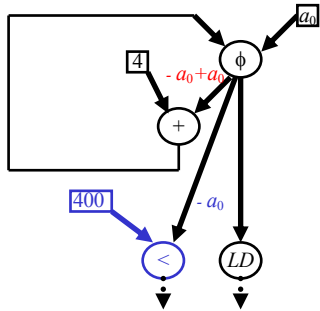
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### Move Addition



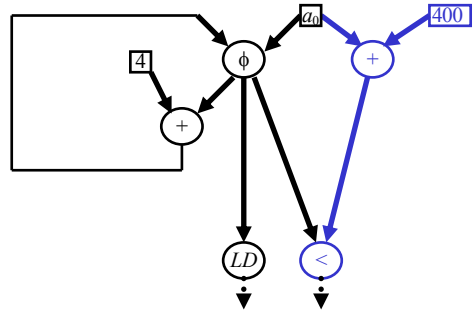
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### Associative Law



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### Change Compare



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