

Control Flow Analysis

[ASU1e 10.4] [ALSU2e 9.6] [Muchnick 7]

- necessary to enable global optimizations beyond basic blocks
- basis for data-flow analysis
- reconstruction of if-then-else, **loops**
 - from MIR, from unstructured source code or from target code
 - loops: candidates for loop transformations, software pipelining
 - if-then-else: candidates for predication
- identify basic blocks of a routine
- construct its flow graph / basic block graph

1. Dominator-based analysis

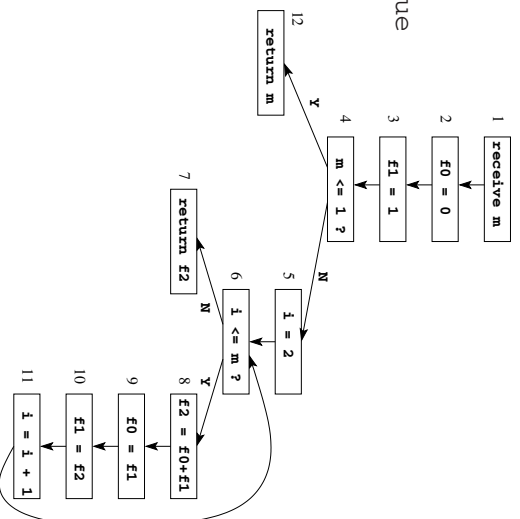
2. Interval analysis

3. Structural analysis

(iterative)
(recursive)
(recursive)

Example (cont.): Control Flow Graph

```
// MIR
1 receive m
2 // read arg value
3 f0 = 0
4 f1 = 1
5 if m<=1 goto L3
6 i = 2
7 L1: if i<=m goto L2
8 return f2
9 L2: f2 = f0 + f1
10 f0 = f1
11 f1 = f2
12 i = i + 1
13 L3: return f2
```



Control Flow Analysis – Running Example

```
// Fibonacci - Iterative alg.
// MIR, flattened
1 receive m
2 // read arg value
3 f0 = 0
4 f1 = 1
5 if m<=1 goto L3
6 i = 2
7 L1: if i<=m goto L2
8 return f2
9 L2: f2 = f0 + f1
10 f0 = f1
11 f1 = f2
12 i = i + 1
13 L3: return f2
```

Detecting basic blocks

basic block (BB)

= max. sequence of consecutive statements (IR or target level) that can be entered by program control only via the first one and left only via the last one.

first instruction (“**leader**”) of a BB: either

- + entry point of a procedure, or
- + branch target, or
- + instruction immediately following a branch or return

! call instructions need not delimit the basic block

(ok for most cases, but not for e.g. instruction scheduling)

! exception-based control transfer not considered here

Basic-block graph

Terminology: in [Muchnick'97] called **control-flow graph CFG**, whereas “our” CFG (statement level) is there called a “flowchart”

rooted, directed graph $G = (N, E)$

nodes = basic blocks + **entry** + **exit**

edges = control flow edges from CFG/flowchart

(there connecting BB exits to the leaders of their successor BBs)

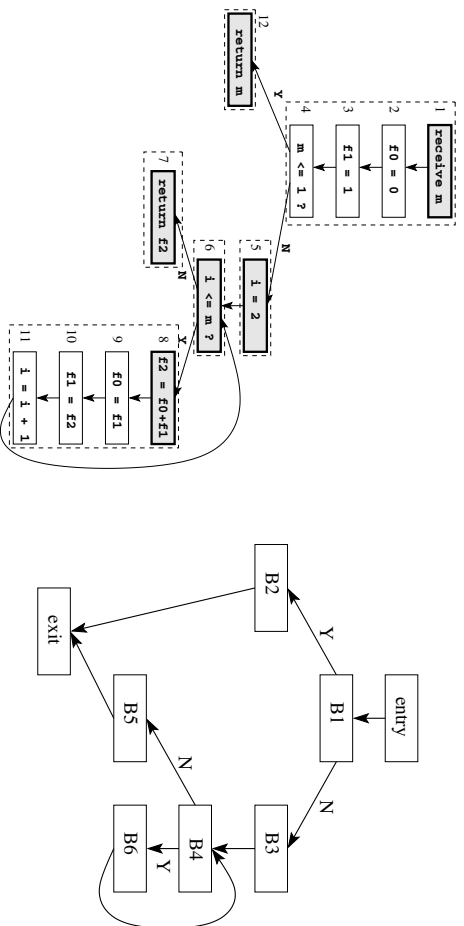
+ **entry** → initial basic block

+ final basic blocks (no succ.) → **exit**

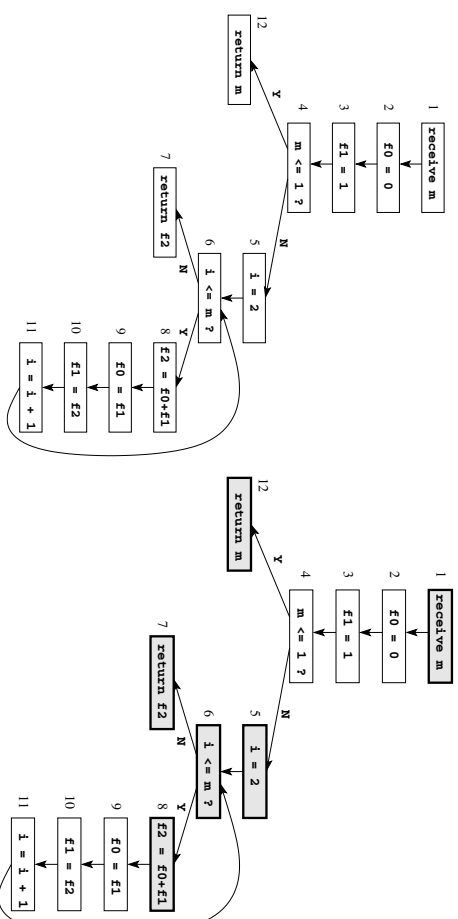
successor BB's of a BB b : $Succ(b) = \{n \in N : (b, n) \in E\}$

predecessor BB's of a BB b : $Pred(b) = \{n \in N : (n, b) \in E\}$

Example (cont.): CFG + Basic Blocks → Basic Block Graph



Example (cont.): CFG → Basic Block Leaders



Extended basic blocks, regions

Extended basic block (EBB)

= max. sequence of instructions beginning with a leader that contains no join nodes other than (maybe) its first node

→ single entry, multiple exits, tree-like internal control flow

→ EBB also known as **treeregion**

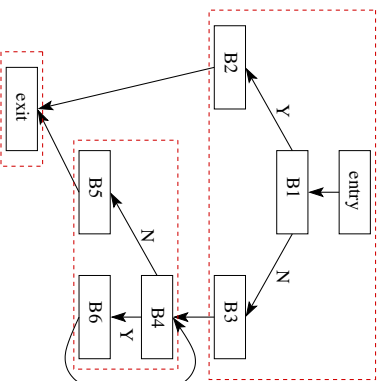
EBB's are useful for some optimizations e.g. instruction scheduling

Algorithm for computing the EBB's of a CFG: see e.g. [Muchnick 7.1]

Region

= strongly connected subgraph (SCG) of the CFG with a single entry

Example (cont.): Extended Basic Blocks



Graph-theoretic concepts of control-flow analysis (1)

depth-first search (dfs): recursively explore descendants of a node before any of its siblings (as far as not yet visited)

dfs-number: order in which dfs enters nodes

tree edges: edges followed by dfs via recursive calls

dfs-tree: (nodes, tree edges)

non-tree edges classified as

- forward edges “F”
- back edges “B”
- cross edges “C”

not unique! depends on ordering of descendants

see also DFS-slides on course homepage

Finding Loops

Programs spend most of the execution time in loops.

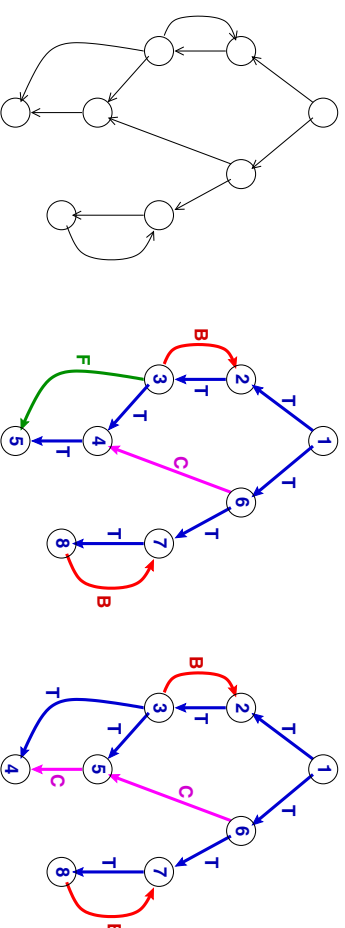
- Optimizations that exploit the loop structure are important
 - loop unrolling, loop parallelization, software pipelining, ...

Loops may be expressed in programs by different constructs (while, for, goto, ..., compiler-converted tail-recursion)

→ Find uniform treatment for program loops

Use a general approach based on graph-theoretic properties of CFG.

Example: DFS-tree, edge classification



Graph-theoretic concepts of control-flow analysis (2)

preorder traversal of a digraph $G = (N, E)$:

at each node $b \in N$ process b before its descendants
(not unique; in dfsnum-order)

postorder traversal

at each node $b \in N$ process b after its descendants

Dominance, immediate dominance, strict dominance

Given: flow graph $G = (N, E)$, nodes $d, i, p, b \in N$

d **dominates** b ($d \text{ dom } b$)

if every possible execution path $\text{entry} \rightarrow^* b$ includes d

dom is reflexive, transitive, antisymmetric \rightarrow partial order on N

i **immediately dominates** b ($i \text{ idom } b$)

if $i \text{ dom } b$ and there is no $c \in N, i \neq c \neq b$, with $i \text{ dom } c$ and $c \text{ dom } b$

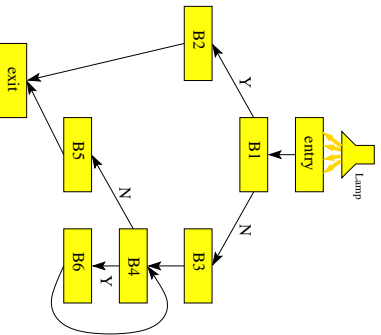
$\text{idom}(b)$ is unique for each $b \in N$

\rightarrow **(i)dominator tree**, rooted at $\boxed{\text{entry}}$

d **strict dominance** $d \text{ sdom } b$ if $d \text{ dom } b$ and $d \neq b$

Dominance intuition (1)

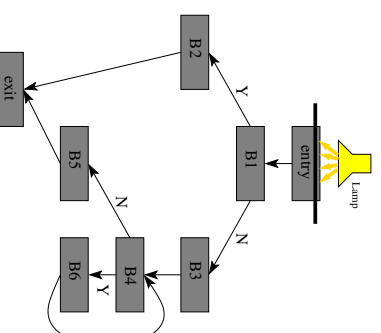
Imagine a source of light going into the entry node,
nodes are transparent and edges are optical fibers



Place an opaque barrier at node $v \rightarrow$ nodes dominated by v get dark

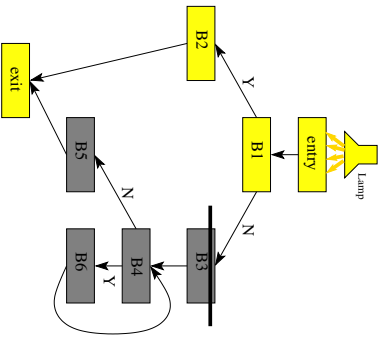
Dominance intuition (2)

The entry node dominates all nodes:



Dominance intuition (3)

Node B_3 dominates B_3, B_4, B_5, B_6 :



Postdominance

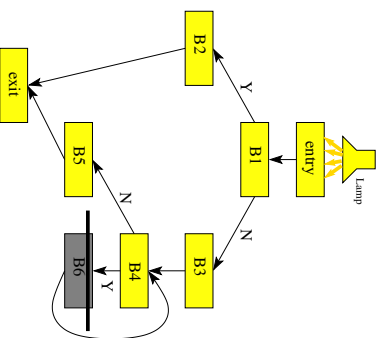
p postdominates b (p pdom b)

if every possible execution path $b \rightarrow^* \text{exit}$ includes p

p pdom $b \iff b$ dom p in the reversed flow graph

Dominance intuition (4)

Node B_6 only dominates itself:



Computing the dominators of a node

Algorithm 1:

a dom b

iff

(1) $a = b$,

or

(2) \exists unique immediate predecessor of b , namely a ,

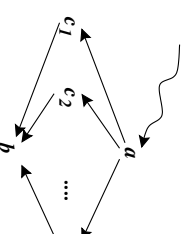
i.e. $Pred(b) = \{a\}$,

or

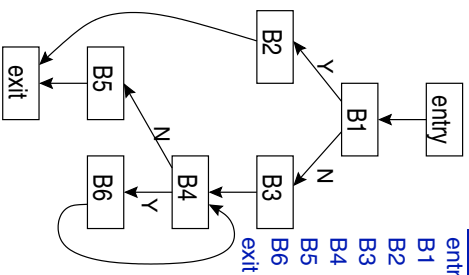
(3) for all $c \in Pred(b)$

$c \neq a$ and a dom c .

change \leftarrow true;
 Domin(r) $\leftarrow \{r\}$;
 while (change)
 change \leftarrow false
 for all $n \in N - \{r\}$ // in dfsnum order
 $D \leftarrow \{n\} \cup \bigcap_{p \in Pred(n)} \text{Domin}(p)$
 if $D \neq \text{Domin}(n)$
 Domin(n) $\leftarrow D$; change \leftarrow true
 return Domin

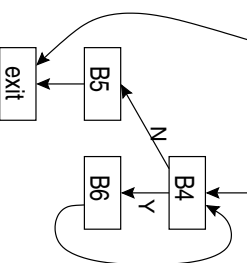


Example: Computing dominators

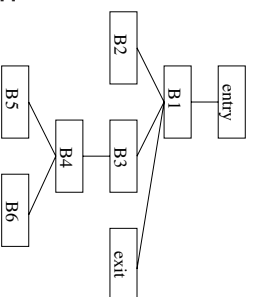


node t	Domin(t), init.	change=true	Domin(t), iter. 1	iter. 2 ...
entry	{entry}		{entry}	...
B1	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1} change=true	...
B2	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, B2}	...
B3	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, B3}	...
B4	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, B3, B4}	...
B5	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, B3, B4, B5}	...
B6	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, B3, B4, B6}	...
exit	{entry, B1, B2, B3, B4, B5, B6, exit}		{entry, B1, exit}	...

node t	init.	Tmp(t)=Domin(t)-{ t }	Tmp(t), iter. 1
entry	{entry}	{entry}	{entry}
B1	{entry}	{entry}	{entry}
B2	{entry, B1}	{B1}	{B1}
B3	{entry, B1}	{B1}	{B1}
B4	{entry, B1, B3}	{B3}	{B3}
B5	{entry, B1, B3, B4}	{B4}	{B4}
B6	{entry, B1, B3, B4}	{B4}	{B4}
exit	{entry, B1}	{B1}	{B1}



Dominator tree:



Extension for computing immediate dominators

```

... compute Domin ...
for each  $n \in N$ 
  Tmp( $n$ )  $\leftarrow$  Domin( $n$ ) - { $n$ }
  for each  $n \in N - \{r\}$  // in dfsnum order
    // if a  $s$  in Tmp( $n$ ) has a dominator  $t \neq s$ , remove  $t$  from Tmp( $n$ )
    for each  $s \in$  Tmp( $n$ )
      for each  $t \in$  Tmp( $n$ ) - { $s$ }
        if  $t \in$  Tmp( $s$ ) then
          Tmp( $n$ )  $\leftarrow$  Tmp( $n$ ) - { $t$ }
  for each  $n \in N - \{r\}$  // in dfsnum order
    idom( $n$ )  $\leftarrow$  the  $b \in$  Tmp( $n$ )

```

Total time: $O(n^2e)$ if sets are represented by bitvectors

Computing dominators

Algorithm 2 [Lengauer/Tarjan'79]

based on depth first search and path compression

time $O(e \log n)$ or $O(e \cdot \alpha(e, n))$

(see e.g. [Muchnick pp. 185–190])

Loops and Strongly Connected Components

We call a (backward, B) edge (m, n) a **loop back edge** if $n \text{ dom } m$.

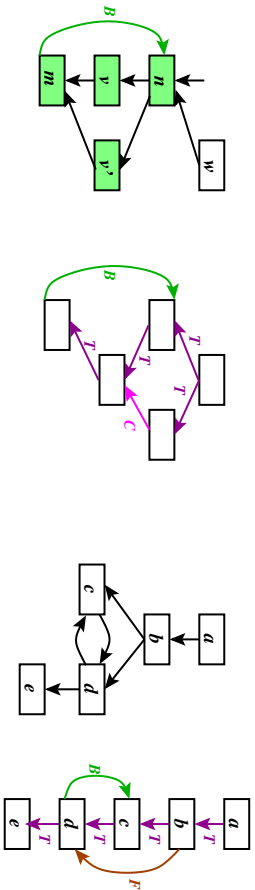
Remark: Not every B edge is a loop back edge!

Natural loop of a loop back edge (m, n)

= subgraph of n and all nodes v

from which m can be reached without passing through n

n is the **loop header**.

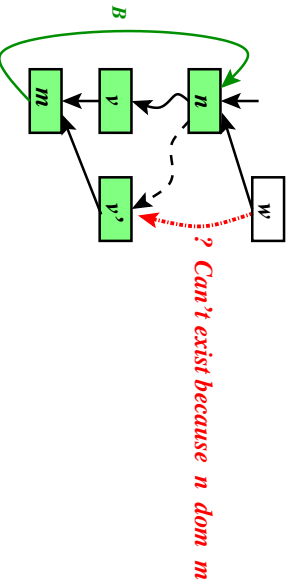


c does not dominate $d \Rightarrow$ not a natural loop (2 entry points)

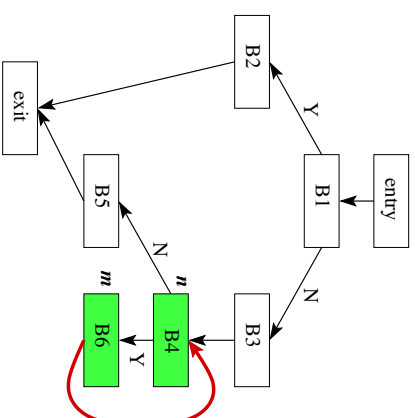
Identifying the natural loop of a loop back edge

Algorithm: Compute the loop node set for a given loop back edge (m, n)

- Start by marking m and n as loop nodes.
- Backwards from m , (df)search predecessors v , stopping recursive backward search at already found loop nodes.

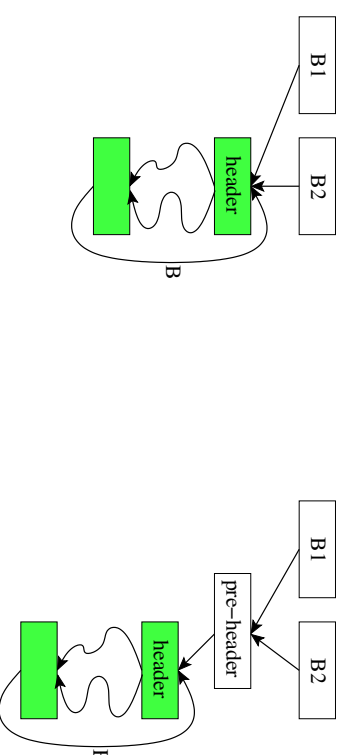


Example (cont.): Natural Loop



Loop header, preheader

For technical reasons, add a pre-header (initially empty) if the header has more than 2 predecessors:



→ Easier to place new instructions immediately before the loop

Properties of Natural Loops

- Two natural loops with different headers* are either disjoint or one is nested in the other.
- Each natural loop is a SCC.

Background:

Strongly connected component (SCC)

= subgraph $S = (N_S, E_S)$, $N_S \subseteq N$, $E_S \subseteq E$,

where every node in V_S is reachable in S from every other node in V_S via edges in E_S .

SCC's can be computed with **Tarjan's algorithm** (extension of dfs)

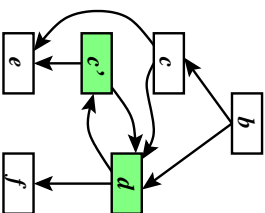
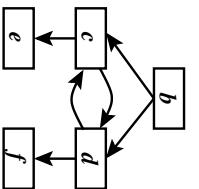
in time $O(|V| + |E|)$ [Tarjan'72]

* Several loops sharing a common header node is a pathological special case that must be treated ad hoc. See e.g. Muchnick 7.4 for more details.

Reducibility of flow graphs

A flow-graph is **reducible** if all B edges in any DFS tree are loop back edges.

Intuitively: ... if there are no jumps into the middles of loops (e.g., goto's).



Reducible flow graphs are well-structured (loops properly nested).

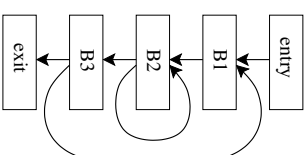
Irreducible flow graphs are rare

and can be made reducible by replicating nodes.

Properties of Natural Loops (cont.)

A SCC $S \subseteq V$ is **maximal** if every SCC containing S is just S itself.

Example:



$S_1 = \{B1, B2, B3\}$ is a maximal SCC.

$S_2 = \{B2\}$ is a SCC but not a maximal SCC.

Interval analysis

- Divide flowgraph into regions (e.g., loops in CFA)

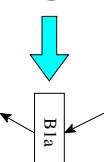
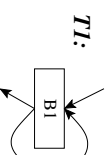
- Repeatedly collapse a region to an abstract node

→ abstract flowgraph

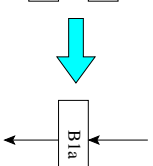
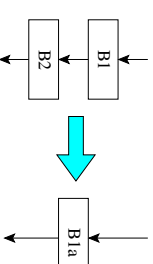
→ nested regions (control tree)

Hierarchical folding structure allows for faster / simpler data flow analysis

Simplest variant: **T1-T2 Analysis** [Ullman'73]



T2:

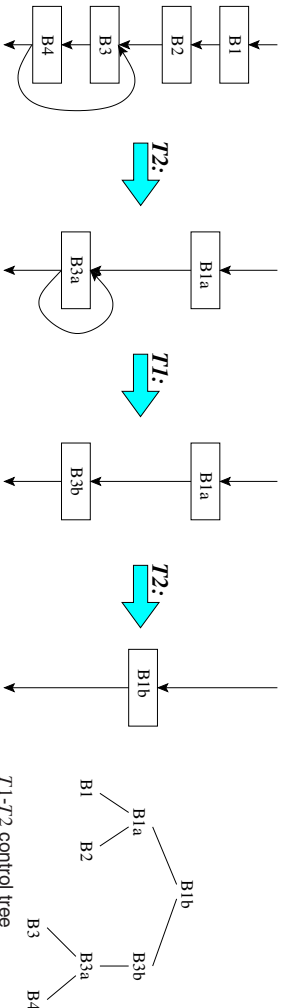


- Try to fold entire flow graph into a single node
- Works only for very restricted flow graphs

T1-T2 Analysis — Example



Example:



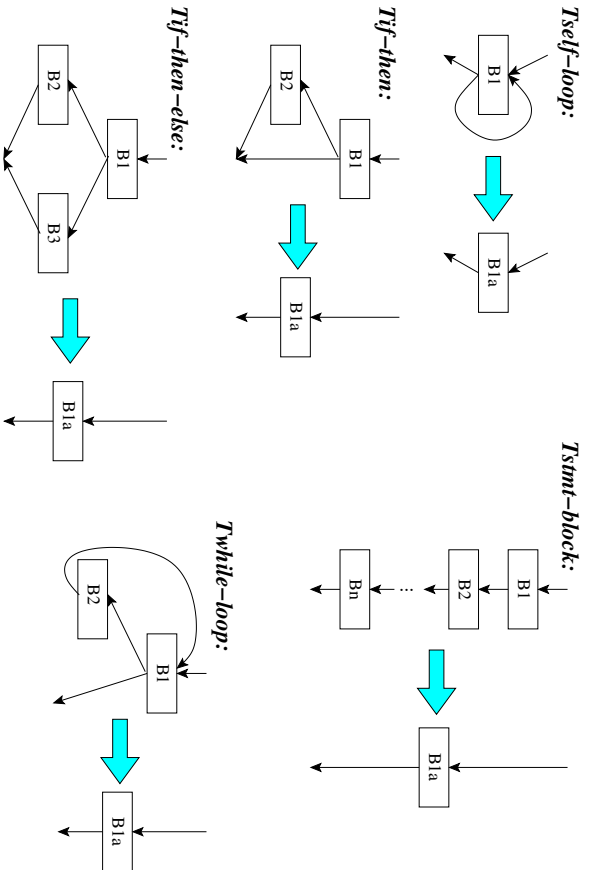
Structural Analysis

is a special case of interval analysis:

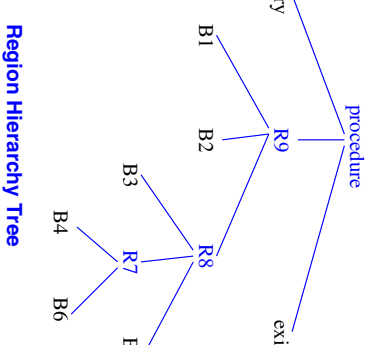
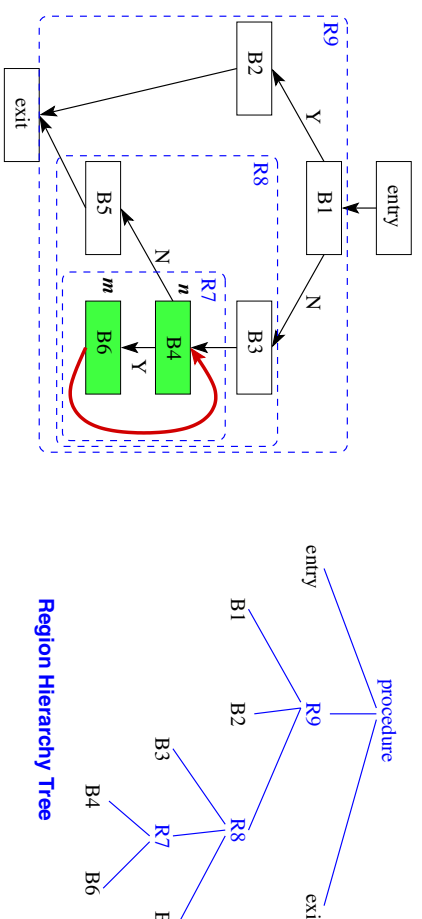
- CFG folding follows the hierarchical structure of the program
→ folding transformations for loops, if-then-else, switch, etc.
- Every region has 1 entry point
- Works only for well-structured programs
 - Extensions to handle arbitrary flowgraphs
(define a new region / transf. for otherwise irreducible constructs)

+ Equations etc. for dataflow analysis can be pre-formulated for each construct → faster

Structural analysis — Some regions and transformations



Example (cont.): Structural analysis



Remark: If only loop-based regions are of interest, the hierarchy flattens accordingly (R8 and R9 merged with top level).

Computing a bottom-up order of regions of a reducible flow graph

Input: A reducible flow graph G

Output: A bottom-up ordered list R of loop-based regions of G

1. $R \leftarrow \{B_1, B_2, \dots\}$ = all leaf regions, i.e., all single blocks in G , in any order

2. repeat

 Choose a natural loop L such that,

 if there are any natural loops L' contained within L ,

 then the (body and loop) regions for these L' were already added to R .

R .add(the region consisting of the body of L)

 // body of $L = L$ without the back edges to the header of L

R .add (the loop region for L)

until all natural loops have been considered

3. If the entire flow graph is not itself a natural loop,

R .add(the region consisting of the entire flow graph).

Summary: Control-Flow Analysis

- Basic blocks, extended basic blocks
- Loop detection
- Dominator-based CFA
- Interval-based CFA
- Structural analysis