

Föreläsning 18

Sorting and selection

TDDD86: DALP

Utskriftsversion av Föreläsning i *Datastrukturer, algoritmer och programmeringsparadigm*
25 November 2024

IDA, Linköpings universitet

18.1

Content

Contents

1	Sorting	1
1.1	Introduction	1
1.2	Insertion sort	2
1.3	Selection sort	2
1.4	Divide-and-conquer	3
1.5	Quick-sort	4
2	Selection	10
2.1	Introduction	10
2.2	Quick-select	10

18.2

1 Sorting

1.1 Introduction

Sorting

Input:

- A list L containing data with *keys* from totally ordered set K

Output:

- A list L' with the same data sorted in increasing order wrt. the keys

Example

$[8, 2, 9, 4, 6, 10, 1, 4] \rightarrow [1, 2, 4, 4, 6, 8, 9, 10]$

18.3

Sorting categories

- in-place vs out-of-place sorting
- internal vs external sorting
- stable vs non-stable sorting
- Comparison vs non-comparison sorting

18.4

Strategies

Sorting by insertion

Look for the right place to insert each new element that needs to be added to the sorted sequence. . . *Insertion sort*, Shell sort, . . .

Sorting by selection

Look, at each iteration, in the unsorted sequence for the least element left and add it to the end of sorted sequence. . . *Selection sort*, *Heap sort*, . . .

Sorting by permutation

Search in some pattern and permute places each time a pair is found to violate the targeted order. . . *Quick sort*, *Merge sort*, . . .

18.5

1.2 Insertion sort

(Linear) insertion sort

- An in-place algorithm!
- Partition the array that is to be sorted $A[0, \dots, n-1]$ into two parts:
 - A sorted $A[0, \dots, i-1]$ part
 - An unsorted $A[i, \dots, n-1]$ part

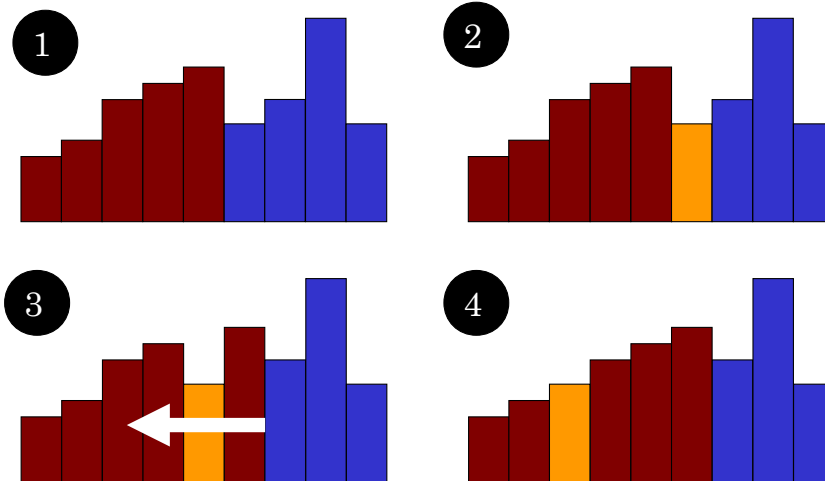
Initially, $i = 1$ and $A[0, \dots, 0]$ is (trivially) sorted

```

procedure INSERTIONSORT( $A[0, \dots, n-1]$ )
  for  $i = 1$  to  $n-1$  do
    insert in  $A[i]$  in the right position in  $A[0, \dots, i-1]$ 
  
```

18.6

Example: Visualizing insertion sort



18.7

Worst case analysis for insertion sort

```

1: procedure INSERTIONSORT( $A[0, \dots, n-1]$ )
2:   for  $i = 1$  to  $n-1$  do
3:      $j \leftarrow i; x \leftarrow A[i]$ 
4:     while  $j \geq 1$  and  $A[j-1] > x$  do
5:        $A[j] \leftarrow A[j-1]; j \leftarrow j-1$ 
6:      $A[j] \leftarrow x$ 
  
```

- t_2 : $n-1$ times
- t_3 : $n-1$ times
- t_4 : Let I be the number of iterations in the worst case for the inner loop:

$$I = 1 + 2 + \dots + (n-1) = n(n-1)/2 = (n^2 - n)/2$$

- t_5 : I time
- t_6 : $n-1$ time
- Total: $t_2 + t_3 + t_4 + t_5 + t_6 = 3(n-1) + (n^2 - n) = n^2 + 2n - 3$ So $O(n^2)$ in the worst case. ... *but good if the sequence is almost sorted*

18.8

1.3 Selection sort

Selection sort

- An in-place algorithm
- Partition the array to be sorted $A[0, \dots, n-1]$ into two parts
 - A sorted $A[0, \dots, i-1]$ where all elements are smaller or equal to $A[i, \dots, n-1]$
 - An unsorted sequence $A[i, \dots, n-1]$

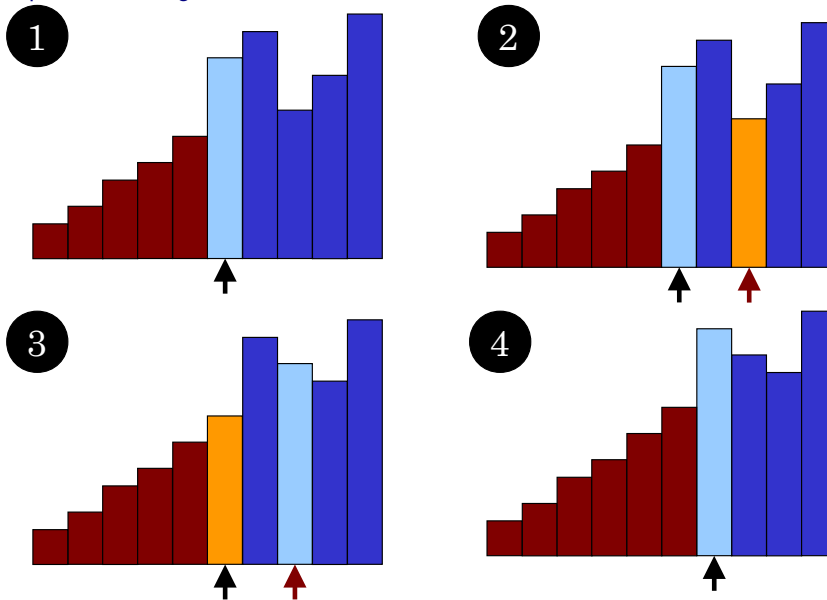
Initially $i = 0$, hence, the sorted part is empty (and hence trivially sorted)

```

procedure SELECTIONSORT( $A[0, \dots, n-1]$ )
  for  $i = 0$  to  $n-2$  do
    find minimal element  $A[j]$  in  $A[i, \dots, n-1]$ 
    swap  $A[i]$  and  $A[j]$ 
  
```

18.9

Example: Visualizing Selection-sort



18.10

Worst case analysis of Selection-sort

```

1: procedure SELECTIONSORT( $A[0, \dots, n-1]$ )
2:   for  $i = 0$  to  $n-2$  do
3:      $s \leftarrow i$ 
4:     for  $j \geq i+1$  to  $n-1$  do
5:       if  $A[j] < A[s]$  then  $s \leftarrow j$ 
6:     SWAP( $A[i], A[s]$ )
  
```

- t_2 : $n-1$ times
- t_3 : $n-1$ times
- t_4 : Let I be the number of iterations of the inner loop in the worst case:

$$I = (n-2) + (n-3) + \dots + 1 = (n-1)(n-2)/2 = (n^2 - 3n + 2)/2$$

- t_5 : I times
- t_6 : $n-1$ times
- Total: $t_2 + t_3 + t_4 + t_5 + t_6 = 3(n-1) + (n^2 - 3n + 2) = n^2 - 1 \in O(n^2)$

18.11

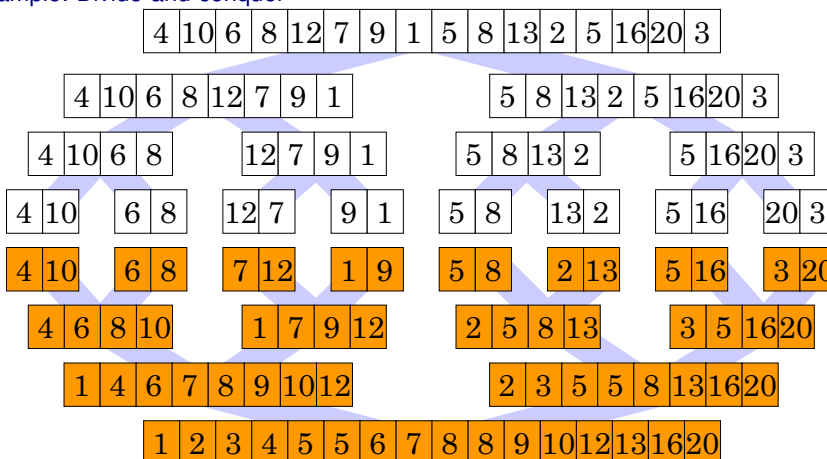
1.4 Divide-and-conquer

The divide-and-conquer paradigm in algorithm construction

- **divide**: divide the problem in smaller independent problems
- **conquer**: solve the sub-problems recursively (or directly if trivially)
- **combine** solutions of the sub-problems into a solution to the original problem

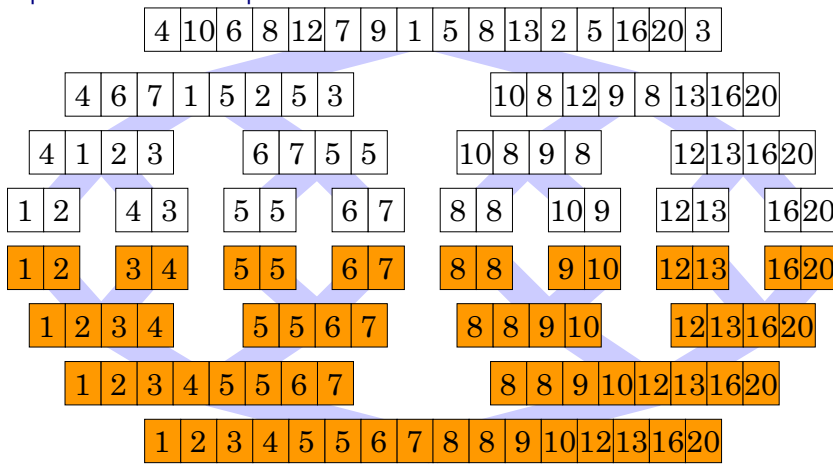
18.12

Example: Divide-and-conquer



18.13

Example: Divide-and-conquer



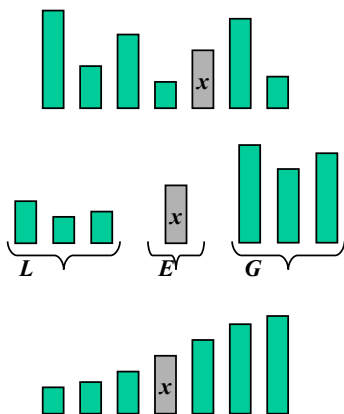
18.14

1.5 Quick-sort

Quick-sort

Quick-sort is a *randomized* sorting algorithm based on the divide-and-conquer paradigm

- **Divide**: randomly choose an element x (called pivot) and partition S to
 - L elements smaller than x
 - E elements equal to x
 - G elements larger than x
- **Conquer**: sort L and G
- **Combine** L , E and G



18.15

Partitioning

- Partition input sequence S as follows:
 - We remove, one element at a time, each element y from S and
 - Insert y in L , E or G depending on the result of the comparison with the pivot-element x
- Each insertion or removal takes place at the beginning or end of a sequence and requires $O(1)$ time
- The partitioning step takes $O(n)$ time

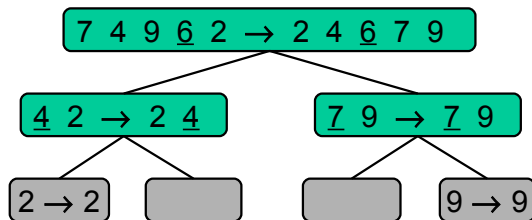
```

function PARTITION( $S, p$ )
 $L, E, G \leftarrow$  empty sequences
 $x \leftarrow S.REMOVE(p)$ 
while  $\neg S.ISEMPTY()$  do
     $y \leftarrow S.REMOVE(S.FIRST())$ 
    if  $y < x$  then
         $L.INSERTLAST(y)$ 
    else if  $y = x$  then
         $E.INSERTLAST(y)$ 
    else
         $G.INSERTLAST(y)$ 
return  $L, E, G$ 
    
```

18.16

Quick-sort tree

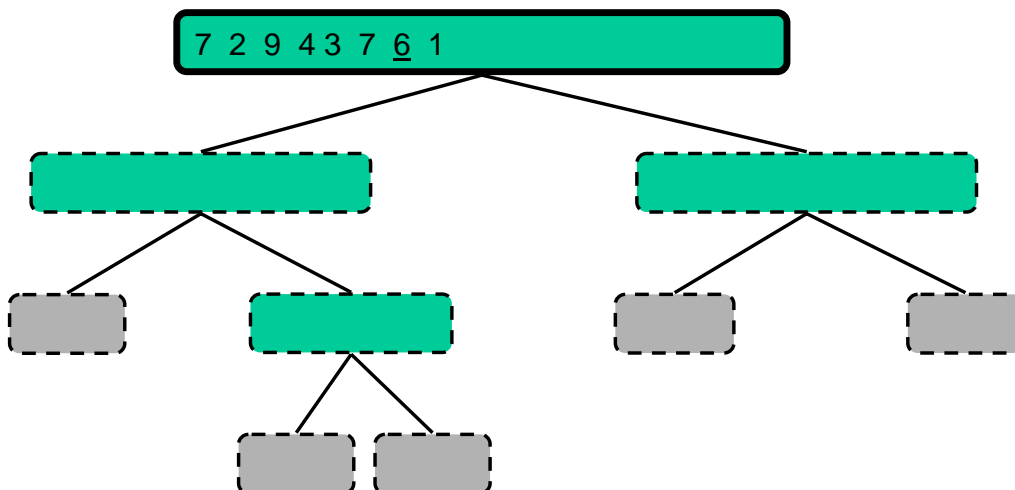
- Execution of quick-sort can be visualized as a binary tree
 - Each node represents a recursive call to quick-sort and stores
 - * Unsorted sequence before execution and the pivot
 - * Sorted sequence after execution
 - Root is the original call
 - Leaves are calls to sub-sequences of lengths 0 or 1



18.17

Example: Execution of quick-sort

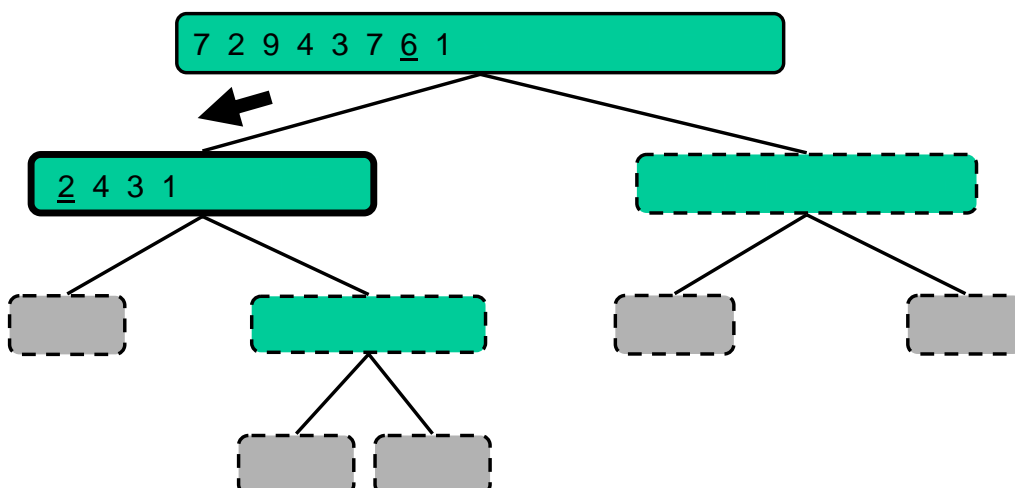
- Choice of a pivot
- example: 6, 2, 3, 7



18.18

Example: Execution of quick-sort

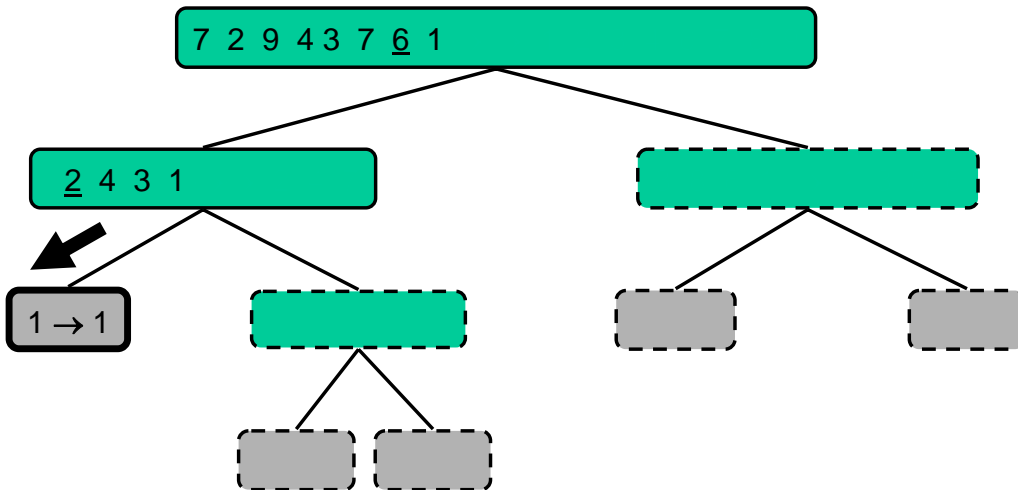
- Partitioning, recursive call, choice of a pivot



18.19

Example: Execution of quick-sort

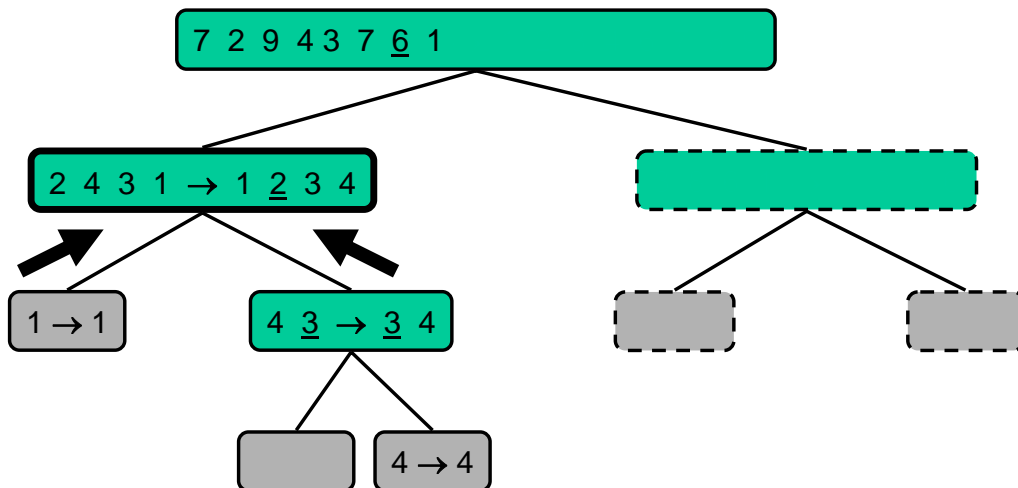
- Partitioning, recursive call, base case



18.20

Example: Execution of quick-sort

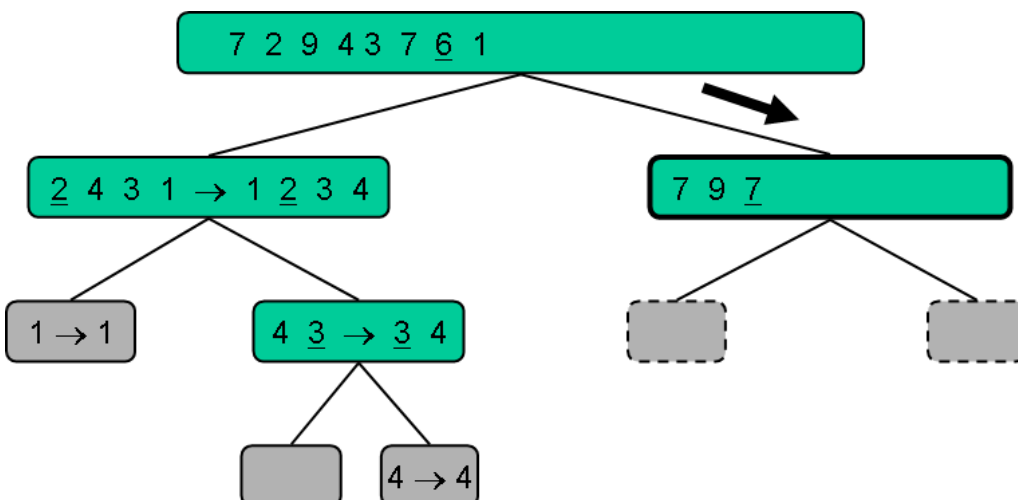
- Recursive call, ..., base case, combine



18.21

Example: Execution of quick-sort

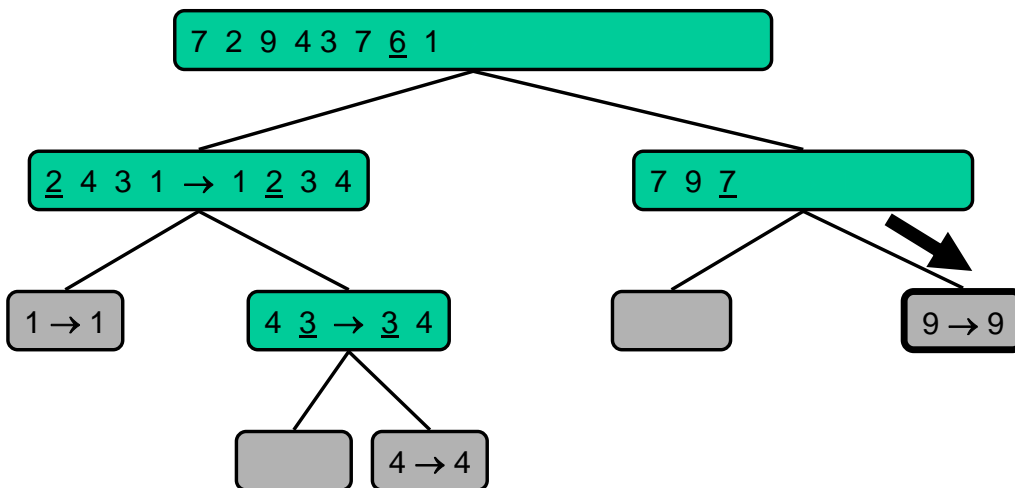
- Recursive call, choice of pivot



18.22

Example: Execution of quick-sort

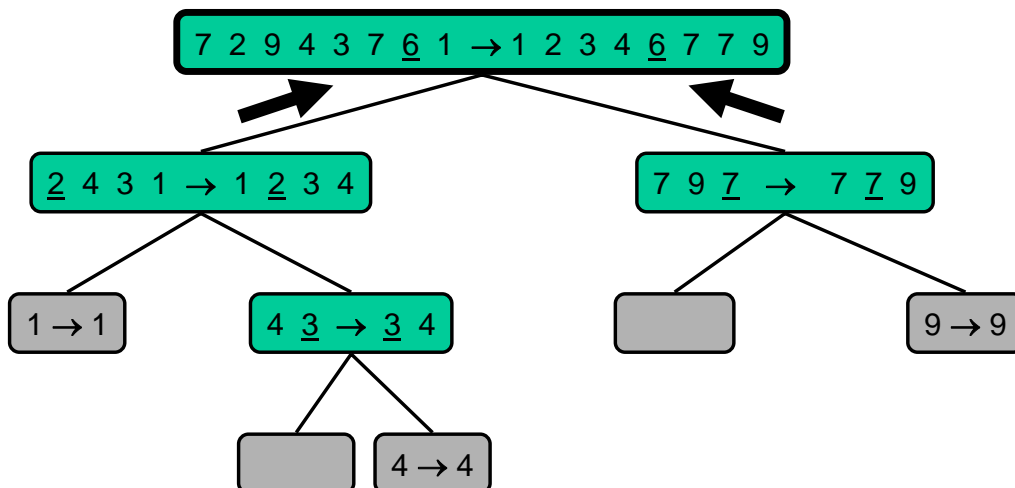
- Partitioning, ..., recursive call, base case



18.23

Example: Execution of quick-sort

- Combine



18.24

Execution time in worst-case

- Worst case for quick-sort happens when the pivot element is a unique minimal or maximal element
- One of L or G is $n - 1$ elements long and the other is of length 0
- Execution time is then proportional to the sum

$$n + (n - 1) + \dots + 2 + 1$$

- The worst case execution time of quick-sort is then $O(n^2)$

18.25

Execution time in worst-case

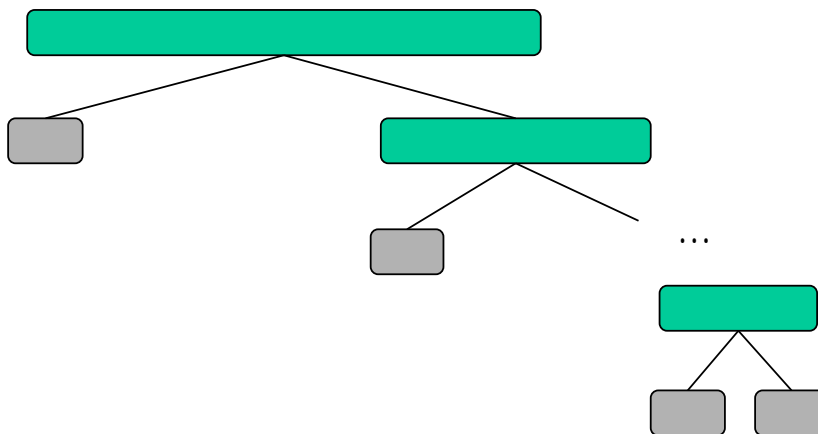
djup tid

0 n

1 $n-1$

... ..

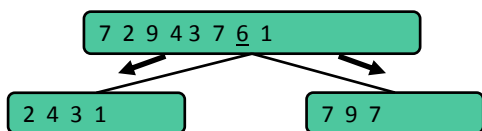
$n-1$ 1



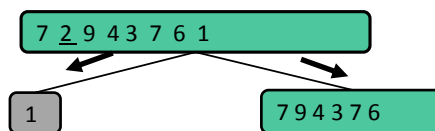
18.26

Expected execution time

- Consider a recursive call in quick-sort on a sequence of length s
 - A good call: length of L and G are both $< 3s/4$
 - A bad call: one of L or G has length $\geq 3s/4$

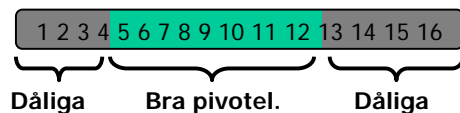


Bra anrop



Dåligt anrop

- A call is good with probability $1/2$
 - Half of all possible pivots result in a good call:



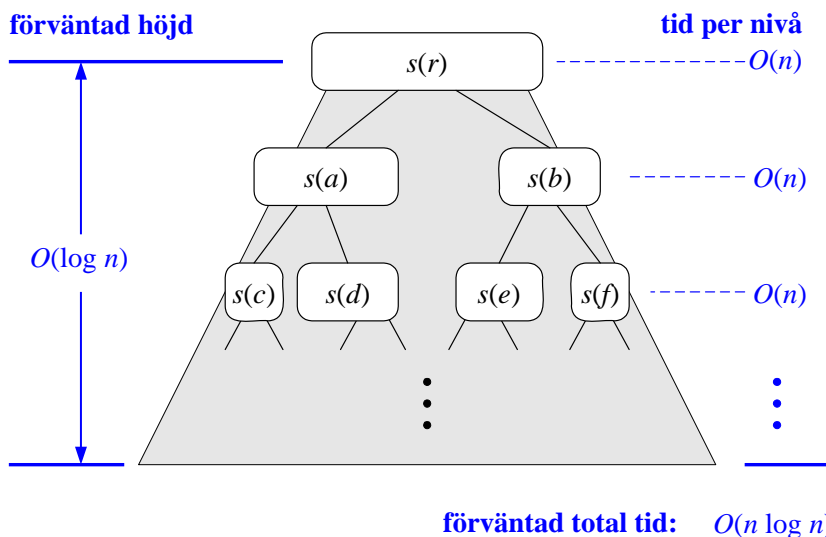
18.27

Expected execution time

- Probabilistic fact: Expected number of coin flips to obtain k heads is $2k$
- For a node at depth i , we expect:
 - $i/2$ ancestors are good calls
 - length of the input sequence is at most $(3/4)^{i/2}n$
- Consequently:
 - For a node at depth $2\log_{4/3} n$, the expected input sequence length is at most 1
 - The expected height of the quick-sort tree is $O(\log n)$
- Amount of work performed at the same depth is $O(n)$
- Therefore, the expected execution time for quick sort is $O(n \log n)$

18.28

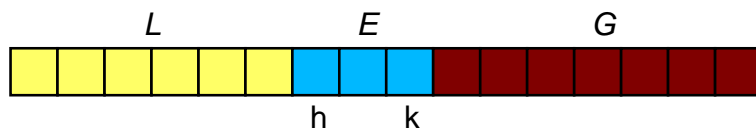
Expected execution time



18.29

Quick-sort with constant extra memory

- Quick-sort can be implemented as an *in-place* sorting algorithm
- In the partitioning step, we rearrange the elements in the input sequence so that:
 - elements that are less than the pivot element have a rank that is smaller than h
 - elements that are equal to the pivot element have a rank between h and k
 - elements that are larger than the pivot element have a rank that is larger than k



18.30

Algorithm for quick-sort with constant extra memory

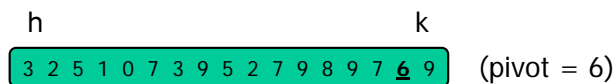
```

procedure INPLACEQUICKSORT( $S, l, r$ )
  if  $l \geq r$  then return
   $i \leftarrow$  randomly chosen rank between  $l$  and  $r$ 
   $x \leftarrow S.ELEMENTRANK(i)$ 
   $(h, k) \leftarrow$  INPLACEPARTITION( $x$ )
  INPLACEQUICKSORT( $S, l, h - 1$ )
  INPLACEQUICKSORT( $S, k + 1, r$ )
  
```

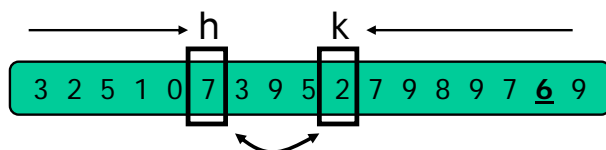
18.31

Partitioning with constant extra memory

- Perform partitioning using two indices to partition S in L and $E \cup G$ (a similar method can be used to partition $E \cup G$ in E and G)



- Repeat until h and k cross each other (i.e., $h > k$):
 - Sweep h to the right until an element \geq than the pivot element is found
 - Sweep k to the left until an element $<$ pivot element is found
 - Swap the elements at indices h and k



18.32

2 Selection

2.1 Introduction

Selection problem

- Given an integer i and n elements x_1, x_2, \dots, x_n from a total order, find the i th smallest element in the sequence.
- We could sort the sequence in $O(n \log n)$ time and then index the i :th element in constant time.

i=3 [7 4 9 6 2 → 2 4 6 7 9

- Can we solve the selection problem faster?

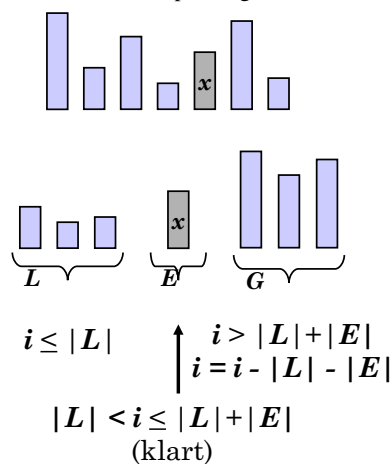
18.33

2.2 Quick-select

Quick-select

Quick-Select is a randomized selection algorithm based on the *prune-and-search* paradigm:

- *Prune*: choose x randomly and partition S into
 - L elements smaller than x
 - E elements equal to x
 - G elements larger than x
- *Search*: depending on i , the solution is either in E or we need to continue recursively in L or G



18.34

Partitioning

- Partition input sequence as in quick-sort:
 - We pick, one element at a time, each element y from S and
 - Insert y in L , E or G depending on the result of comparison with the pivot x
- Each insertion or removal is in the beginning or the end of a sequence, and therefore takes $O(1)$ time
- Consequently, the partitioning step in quick-select takes $O(n)$ time

```

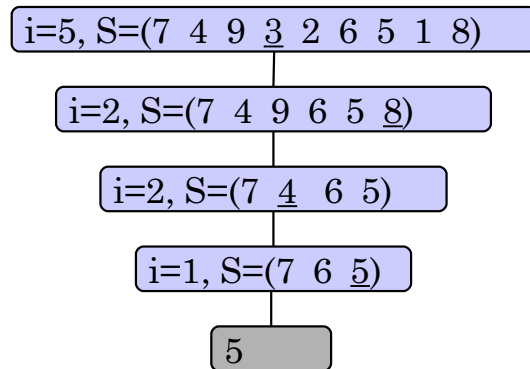
function PARTITION( $S, p$ )
   $L, E, G \leftarrow$  empty sequences
   $x \leftarrow S.REMOVE(p)$ 
  while  $\neg S.ISEMPTY()$  do
     $y \leftarrow S.REMOVE(S.FIRST())$ 
    if  $y < x$  then
       $L.INSERTLAST(y)$ 
    else if  $y = x$  then
       $E.INSERTLAST(y)$ 
    else
       $G.INSERTLAST(y)$ 
  return  $L, E, G$ 

```

18.35

Visualizing Quick-select

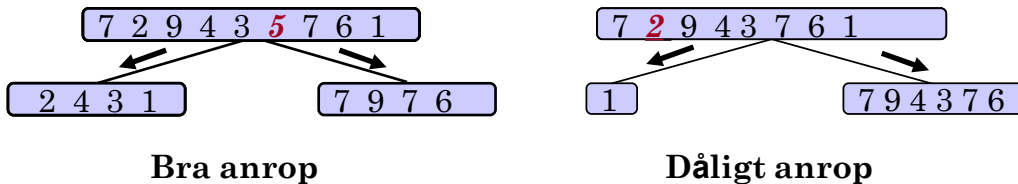
- Execution of quick-select can be visualized with the recursion path
 - Each node represents a recursive call to quick-select and stores i and the remaining sequence S



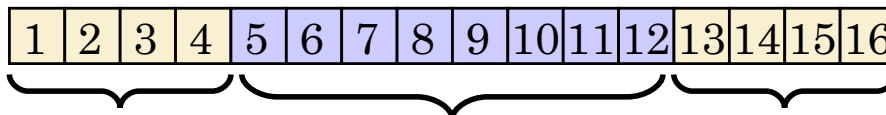
18.36

Expected execution time

- Consider a recursive call to quick-select on a sequence of length s
 - Good call: lengths of L and G are both $< 3s/4$
 - Bad call: one of L or G has a length $\geq 3s/4$



- A call is good with probability $1/2$
 - Half of all the possible pivot elements result in good calls:



Dåliga pivotelement Bra pivotelement Dåliga pivotelement

18.37

Expected execution time

- Probabilistic fact: The expected number of coin flips to get a head is two.
- Probabilistic fact: Expected function is linear
 - $E(X + Y) = E(X) + E(Y)$
 - $E(c \times X) = c \times E(X)$ for any constant c
- Let $T(n)$ be the expected execution time for quick-select
- We have $T(n) \leq b \cdot n \cdot g(n) + T(3n/4)$ where:
 - b is some constant
 - $g(n)$ is the expected number of call before a good call

18.38

Expected execution time

- Consequently:
 - $T(n) \leq b \cdot n \cdot g(n) + T(3n/4)$
- Since a good call is expected to happen in two steps:
 - $T(n) \leq 2 \cdot b \cdot n + T(3n/4)$
- Hence, $T(n)$ is bounded by a geometric series:
 - $T(n) \leq 2 \cdot b \cdot n + 2 \cdot b \cdot n \cdot (3/4) + 2 \cdot b \cdot n \cdot (3/4)^2 + 2 \cdot b \cdot n \cdot (3/4)^3 + \dots$
- As a result, $T(n) \in O(n)$
- We can solve the selection problem in $O(n)$ expected time (worst case is $O(n^2)$ time)

18.39