

TDDDD07 – Real-time Systems

Lecture 9: Dependability and Design

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Dependability topics



Lectures 7 - 9 cover theory and practical examples

- Basic notions of dependability and redundancy in fault-tolerant systems
- Fault tolerance:
 - Relating faults/redundancy to distributed systems from lectures 4-6
 - Relating timing and fault tolerance

Lecture 8: Adds industrial perspective

Lecture 9: Fault prevention and design aspects

Treatment of faults

- Recall: four approaches for treating faults in dependable systems
- This lecture:
 1. Fault prevention
 2. Fault removal
 3. Fault tolerance
 4. Fault forecasting

Reading Material

- Ch. 15.1-15.4, 15.7 B&W or Ch. 5.2-5.3 in Carlsson et al.
- Section 5.1 and 5.3 of article by Avezienis et al. 2004
- Platform-independent design: Huang et al. 2003
- UML-MARTE: Weissnegger et al. 2015

Why dependability-by-design is important (and hard)

System Requirements

- Functional requirements
 - Describe the main objectives of the system, referred to as “correct service” earlier
- Extra-functional requirements
 - Cover other requirements not relating to main function, in particular dependability
 - acceptable frequency and severity of service failures
 - Also called non-functional properties (NFP), e.g. Timeliness, availability, energy efficiency
- Let's start with one that we studied in this course...

Design for timeliness

Basic approach:

- define end-to-end deadlines
- define deadlines for individual tasks
- ascertain (worst case) execution/communication time for each task/message
- document assumptions/restrictions
- Prove/show that implementation satisfies requirements



So, what is so hard about this?

Layers of design

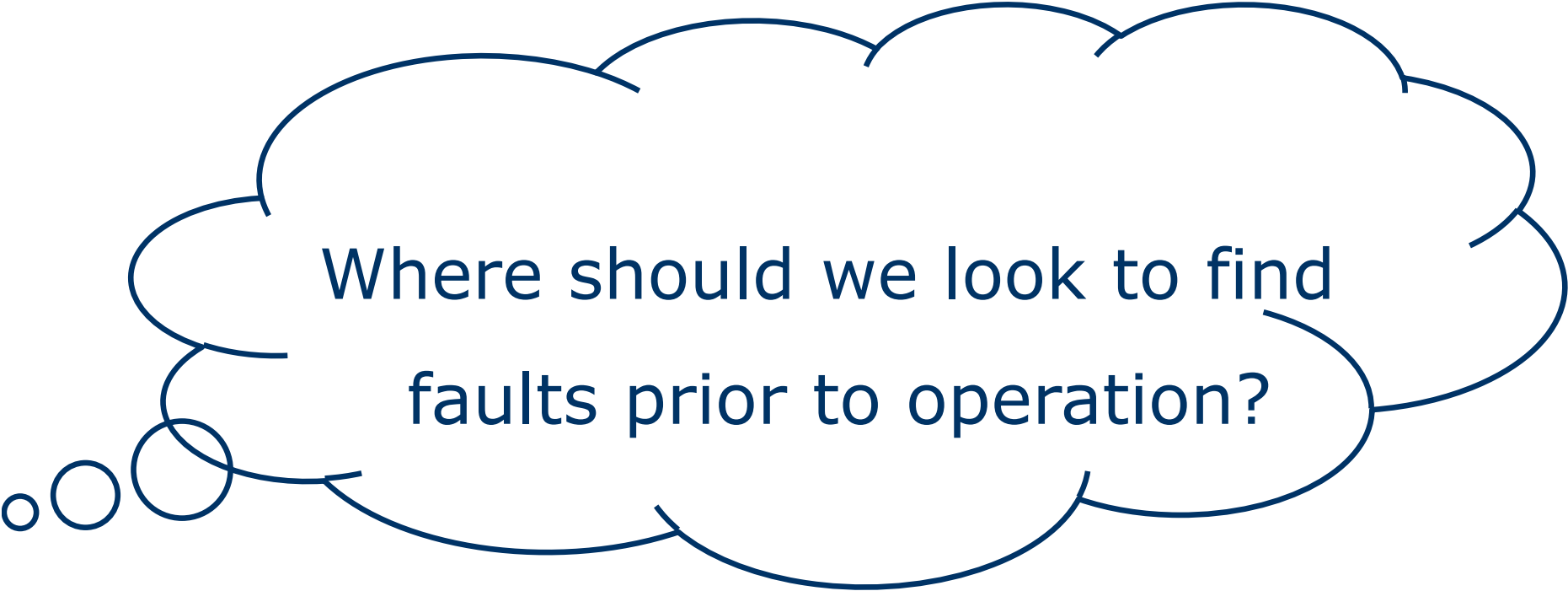
Application modelling support

Programming environment support

System software support
(kernels, communication protocols)

Hardware support

Fault prevention/removal



Where should we look to find faults prior to operation?

Historical snapshots

- Hardware design
 - 1970's Dedicated hardware
 - 1980's Microcomputers & ASICS
 - 1990's High performance Microcomputers, FPGAs, MEMs
 - 2000's SoCware, Multicore
- Earlier predictable hardware is replaced with components that are complex to analyse (caches, pipelines, inter-connects, accelerators)

Layers of design

Application modelling support

Programming environment support

System software support (kernels)

Hardware support

Historical snapshots

- OS Scheduling principles
 - 1970's Fixed priority scheduling
 - 1980's Multiprocessor, Dynamic
 - 1990's Incorporating shared resources
 - 2000's Load variations, Multicore scheduling
- OS interfaces to optimise memory management e.g. prefetching instructions to boost performance, Virtualisers/orchestrators in cloud platforms

Layers of design

Application modelling support

Programming environment support

System software support (kernels)

Hardware support

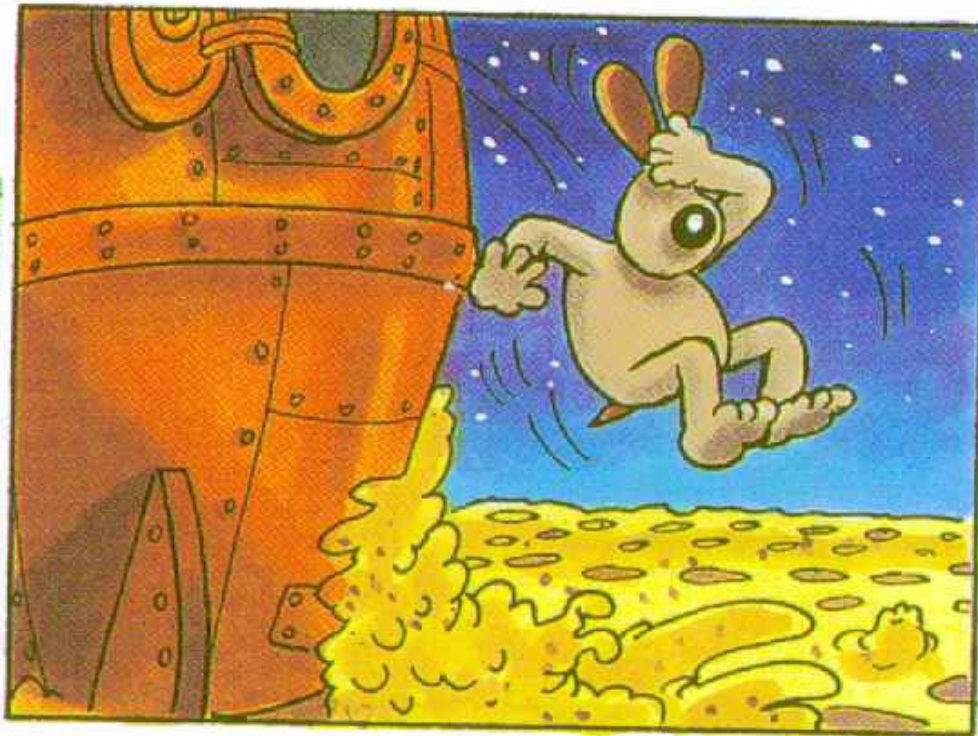
Historical snapshots

- Programming environments
 - 1970's "High" level programming
 - 1980's Real-time specific: Ada
 - 1990's OO languages, languages with formal semantics
 - 2000's Software libraries (reuse), AUTOSAR components in automotive
- Today: Data-driven, machine learning!

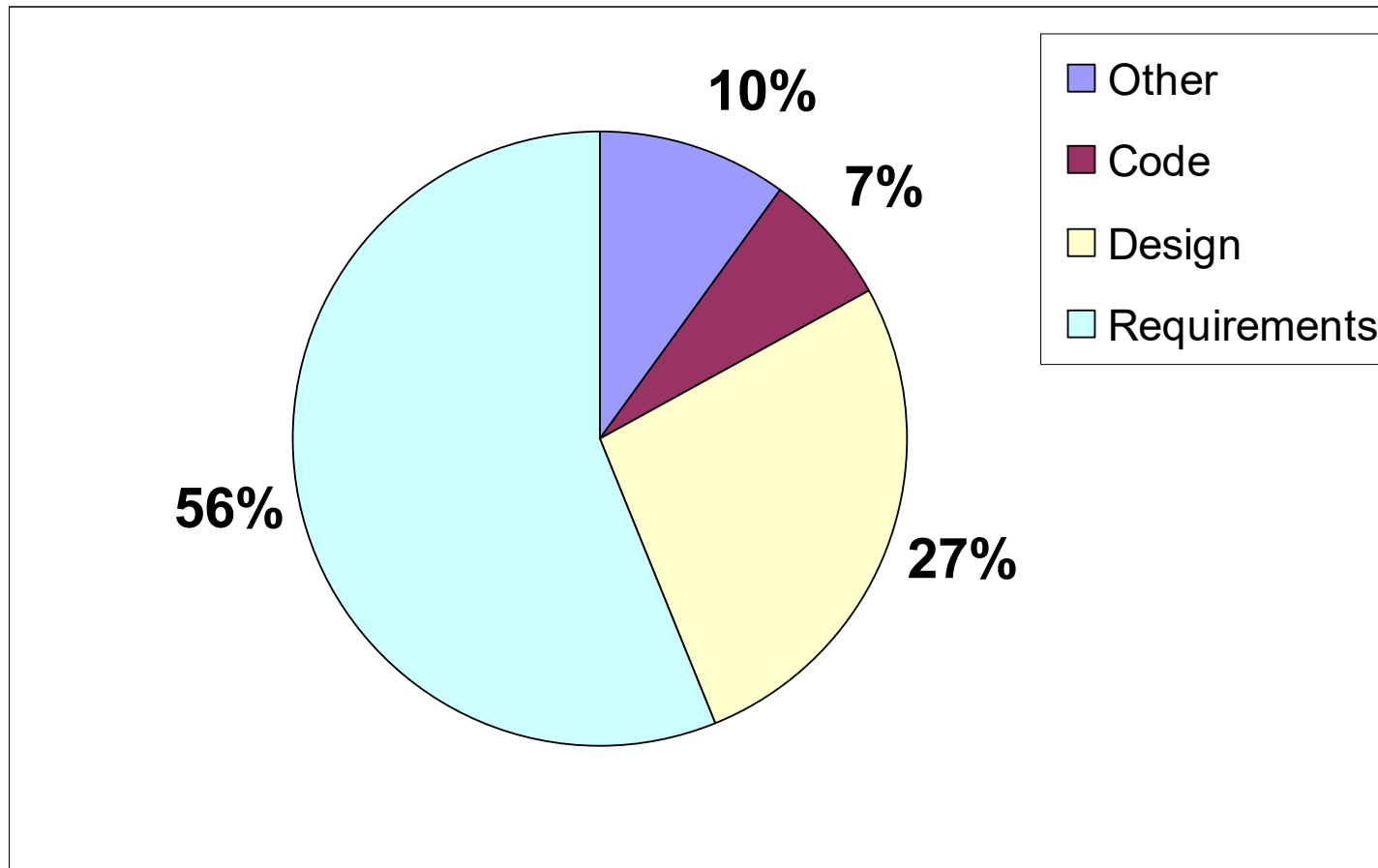


Engineers: Fool me once,
shame on you – fool me
twice, shame on me

Software developers: Fool me N times, who cares, this is complex and anyway no one expects software to work...



Software: where do we find faults?



[Cooling 2003]

Testing is not enough...

If a test fails, what was the cause?

- Undocumented assumptions on operational conditions, external impact?
- Wrong program code?
- Unexpected impact of OS? Scheduling?
- Virtualiser overhead?
- Hardware timing dependencies?
- Embedded test code affecting timing?

Platform-independent design

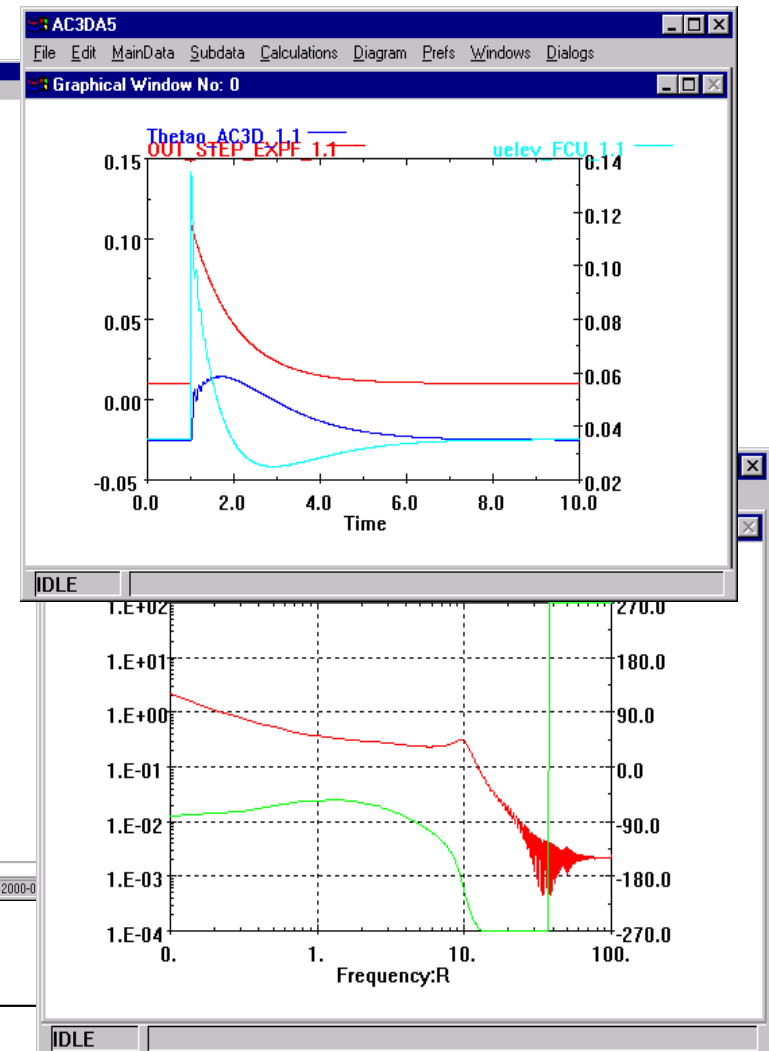
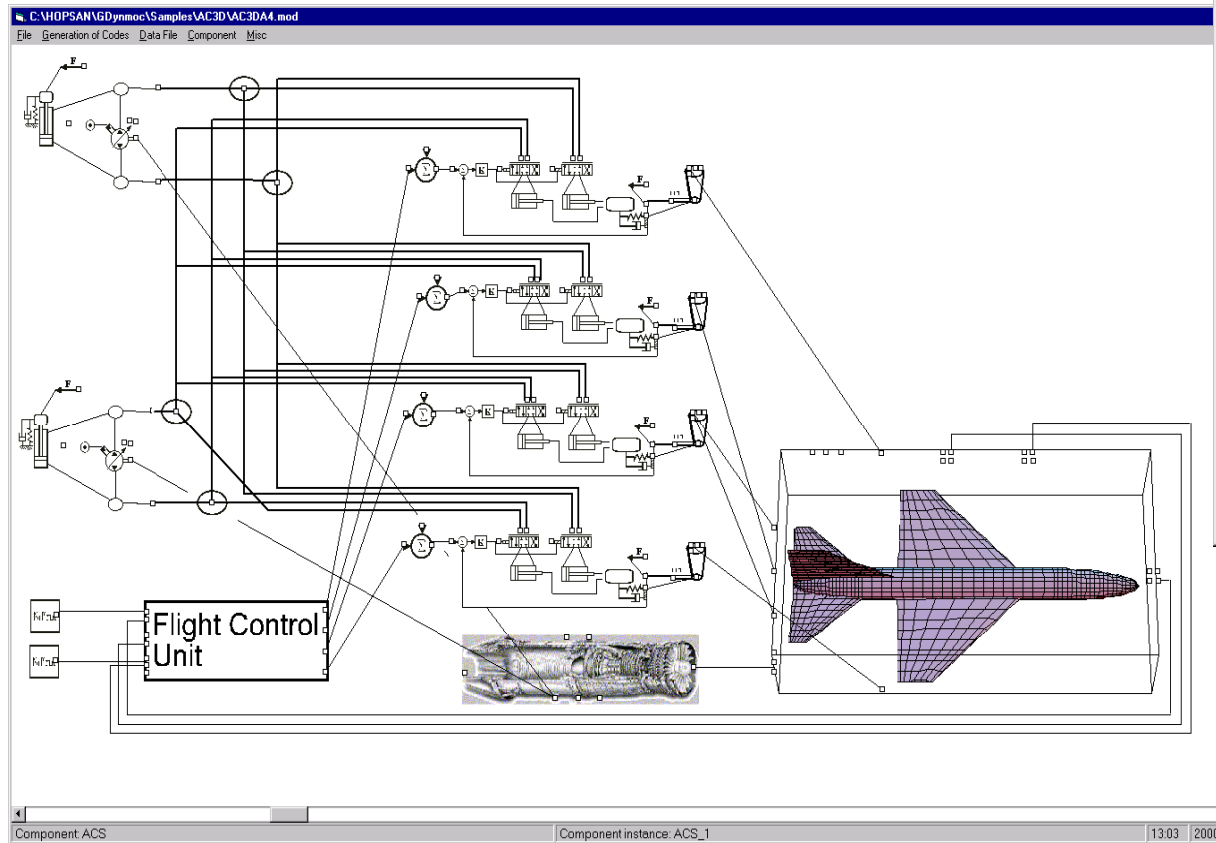


Eliminating “butterfly effect”
means trying to isolate the
impacts of different layers

Back to basics

- define end-to-end deadlines
 - Model the environment!
- define deadlines for individual tasks
 - Specify system decomposition!
- ascertain (worst case) execution/communication time for each task/message
 - Assume hardware/bus characteristics!
- document assumptions/restrictions
 - Model, model, model!
- Prove/show that implementation satisfies requirements
 - Analyse models, then test implementation!

Non-digital hardware



An engineering discipline

Using mathematics can never be wrong!

Model-based development (MBD)

Model-based development

- In software-intensive systems
 - Models as “higher level” programs
- Idea: use models to analyse the design, automatically generate code from the model!
- Adequate support for modularisation: Well-tested libraries with well-defined interfaces

Layers of design

Application modelling support

Programming environment support

System software support (kernels)

Hardware support

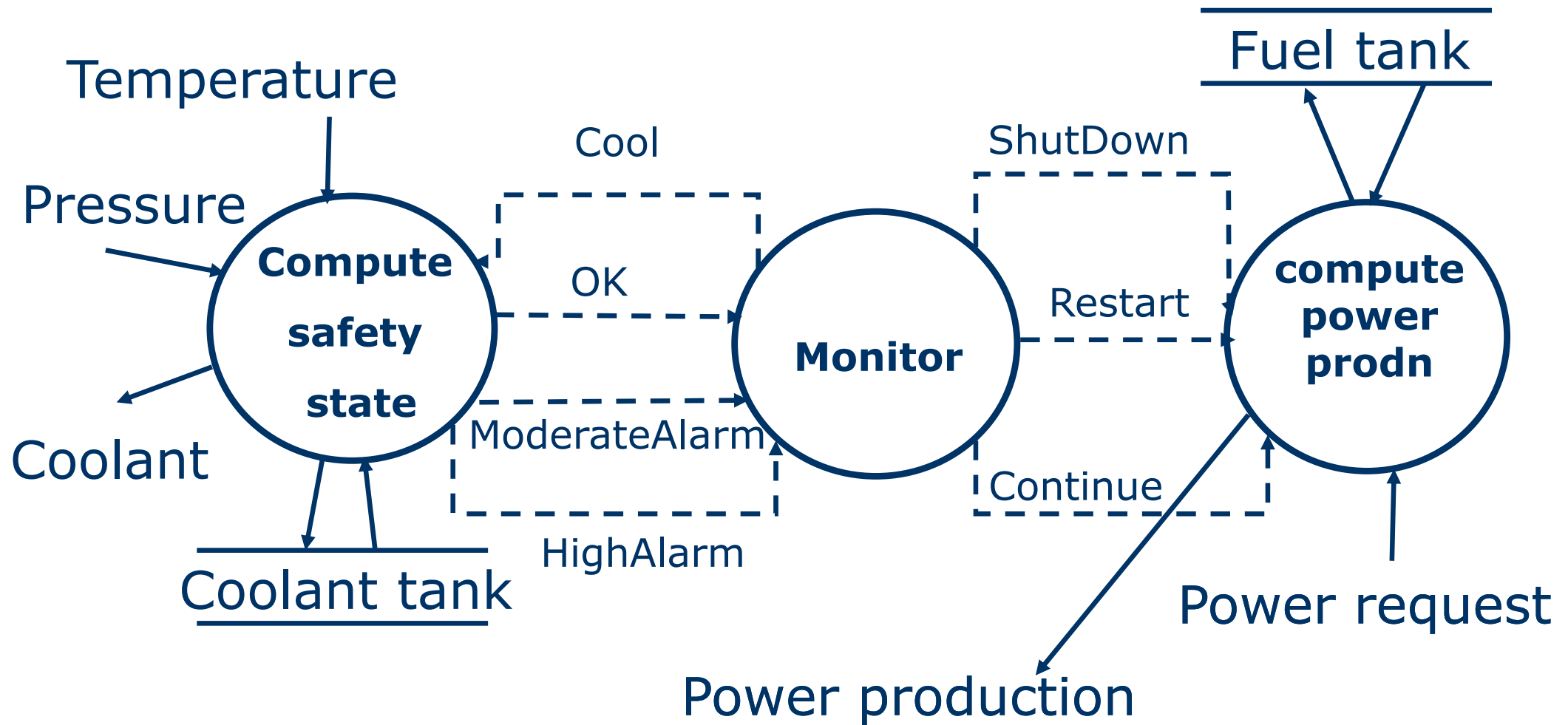
Historical snapshots

- Mathematical modelling & analysis tools
 - 1970's Sequential systems
 - 1980's Concurrent/Distributed systems
 - 1990's Timed models, Combining discrete & continuous, UML
 - 2000's Incorporation in tools: MBD (domain-specific or universal)
- Today: Models in learning-based systems, explainable AI

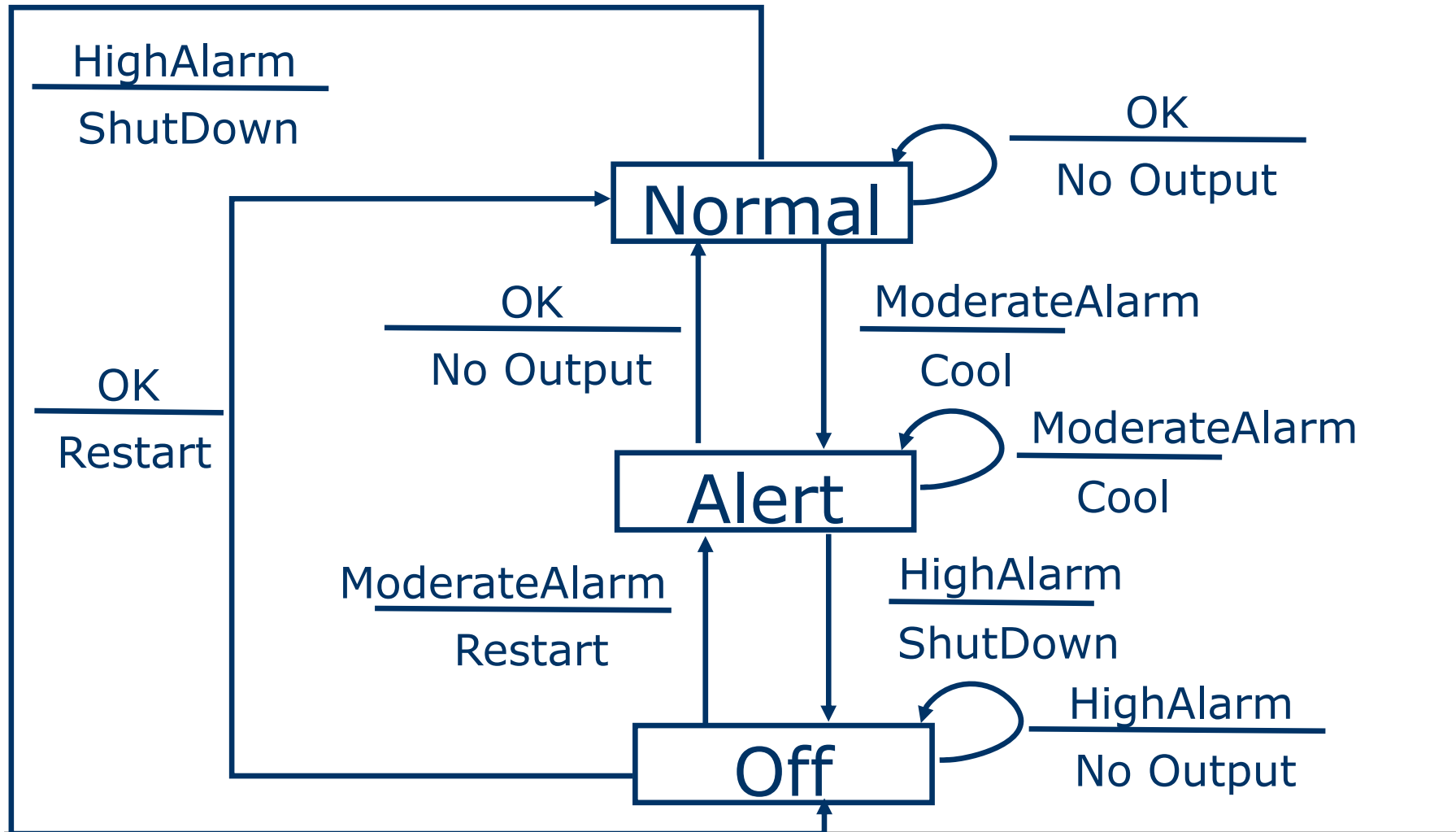
UML standard

- UML 2.0 models components with required and provided interfaces
- Family of modelling techniques that are a further development of languages in early 80's (Ward & Mellor Diagrams)
- Next two slides from an example
[Heitmeyer and Mandrioli, Wiley, 1996]

Power plant: Functional part & safety part



Monitor state machine



Fault prevention and removal

In classical (not learning based) software



What do we want to do with models once we create them?

Use of high-level models

- Tools to represent digital hardware and software components, support for *functional analysis by*
 - Simulations
- Theory:
 - Formal verification of functional properties
 - Semi-automatic code generation

Simulations of a model

Need a unique interpretation:

- What happens in this state if that input arrives?
- The language should
 - have (standard) operational semantics to enable “execution” of the model
 - be platform-independent

Simulations

What do they show?



Formal proofs

- Can be used to **Prove** that *specific* bad things *never* happen
- **Create counterexamples**, identify (design) faults that lead to demonstrated bad things
 - debugging the design
- Can be automated, but suffer from combinatorial explosion

Abstractions and search algorithms help

- Smart data structures for efficient representation of state space
- Smart deduction engines (satisfiability checkers) that find proofs fast
- Smart abstractions of the design to capture the essential properties
 - Synchronous languages (e.g. Esterel, Lustre), used for Airbus 320 software

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Adding time to UML

- UML profile for Real-time and Embedded Systems (MARTE)
- Is the approach most automotive and aerospace systems use if they are modelling at all...
- Meta-models for a class of systems with timing and performance parameters



See case study in the
Weissnegger et al. paper

Questions?

www.ida.liu.se/~TDDD07