

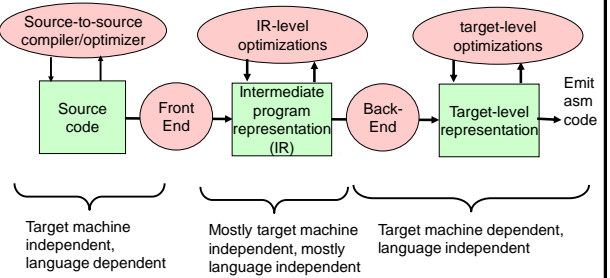


# Code Optimization

## Code Optimization – Overview



**Goal:** Faster code and/or smaller code and/or low energy consumption



## Remarks



- Often multiple levels of IR:
  - high-level IR (e.g. abstract syntax tree AST),
  - medium-level IR (e.g. quadruples, basic block graph),
  - low-level IR (e.g. directed acyclic graphs, DAGs)
- do optimization at most appropriate level of abstraction
- code generation is continuous lowering of the IR towards target code
- "Postpass optimization":  
done on *binary code* (after compilation or without compiling)

## Disadvantages of Compiler Optimizations



- Debugging made difficult
  - Code moves around or disappears
  - Important to be able to switch off optimization
- Increases compilation time
- May even affect program semantics
  - $A = B^*C - D + E \rightarrow A = B^*C + E - D$   
may lead to overflow if  $B^*C + E$  is a too large number

## Optimization at Different Levels of Program Representation



- **Source-level optimization**
  - Made on the source program (text)
  - Independent of target machine
- **Intermediate code optimization**
  - Made on the intermediate code (e.g. on AST trees, quadruples)
  - Mostly target machine independent
- **Target-level code optimization**
  - Made on the target machine code
  - Target machine dependent

## Source-level Optimization



At source code level, independent of target machine

- Replace a slow algorithm with a quicker one, e.g. Bubble sort  $\rightarrow$  Quick sort
- Poor algorithms are the main source of inefficiency but difficult to optimize
- Needs pattern matching, e.g. [K.'96] [di Martino, K. 2000]

## Intermediate Code Optimization



At the intermediate code (e.g., trees, quadruples) level  
In most cases target machine independent

- Local optimizations within basic blocks (e.g. common subexpression elimination)
- Loop optimizations (e.g. loop interchange to improve data locality)
- Global optimization (e.g. code motion, within procedures)
- Interprocedural optimization (between procedures)

## Target-level Code Optimization



At the target machine binary code level  
Dependent on the target machine

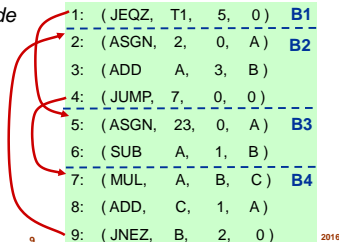
- Instruction selection, register allocation, instruction scheduling, branch prediction
- Peephole optimization

## Basic Block



A **basic block** is a sequence of textually consecutive operations (e.g. quadruples) that contains no branches (except perhaps its last operation) and no branch targets (except perhaps its first operation).

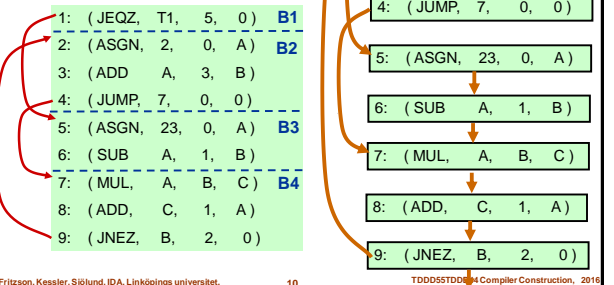
- Always executed in same order from entry to exit
- A.k.a. *straight-line code*



## Control Flow Graph



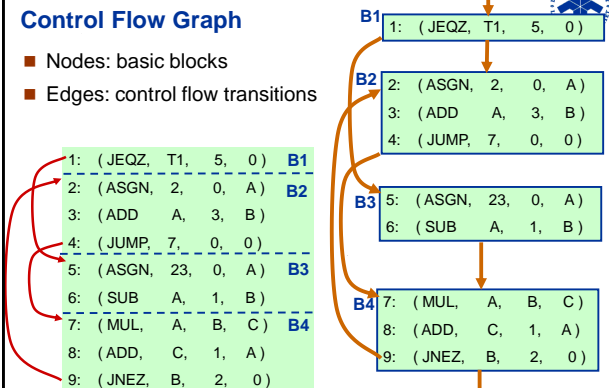
Nodes: primitive operations (e.g. quadruples), or basic blocks.  
Edges: control flow transitions



## Basic Block Control Flow Graph



Nodes: basic blocks  
Edges: control flow transitions



## Local Optimization

(within single Basic Block)



## Local Optimization



- Within a single basic block
  - Needs no information about other blocks
- Example: **Constant folding** (Constant propagation)
  - Compute constant expressions at compile time

```

const int NN = 4;
...
i = 2 + NN;
j = i * 5 + a;
    
```

→

```

const int NN = 4;
...
i = 6;
j = 30 + a;
    
```

## Local Optimization (cont.)



- **Elimination of common subexpressions**

```

A[ i+1 ] = B[ i+1 ];
    
```

→

```

tmp = i+1;
A[ tmp ] = B[ tmp ];
    
```

```

D = D + C * B;
A = D + C * B;
    
```

→

```

T = C * B;
D = D + T;
A = D + T;
    
```

Common subexpression elimination builds **DAGs** (directed acyclic graphs) from expression trees and forests

NB: Redefinition of D → D+T is *not* a common subexpression! (does not refer to the same *value*)

## Local Optimization (cont.)



- **Reduction in operator strength**
  - Replace an expensive operation by a cheaper one (on the given target machine)

Example:  $x = y ** 2 \rightarrow x = y * y$

Example:  $x = 2.0 * y \rightarrow x = y + y$

Example: Concatenation in Snobol string language

$L := \text{Length}(S1 || S2) \rightarrow L := \text{Length}(S1) + \text{Length}(S2)$

## Some Other Machine-Independent Optimizations



- Array-references
  - $C = A[I, J] + A[I, J+1]$
  - Elements are beside each other in memory. Ought to be "give me the next element".
- Inline expansion of code for small routines
  - $x = \text{sqr}(y) \Rightarrow x = y * y$
- Short-circuit evaluation of tests
  - **while**  $(a > b)$  **and**  $(c-b < k)$  **and** ...
  - If **false** the rest does not need to be evaluated

## More examples of machine-independent optimization



- See for example the OpenModelica Compiler (<https://github.com/OpenModelica/OMCompiler/blob/master/Compiler/FrontEnd/ExpressionSimplify.mo>) optimizing abstract syntax trees

```

// listAppend(e1, {}) => e1 is O(1) instead of O(len(e1))
case DAE.CALL(path=Absyn.IDENT("listAppend"),
  expLst=(e1, DAE.LIST(valList={})))
  then e1;
// atan2(y, 0) = sign(y) * pi/2
case (DAE.CALL(path=Absyn.IDENT("atan2"), expLst=(e1, e2)))
guard Expression.isZero(e2)
algorithm
  e := Expression.makePureBuiltinCall(
    "sign", {e1}, DAE.T_REAL_DEFAULT);
then DAE.BINARY(
  DAE.RCONST(1.570796326794896619231321691639751442),
  DAE.MUL(DAE.T_REAL_DEFAULT),
  e);
    
```

## Exercise 1: Draw a basic block control flow graph (BB CFG)





# Loop Optimization

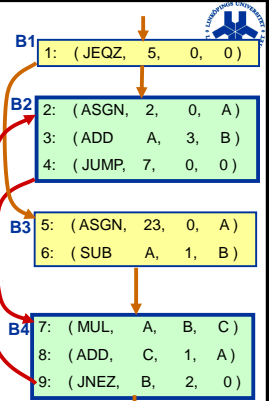
## Loop Optimization

Minimize time spent in a loop

- Time of loop body
- Data locality
- Loop control overhead

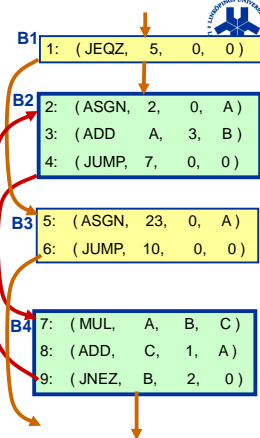
What is a loop?

- A **strongly connected component** (SCC) in the control flow graph resp. basic block graph
- SCC strongly connected, i.e., all nodes can be reached from all others
- Has a **unique** entry point
- Example: { B2, B4 } is an SCC with 2 entry points → not a loop in the strict sense...



## Loop Example

- Removed the 2nd entry point from the previous example
- Example: { B2, B4 } is an SCC with 1 entry points → is a loop!



## Loop Optimization Examples (1)

- Loop-invariant code hoisting
  - Move loop-invariant code out of the loop
- Example:

```

for (i=0; i<10; i++)
  a[i] = b[i] + c / d;
  
```

→

```

tmp = c / d;
for (i=0; i<10; i++)
  a[i] = b[i] + tmp;
  
```

## Loop Optimization Examples (2)

- Loop unrolling
  - Reduces loop overhead (number of tests/branches) by duplicating loop body. Faster code, but code size expands.
  - In general case, e.g. when odd number loop limit – make it even by handling 1st iteration in an if-statement before loop
- Example:

```

i = 1;
while (i <= 50) {
  a[i] = b[i];
  i = i + 1;
}
  
```

→

```

i = 1;
while (i <= 50) {
  a[i] = b[i];
  i = i + 1;
  a[i] = b[i];
  i = i + 1;
}
  
```

## Loop Optimization Examples (3)

- Loop interchange
  - To improve data locality, inner loop data access within a cache block (reduce cache misses / page faults)
- Example:

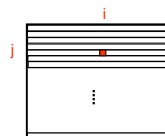
```

for (i=0; i<N; i++)
  for (j=0; j<M; j++)
    a[j][i] = 0.0;
  
```

→

```

for (j=0; j<M; j++)
  for (i=0; i<N; i++)
    a[j][i] = 0.0;
  
```



Faster with consecutive data accesses for inner loop

## Loop Optimization Examples (4)



### Loop fusion

- Merge loops with identical headers
- To improve data locality and reduce number of tests/branches
- Example:

```

for (i=0; i<N; i++)
  a[i] = ... ;
for (i=0; i<N; i++)
  ... = ... a[i] ... ;
    
```

→

```

for (i=0; i<N; i++) {
  a[i] = ... ;
  ... = ... a[i] ... ;
}
    
```

## Loop Optimization Examples (5)



### Loop collapsing

- Flatten a multi-dimensional loop nest
- May simplify addressing (relies on consecutive array layout in memory)
- Loss of structure
- Example:

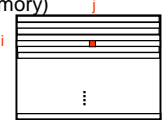
```

for (i=0; i<N; i++)
  for (j=0; j<M; j++)
    ... a[i][j] ... ;
    
```

→

```

for (ij=0; ij<M*N; ij++) {
  ... a[ij] ... ;
}
    
```



## Exercise 2: Draw CFG and find possible loops



## Global Optimization (within a single procedure)



## Global Optimization

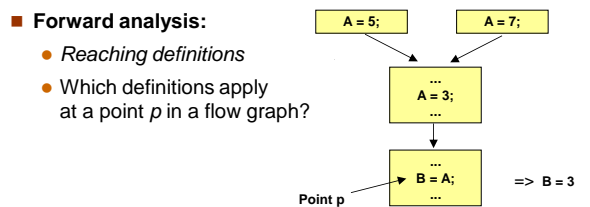


- More optimization can be achieved if a *whole procedure* is analyzed (Whole program analysis is called interprocedural analysis)
  - Global optimization is done within a single procedure
  - Needs *data flow analysis*
- Example global optimizations:
  - Remove variables which are never referenced.
  - Avoid calculations whose results are not used.
  - Remove code which is not called or reachable (i.e., *dead code elimination*).
  - Code motion
  - Find uninitialized variables

## Data Flow Analysis (1)



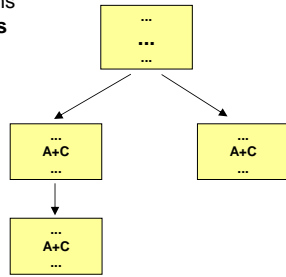
- Concepts:
  - *Definition*:  $A = 5$   $A$  is defined
  - *Use*:  $B = A * C$   $A$  is used
- The flow analysis is performed in two phases, forwards and backwards



## Data Flow Analysis (2), Forward

- Available expressions
  - Used to eliminate common subexpressions over block boundaries

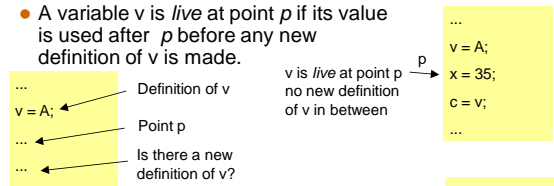
Example:  
An available expression  
A+C



## Data Flow Analysis (3), Backward

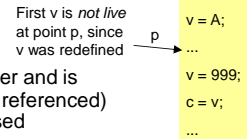
- Live variables

- A variable  $v$  is *live* at point  $p$  if its value is used after  $p$  before any new definition of  $v$  is made.



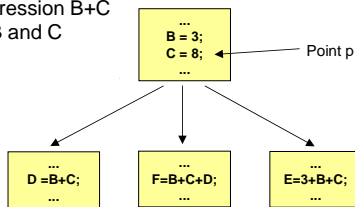
- Example:

- If variable  $A$  is in a register and is dead (not live, will not be referenced) the register can be released



## Data Flow Analysis (4), Backward

- Very-Busy Expressions or Anticipated Expressions
- An expression  $B+C$  is *very-busy* at point  $p$  if all paths leading from the point  $p$  eventually compute the value of the expression  $B+C$  from the values of  $B$  and  $C$  available at  $p$ .



## Remarks

- Need to analyze **data dependences** to make sure that transformations do not change the semantics of the code
- Global transformations** need control and data flow analysis (within a procedure – *intraprocedural*)
- Interprocedural analysis** deals with the whole program
- Covered in more detail in courses (Discontinued) TDDC86 Compiler optimizations and code generation (9 hp Ph.D. student level) DF00100 Advanced Compiler Construction

## Target Optimizations on Target Binary Code

## Target-level Optimizations

Often included in main code generation step of back end:

- Register allocation
  - Better register use → less memory accesses, less energy
- Instruction selection
  - Choice of more powerful instructions for same code → faster + shorter code, possibly using fewer registers too
- Instruction scheduling → reorder instructions for faster code
- Branch prediction (e.g. guided by profiling data)
- Predication of conditionally executed code

→ See lecture on code generation for RISC and superscalar processors (TDD844)  
→ Much more in TDDC86 Compiler optimizations and code generation

## Postpass Optimizations (1)

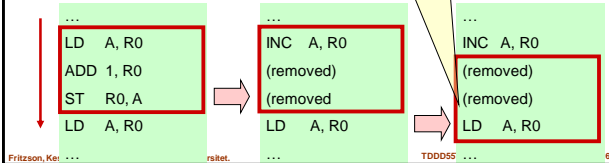


- "postpass" = done after target code generation

### ■ Peephole optimization

- Very simple and limited
- Cleanup after code generation or other transformation
- Use a window of very few consecutive instructions
- Could be done in hardware by superscalar processors...

Cannot remove LD instruction since the peephole context is too small (3 instructions). The INC instruction which also loads A is not visible!



## Postpass Optimizations (2)

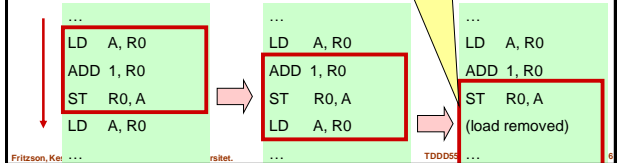


- "postpass" = done after target code generation

### ■ Peephole optimization

- Very simple and limited
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- Could be done in hardware by superscalar processors...

Greedy peephole optimization (as on previous slide) may miss a more profitable alternative optimization (here, removal of a load instruction)



## Postpass Optimizations (2)



### ■ Postpass instruction (re)scheduling

- Reconstruct control flow, data dependences from binary code
- Reorder instructions to improve execution time
- Works even if no source code available
- Can be *retargetable* (parameterized in processor architecture specification)
- E.g., aiPop™ tool by AbsInt GmbH, Saarbrücken