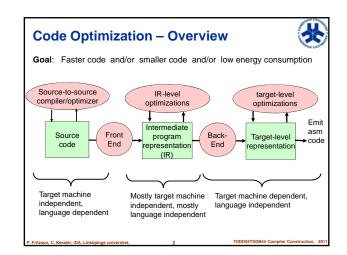
TDDD55 Compiler and Interpreters
TDDB44 Compiler Construction

Code Optimization



Remarks



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- Often multiple levels of IR:
 - high-level IR (e.g. abstract syntax tree AST),
 - medium-level IR (e.g. quadruples, basic block graph),
 - low-level IR (e.g. directed acyclic graphs, DAGs)
 - → do optimization at most appropriate level of abstraction
 - → code generation is continuous lowering of the IR towards target code
- "Postpass optimization": done on binary code (after compilation or without compiling)

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Disadvantages of Compiler Optimizations



- Debugging made difficult
 - Code moves around or disappears
 - Important to be able to switch off optimization
- Increases compilation time
- May even affect program semantics
 - A = B*C D + E \rightarrow A = B*C + E D

may lead to overflow if B*C+E is a too large number

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Optimization at Different Levels of Program Representation



- Source-level optimization
 - Made on the source program (text)
 - Independent of target machine
- Intermediate code optimization
 - Made on the intermediate code (e.g. on AST trees, quadruples)
 - Mostly target machine independent
- Target-level code optimization
 - Made on the target machine code
 - Target machine dependent

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Source-level Optimization



At source code level, independent of target machine

- Replace a slow algorithm with a quicker one, e.g. Bubble sort → Quick sort
- Poor algorithms are the main source of inefficiency but difficult to optimize
- Needs pattern matching, e.g. [K.'96] [di Martino, K. 2000]

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Intermediate Code Optimization



At the intermediate code (e.g., trees, quadruples) level In most cases target machine independent

- Local optimizations within basic blocks (e.g. common subexpression elimination)
- Loop optimizations (e.g. loop interchange to improve data locality)
- Global optimization (e.g. code motion, within procedures)
- Interprocedural optimization (between procedures)

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Target-level Code Optimization



0)

At the target machine binary code level Dependent on the target machine

- Instruction selection, register allocation, instruction scheduling, branch prediction
- Peephole optimization

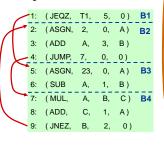
Basic Block



- A basic block is a sequence of textually consecutive operations (e.g. quadruples) that contains no branches (except perhaps its last operation) and no branch targets (except perhaps its first operation).
 - Always executed in same order from entry to exit
 - (JEQZ, T1, • A.k.a. straight-line code 2: (ASGN, 2, 0, A) B2 3: (ADD A, 3, B) 4: (JUMP, 7, 0, 0) 5: (ASGN, 23, 0, A) (SUB (MUL. C) A. B. 8: (ADD, C, 1, A) (JNEZ, В, 0)

Control Flow Graph

- Nodes: primitive operations (e.g. quadruples), or basic blocks.
- Edges: control flow transitions



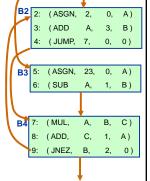
(ASGN, 3: (ADD B) (JUMP, 0, 0) (ASGN, 23, A) 0, 6: (SUB В) 7: (MUL, A, B, C) A) (JNEZ В, 0)

1: (JEQZ,

Basic Block Control Flow Graph

- Nodes: basic blocks
- Edges: control flow transitions





1: (JEQZ, T1,

Local Optimization

(within single Basic Block)

