732A54/TDDE31 Big Data Analytics Lecture 9: Machine Learning with Spark

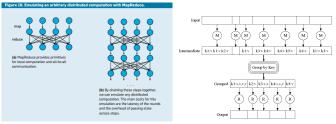
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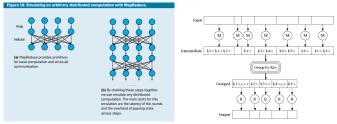
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 - Logistic Regression
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Literature

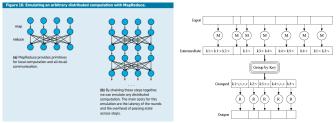
- Main sources
 - Zaharia, M. et al. Resilient Distributed Datasets: A Fault-Tolerant Abstraction for In-Memory Cluster Computing. In Proceedings of the 9th USENIX Symposium on Networked Systems Design and Implementation, 15-28, 2012.
 - Meng, X. et al. MLlib: Machine Learning in Apache Spark. Journal of Machine Learning Research, 17(34):1-7, 2016.
- Additional sources
 - Zaharia, M. et al. Apache Spark: A Unified Engine for Big Data Processing. Communications of the ACM, 59(11):56-65, 2016.
 - Spark programming guide available at https://spark.apache.org/docs/latest/rdd-programming-guide.html
 - MLlib manual available at http://spark.apache.org/docs/latest/ml-guide.html
 - Slides for 732A99/TDDE01 Machine Learning.



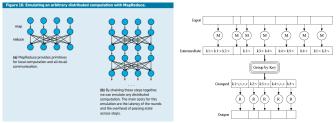
 Recall from the previous lecture that MapReduce can emulate any distributed computation, since this can be divided into a sequence of MapReduce calls.



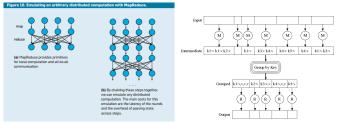
However, the emulation may be inefficient since the message exchange relies on external storage, e.g. disk.



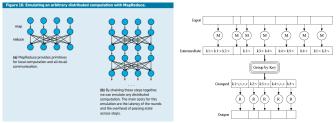
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- Apache Spark is a framework to process large amounts of data by parallelizing computations across a cluster of nodes.



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- This is a problem for iterative machine learning algorithms. Even worse: Each iteration (i.e., MapReduce call) loads the data anew from disk.
- Apache Spark is a framework to process large amounts of data by parallelizing computations across a cluster of nodes.
- It builds on MapReduce's ability to emulate any distributed computation but it makes it more efficiently by emulating in-memory data sharing across MapReduce calls.



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- This is a problem for iterative machine learning algorithms. Even worse: Each iteration (i.e., MapReduce call) loads the data anew from disk.
- Apache Spark is a framework to process large amounts of data by parallelizing computations across a cluster of nodes.
- It builds on MapReduce's ability to emulate any distributed computation but it makes it more efficiently by emulating in-memory data sharing across MapReduce calls.
- It includes MLlib, a library for machine learning that uses linear algebra libraries on each node.

Data sharing is achieved via resilient distributed datasets (RDDs).

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$\begin{tabular}{l l l l l l l l l l l l l l l l l l l $				
Institute of the second sec				$RDD[T] \Rightarrow RDD[U]$
$\label{eq:result} \textbf{Actions} \begin{matrix} \text{is ample}[f_{netcrine}: \text{Fiscal} \): \text{RDD}[\text{T}] \rightarrow \text{RDD}[\text{T}] \ (\text{Deterministic sampling}) \\ group By Key(j : \text{RDD}[(K, V)] \Rightarrow \text{RDD}((K, \text{Seq}[V])) \\ reduce By Key(j : (V, V) \Rightarrow V) : \text{RDD}[(K, V)] \Rightarrow \text{RDD}[(K, \text{Seq}[V])] \\ is (RDD(V, (V, V)] \Rightarrow RDD[(T, V)] \\ join() : ((\text{RDD}[(K, V)]) \Rightarrow \text{RDD}[(T, W)]) \Rightarrow \text{RDD}[(K, (V, W)]) \\ cogroup() : ((\text{RDD}[(K, V)]) \Rightarrow \text{RDD}[(K, (V, W)]) \\ crossProduct() : ((\text{RDD}[T, \text{RDD}[(V]) \Rightarrow \text{RDD}[(T, U)] \\ mapValues(j : V \Rightarrow W) : \text{RDD}[(K, V)] \Rightarrow \text{RDD}[(T, V)] \\ partition By(p : Partitioner[K]) : \text{RDD}[(K, V)] \Rightarrow \text{RDD}[(T, V)] \\ comm(j : \text{RDD}[T] \Rightarrow \text{Long} \\ collect() : \text{RDD}[T] \Rightarrow \text{Long} \\ collect() : \text{RDD}[T] \Rightarrow \text{Cang} \\ lookap(i : K) : \text{RDD}[K, V] \Rightarrow \text{RDD}[V, V] \\ lookap(i : K) : \text{RDD}[K, V] \Rightarrow \text{RDD}[V, V] \\ lookap(i : K) : \text{RDD}[T] = T \\ lookap(i : K) : \text{RDD}[T, V] \Rightarrow \text{Cang}[V] \ (On hash/range partitioned RDDs) \\ \end{matrix}$		$filter(f : T \Rightarrow Bool)$	2	$RDD[T] \Rightarrow RDD[T]$
errougby&cr() ::::::::::::::::::::::::::::::::::::		$flatMap(f : T \Rightarrow Seq[U])$	2	$RDD[T] \Rightarrow RDD[U]$
Transformations reduceByKey(f: (V, V) \Rightarrow V) : RDD[(K, V)] \Rightarrow RDD[(K, V)] \Rightarrow Transformations union() : (RDD[T, RDD[T, N)] \Rightarrow RDD[T, U) $join()$: (RDD[K, V], RDD[T, N)] \Rightarrow RDD[K, (V, W)] \Rightarrow RDD[K, (V, W)] \Rightarrow RDD[K, (V, W)] \Rightarrow RDD[K, (V, W)] \Rightarrow RDD[(K, (Seq[V]), Seq[V]))] $corsuProduce()$: (RDDT[T, RDD[U], RDD[T, D)] $arapidue()$: (RDT, RDD[T, RDD[T], RDD[T], RDD[T], Potentional (K, V)] \Rightarrow RDD[K, V] \Rightarrow RDD[K, V] \Rightarrow Actions $collect()$: RDD[T] \Rightarrow Long $collect()$: RDD[T] \Rightarrow Seq[T] $collect()$: RDD[T] \Rightarrow Seq[T] $collect()$: RDD[T] \Rightarrow Theology (C, T, T) \Rightarrow Theology (F, T) \Rightarrow Seq[V] (On hash/range partitioned RDDs)		sample(fraction : Float)	2	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
		groupByKey()	:	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$		$reduceByKey(f : (V, V) \Rightarrow V)$:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
$\label{eq:constraint} \textbf{Actions} \left(\begin{array}{c} coproup() : (RDD[(X, V)], RDD[(X, W)]) \Rightarrow RDD[(X, (Seq[V]), Seq[W])) \\ crossProduct() : (RDDT[, RDD[(1), PDD[(1, U)] \\ mapNidues(f) : V \Rightarrow W) : RDD[(X, V]) \Rightarrow RDD[(X, V)] \\ sort(c: Coprato(T) : RDD[(X, V)] \Rightarrow RDD[(X, V)] \\ partitionetV(f) : RDDT[(X, V)] \Rightarrow RDD[(X, V)] \\ count() : RDDT[(X, V)] \Rightarrow RDD[(X, V)] \\ count() : RDDT[(X, V)] \Rightarrow RDD[(X, V)] \\ count() : RDDT[(X, V)] \Rightarrow RDD[(X, V)] \\ collect() : RDDT[(X, V)] \Rightarrow RDT[(X, V)] \\ collect() : RDDT[(X, V)] \Rightarrow Seq[(X, V)] \\ collect(V, V) = Coll(X, V) \\ collect(V, V, V) = Seq[(Y, V)] \\ collect(V, V) = Seq[(X, V)] \\ collect(V, V) = Seq[(Y, V)] \\ collect(V, V) \\ collect(V, V) = Seq[(Y, V)] \\ collect(V, V) \\ collect(V, V) = Seq[(Y, V)] \\ collect(V, V) \\ $	Transformations	union()	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
$\label{eq:construction} \begin{array}{llllllllllllllllllllllllllllllllllll$		join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
$\label{eq:second} \begin{array}{c} mapNulue(f: V \Rightarrow W) & : RDD(K, V) = RDD(K, W) (Preserves partitioning) \\ sort(c: Comparate(K)) & : RDD(K, V) = RDD(K, V) \\ partitionBy(p: Partitioner(K)) & : RDD(K, V) = RDD(K, V) \\ count() & : RDD[T] = Long \\ collect() & : RDD[T] = Seq[T] \\ \mbox{Actions} & reduce(f: (T, T) \Rightarrow T) & : RDD[T, V) = Sq[V] (On hash/range partitioned RDDs) \\ \end{array}$		cogroup()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$
$\label{eq:action} \begin{array}{ c c c c c c c c c c c c c c c c c c c$		crossProduct()	:	$(RDD[T], RDD[U]) \Rightarrow RDD[(T, U)]$
$\begin{tabular}{lllllllllllllllllllllllllllllllllll$		$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
$\begin{array}{c} count() : \ \mbox{RDD}[T] \Rightarrow \mbox{Long} \\ collect() : \ \mbox{RDD}[T] \Rightarrow \mbox{Seq}[T] \\ Actions \\ reduce(f: (T, T) \Rightarrow T) : \ \ \mbox{RDD}[T] \Rightarrow T \\ lookup(k: K) : \ \ \mbox{RDD}(K, V] \Rightarrow \mbox{Seq}[V] \ (On hash/range partitioned RDDs) \\ \end{array}$		sort(c:Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Actions $reduce(f : (T, T) \Rightarrow T)$: RDD[T] \Rightarrow Seq[T] $reduce(f : (T, T) \Rightarrow T)$: RDD[T] \Rightarrow T $lookap(i : K)$: RDD(K, V)] \Rightarrow Seq[V] (On hash/range partitioned RDDs)		partitionBy(p:Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Actions $reduce(f : (T, T) \Rightarrow T)$: RDD[T] $\Rightarrow T$ $lookup(k : K)$: RDD[(K, V)] \Rightarrow Seq[V] (On hash/range partitioned RDDs)		count() :	1	$RDD[T] \Rightarrow Long$
$lookup(k: K)$: RDD[(K, V)] \Rightarrow Seq[V] (On hash/range partitioned RDDs)		collect() :	1	$RDD[T] \Rightarrow Seq[T]$
	Actions	$reduce(f : (T,T) \Rightarrow T)$:	1	$RDD[T] \Rightarrow T$
save(path : String) : Outputs RDD to a storage system, e.g., HDFS		lookup(k: K):	1	$RDD[(K, V)] \Rightarrow Seq[V]$ (On hash/range partitioned RDDs)
		save(path : String) :		Outputs RDD to a storage system, e.g., HDFS

			$RDD[T] \Rightarrow RDD[U]$	
	$filter(f : T \Rightarrow Bool)$:	:	$RDD[T] \Rightarrow RDD[T]$	
	$flatMap(f : T \Rightarrow Seq[U])$:	:	$RDD[T] \Rightarrow RDD[U]$	
	sample(fraction : Float) :	:	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)	
	groupByKey() :	:	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$	
	$reduceByKey(f : (V, V) \Rightarrow V)$:	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$	
Transformations	union() :	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$	
	<i>join</i> () :	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$	
	cogroup() :	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$	
	crossProduct() :	:	$(RDD[T], RDD[U]) \Rightarrow RDD[(T, U)]$	
	$mapValues(f : V \Rightarrow W)$:	:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)	
	sort(c:Comparator[K]) :	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$	
	partitionBy(p: Partitioner[K]) :	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$	
	count() :	1	$RDD[T] \Rightarrow Long$	-
	collect() :	1	$RDD[T] \Rightarrow Seq[T]$	
Actions	$reduce(f : (T,T) \Rightarrow T)$:	1	$RDD[T] \Rightarrow T$	
	lookup(k: K):	1	$RDD[(K, V)] \Rightarrow Seq[V]$ (On hash/range partitioned RDDs)	
	save(path : String) :	(Outputs RDD to a storage system, e.g., HDFS	

- Note that some transformations and actions do not require RDDs of (key, value) pairs, i.e. so-called pair RDDs.
- Note also that the transformations and actions for non-pair RDDs work on pair RDDs too.

- Data sharing is achieved via resilient distributed datasets (RDDs).
- RDD is a read-only, partitioned collection of records that can only be defined through transformations applied to external storage or to other RDDs.

			$RDD[T] \Rightarrow RDD[U]$
	$filter(f : T \Rightarrow Bool)$	2	$RDD[T] \Rightarrow RDD[T]$
	$flatMap(f : T \Rightarrow Seq[U])$		
	sample(fraction : Float)	2	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
	groupByKey()	:	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
	$reduceByKey(f : (V, V) \Rightarrow V)$	5	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Transformations	union()	5	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
	join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
	cogroup()	\$	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$
	crossProduct()	:	$(RDD[T], RDD[U]) \Rightarrow RDD[(T, U)]$
	$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
	sort(c:Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	partitionBy(p:Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	count() :		$RDD[T] \Rightarrow Long$
	collect() :		$RDD[T] \Rightarrow Seq[T]$
Actions	$reduce(f : (T,T) \Rightarrow T)$:		$RDD[T] \Rightarrow T$
	lookup(k : K) :		$RDD[(K, V)] \Rightarrow Seq[V]$ (On hash/range partitioned RDDs)
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	$flatMap(f : T \Rightarrow Seq[U])$	2	$RDD[T] \Rightarrow RDD[U]$
	sample(fraction : Float)	2	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
	groupByKey()	2	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
	$reduceByKey(f : (V, V) \Rightarrow V)$:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Transformations	union()	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
	join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
	cogroup()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$
	crossProduct()	:	$(RDD[T], RDD[U]) \Rightarrow RDD[(T, U)]$
	$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
	sort(c:Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	partitionBy(p:Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	count() :	1	$RDD[T] \Rightarrow Long$
	collect() :	1	$RDD[T] \Rightarrow Seq[T]$
Actions	$reduce(f : (T,T) \Rightarrow T)$:	1	$RDD[T] \Rightarrow T$
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	save(path : String) :		Outputs RDD to a storage system, e.g., HDFS

Table 2: Transformations and actions available on RDDs in Spark. Seq[T] denotes a sequence of elements of type T.

The sequence of transformations that defines a RDD is called its lineage. It is used to rebuild it in case of failure, i.e. there is no data replication unlike in MapReduce.

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- RDD is a read-only, partitioned collection of records that can only be defined through transformations applied to external storage or to other RDDs.

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	$filter(f : T \Rightarrow Bool)$	2	$RDD[T] \Rightarrow RDD[T]$
	$flatMap(f : T \Rightarrow Seq[U])$	2	$RDD[T] \Rightarrow RDD[U]$
	sample(fraction : Float)	2	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
	groupByKey()	2	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
	$reduceByKey(f : (V, V) \Rightarrow V)$:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Transformations	union()	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
	join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
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	$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
	sort(c:Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	partitionBy(p:Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	count() :	1	$RDD[T] \Rightarrow Long$
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Actions	$reduce(f : (T,T) \Rightarrow T)$:	1	$RDD[T] \Rightarrow T$
	lookup(k: K):	1	$RDD[(K, V)] \Rightarrow Seq[V]$ (On hash/range partitioned RDDs)
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- RDDs are created only when an action is executed. Why ? E.g., [read + filter] more memory efficient than [read, filter].

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	sample(fraction : Float)	2	$RDD[T] \Rightarrow RDD[T]$ (Deterministic sampling)
	groupByKey()	2	$RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
	$reduceByKey(f : (V, V) \Rightarrow V)$:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Transformations	union()	:	$(RDD[T], RDD[T]) \Rightarrow RDD[T]$
	join()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (V, W))]$
	cogroup()	:	$(RDD[(K, V)], RDD[(K, W)]) \Rightarrow RDD[(K, (Seq[V], Seq[W]))]$
	crossProduct()	:	$(RDD[T], RDD[U]) \Rightarrow RDD[(T, U)]$
	$mapValues(f : V \Rightarrow W)$:	$RDD[(K, V)] \Rightarrow RDD[(K, W)]$ (Preserves partitioning)
	sort(c:Comparator[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	partitionBy(p:Partitioner[K])	:	$RDD[(K, V)] \Rightarrow RDD[(K, V)]$
	count() :	1	$RDD[T] \Rightarrow Long$
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Actions	$reduce(f : (T,T) \Rightarrow T)$:	1	$RDD[T] \Rightarrow T$
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- Actually, RDDs are created each time an action is executed, unless the user persist them in memory and/or disk.

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- RDD is a read-only, partitioned collection of records that can only be defined through transformations applied to external storage or to other RDDs.

		: $RDD[T] \Rightarrow RDD[U]$
	$filter(f : T \Rightarrow Bool)$:	: $RDD[T] \Rightarrow RDD[T]$
	$flatMap(f : T \Rightarrow Seq[U])$:	: $RDD[T] \Rightarrow RDD[U]$
	sample(fraction : Float) :	: RDD[T] ⇒ RDD[T] (Deterministic sampling)
	groupByKey() :	: $RDD[(K, V)] \Rightarrow RDD[(K, Seq[V])]$
	$reduceByKey(f : (V, V) \Rightarrow V)$:	: $RDD[(K, V)] \Rightarrow RDD[(K, V)]$
Transformations	union() :	: $(RDD[T], RDD[T]) \Rightarrow RDD[T]$
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- The sequence of transformations that defines a RDD is called its lineage. It is used to rebuild it in case of failure, i.e. there is no data replication unlike in MapReduce.
- RDDs are created only when an action is executed. Why ? E.g., [read + filter] more memory efficient than [read, filter].
- Actually, RDDs are created each time an action is executed, unless the user persist them in memory and/or disk.
- Actions write to disk or return values to the master/driver.

Example in Scala to find error lines in a log file:

1.lines=spark.textFile("hdfs://...")

2.errors=lines.filter(_.startsWith("ERROR"))

3.errors.persist() //Store in memory

4.errors.count() //Materialize

5.errors.filter(_.contains("HDFS")).map(_.split('\t')(3)).collect()

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```
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```
4.errors.count() //Materialize
```

```
5.errors.filter(_.contains("HDFS")).map(_.split('\t')(3)).collect()
```

- Note that:
 - Line 3 indicates to store the error lines in memory. Note persist() =
 persist(MEMORY_ONLY) = cache() ≠ persist(MEMORY_AND_DISK) ≠...
 - However, this does not happen until line 4, when the RDDs are computed.

Example in Scala to find error lines in a log file:

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1.lines=spark.textFile("hdfs://...")
```

```
2.errors=lines.filter(_.startsWith("ERROR"))
```

```
3.errors.persist() //Store in memory
```

```
4.errors.count() //Materialize
```

```
5.errors.filter(_.contains("HDFS")).map(_.split('\t')(3)).collect()
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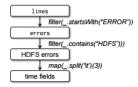
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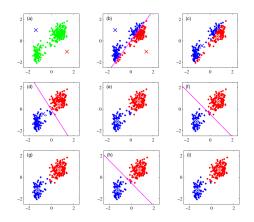
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 - The rest of the RDDs (e.g., lines) are discarded after being used.
 - Line 5 does not access disk because the data are in memory.
 - If any partition of the in-memory data has gone lost, it can be rebuilt with the help of the lineage graph.



Machine Learning with Spark: K-Means

- Consider data clustering (a.k.a. unsupervised learning) via the K-means algorithm.
 - 1 Assign each point to a cluster (a.k.a. subpopulation) at random
 - 2 Compute the cluster centroids as the averages of the points assigned to each cluster
 - 3 Repeat until the centroids do not change
 - 4 Assign each point to the cluster with the closest centroid
 - 5 Update the cluster centroids as the averages of the points assigned to each cluster



Machine Learning with Spark: K-Means

K-Means in Python (data has been persisted when read from file):

```
def closestPoint(p, centers);
    bestIndex = 0
    closest = float("+inf")
    for i in range(len(centers)):
        tempDist = np.sum((p - centers[i]) ** 2)
        if tempDist < closest:</pre>
            closest = tempDist
            bestIndex = i
    return bestIndex
kPoints = data.takeSample(False, K, 1)
tempDist = 1.0
while tempDist > convergeDist:
    closest = data.map(
        lambda p: (closestPoint(p, kPoints), (p, 1)))
    pointStats = closest.reduceBvKev(
        lambda p1 c1, p2 c2: (p1 c1[0] + p2 c2[0], p1 c1[1] + p2 c2[1]))
    newPoints = pointStats.map(
        lambda st: (st[0], st[1][0] / st[1][1])).collect()
    tempDist = sum(np.sum((kPoints[iK] - p) ** 2) for (iK, p) in newPoints)
    for (iK, p) in newPoints:
        kPoints[iK] = p
print("Final centers: " + str(kPoints))
```

• Consider a binary classification problem, i.e. $t \in \{-1, +1\}$. Then,

$$p(t = +1|\mathbf{x}) = \frac{p(\mathbf{x}|t = +1)p(t = +1)}{p(\mathbf{x}|t = +1)p(t = +1) + p(\mathbf{x}|t = -1)p(t = -1)} = \sigma(s(\mathbf{x}))$$

where $s(\mathbf{x}) = \log \frac{p(\mathbf{x}|t=+1)p(t=+1)}{p(\mathbf{x}|t=-1)p(t=-1)}$, and $\sigma(\mathbf{a}) = \frac{1}{1+exp(-\mathbf{a})}$ is called logistic sigmoid function.

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• We assume that $p(\mathbf{x}|t)$ is a member of the exponential family with equal scale parameter (e.g. Gaussian with equal covariance matrix, multinomial), which implies that $s(\mathbf{x}) = \mathbf{w}^T \mathbf{x}$. The model $y(\mathbf{x}) = p(t = +1|\mathbf{x}) = \sigma(\mathbf{w}^T \mathbf{x})$ is called logistic regression.

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- We assume that p(x|t) is a member of the exponential family with equal scale parameter (e.g. Gaussian with equal covariance matrix, multinomial), which implies that s(x) = w^Tx. The model y(x) = p(t = +1|x) = σ(w^Tx) is called logistic regression.
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• We determine the parameters **w** by minimizing the negative log-likelihood: $l(\mathbf{w}) = \sum_{i=1}^{n} \log_{\mathbf{r}}(t_{i} | \mathbf{x}_{i}) = \sum_{i=1}^{n} \log_{\mathbf{r}}(t_{i} + \exp(-t_{i} \mathbf{w}^{T} \mathbf{x}_{i}))$

$$L(\boldsymbol{w}) = -\sum_{n} \log p(t_n | \boldsymbol{x}_n) = \sum_{n} \log(1 + \exp(-t_n \boldsymbol{w}' \boldsymbol{x}_n))$$

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$$L(\boldsymbol{w}) = -\sum_{n} \log p(t_n | \boldsymbol{x}_n) = \sum_{n} \log(1 + \exp(-t_n \boldsymbol{w}^T \boldsymbol{x}_n))$$

whose gradient is $-\sum_n t_n (1 - 1/(1 + \exp(-t_n \boldsymbol{w}^T \boldsymbol{x}_n))) \boldsymbol{x}_n$.

Logistic regression in Scala (note the use of persist, map and reduce):

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Logistic regression in Python (points was persisted when read from file):

```
# Initialize w to a random value
w = 2 * np.random.ranf(size=D) - 1
print("Initial w: " + str(w))
# Compute logistic regression gradient for a matrix of data points
def gradient(matrix, w):
    Y = matrix[:, 0]  # point labels (first column of input file)
   X = matrix[:, 1:] # point coordinates
    # For each point (x, y), compute gradient function, then sum these up
    return ((1.0 / (1.0 + np.exp(-Y * X.dot(w))) - 1.0) * Y * X.T).sum(1)
def add(x, v):
    x += y
    return x
for i in range(iterations):
    print("On iteration %i" % (i + 1))
   w -= points.map(lambda m; gradient(m, w)).reduce(add)
print("Final w: " + str(w))
```

Machine Learning with Spark: MLlib

- Many machine learning methods are already implemented in MLlib, i.e. the user does not need to specify the transformations and actions.
- SVMs in Python: model = SVMWithSGD.train(parsedData, iterations=100)
- NNs in Python:

```
layers = [4, 5, 4, 3]
trainer = MultilayerPerceptronClassifier(maxIter=100, layers=layers,
blockSize=128, seed=1234)
model = trainer.fit(train)
```

MMs in Python:

```
gmm = GaussianMixture().setK(2)
model = gmm.fit(dataset)
```

• *K*-Means in Python:

kmeans = KMeans().setK(2).setSeed(1)

```
model = kmeans.fit(dataset)
```

Machine Learning with Spark: Experiments

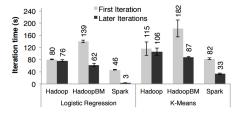


Figure 7: Duration of the first and later iterations in Hadoop, HadoopBinMem and Spark for logistic regression and k-means using 100 GB of data on a 100-node cluster.

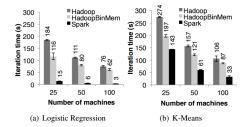


Figure 8: Running times for iterations after the first in Hadoop, HadoopBinMem, and Spark. The jobs all processed 100 GB.

- Implement a kernel model to predict the hourly temperatures for a date and place in Sweden. To do so, you are provided with the files stations.csv and temps.csv. These files contain information about weather stations and temperature measurements for the stations at different days and times. The data have been kindly provided by the Swedish Meteorological and Hydrological Institute (SMHI) and processed by Zlatan Dragisic.
- You are asked to provide a temperature forecast for a date and place in Sweden. The forecast should consist of the predicted temperatures from 4 am to 24 pm in an interval of 2 hours. Use a kernel that is the sum of three Gaussian kernels:
 - The first to account for the distance from a station to the point of interest.
 - The second to account for the distance between the day a temperature measurement was made and the day of interest.
 - The third to account for the distance between the hour of the day a temperature measurement was made and the hour of interest.
- Repeat the exercise about multiplying instead of summing the three kernels above.

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$$y(\mathbf{x}) = \frac{\sum_{n} k\left(\frac{\mathbf{x}-\mathbf{x}_{n}}{h}\right) y_{n}}{\sum_{n} k\left(\frac{\mathbf{x}-\mathbf{x}_{n}}{h}\right)}$$

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where $k : \mathbb{R}^{D} \to \mathbb{R}$ is a kernel function, which is usually non-negative and monotone decreasing along rays starting from the origin. The parameter h is called smoothing factor or width.

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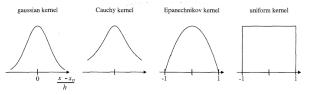
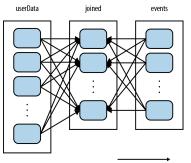


FIGURE 10.3. Various kernels on R.

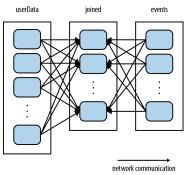
• Gaussian kernel: $k(u) = exp(-||u||^2)$ where $||\cdot||$ is the Euclidean norm.

 Bear in mind that a join operation may trigger a shuffle operation, which is time and memory consuming.



network communication

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Instead, broadcast one of the RDDs to join, if small. This sends a copy of the RDD to each node, and the join can be performed locally (or even skipped).

```
rdd = rdd.collectAsMap()
bc = sc.broadcast(rdd)
bc.value[i]
```

Summary

- Spark is a framework to process large datasets by parallelizing computations.
- It is particularly suitable for iterative distributed computations, since data can be store in memory.
- It includes MLlib, a machine learning library.