

The Team Description of Osaka University “Trackies-99”

Trackies

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Abstract. *This is the team description of Osaka University “Trackies” for RoboCup-99. We have worked two issues for our new team. First, we have changed our robot system from a remote controlled vehicle to a self-contained robot. The other, we have proposed a new learning method based on a Q-learning method so that a real robot can acquire a behavior by reinforcement learning.*