

A Transpositional Redundant Data Update Algorithm for Growing Server-less Video Streaming Systems



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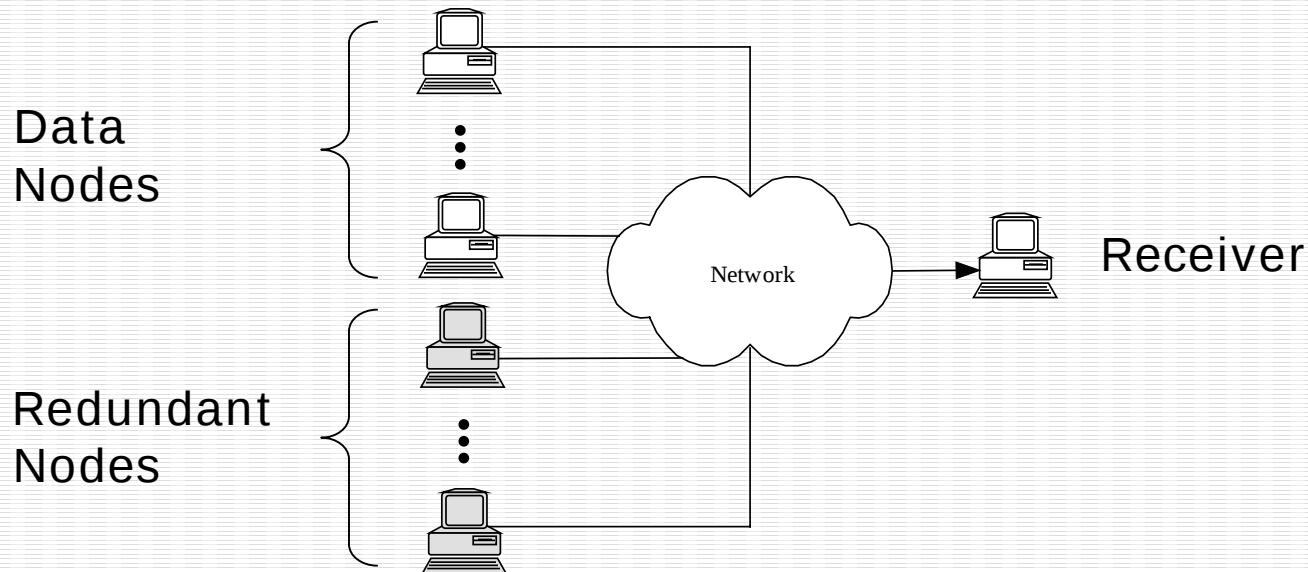
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Outline

- Background
- Previous Works
- Transpositional Redundant Data Update (TRDU)
- Multiple Redundant Nodes
- Performance Evaluation
- Conclusion and Future Works

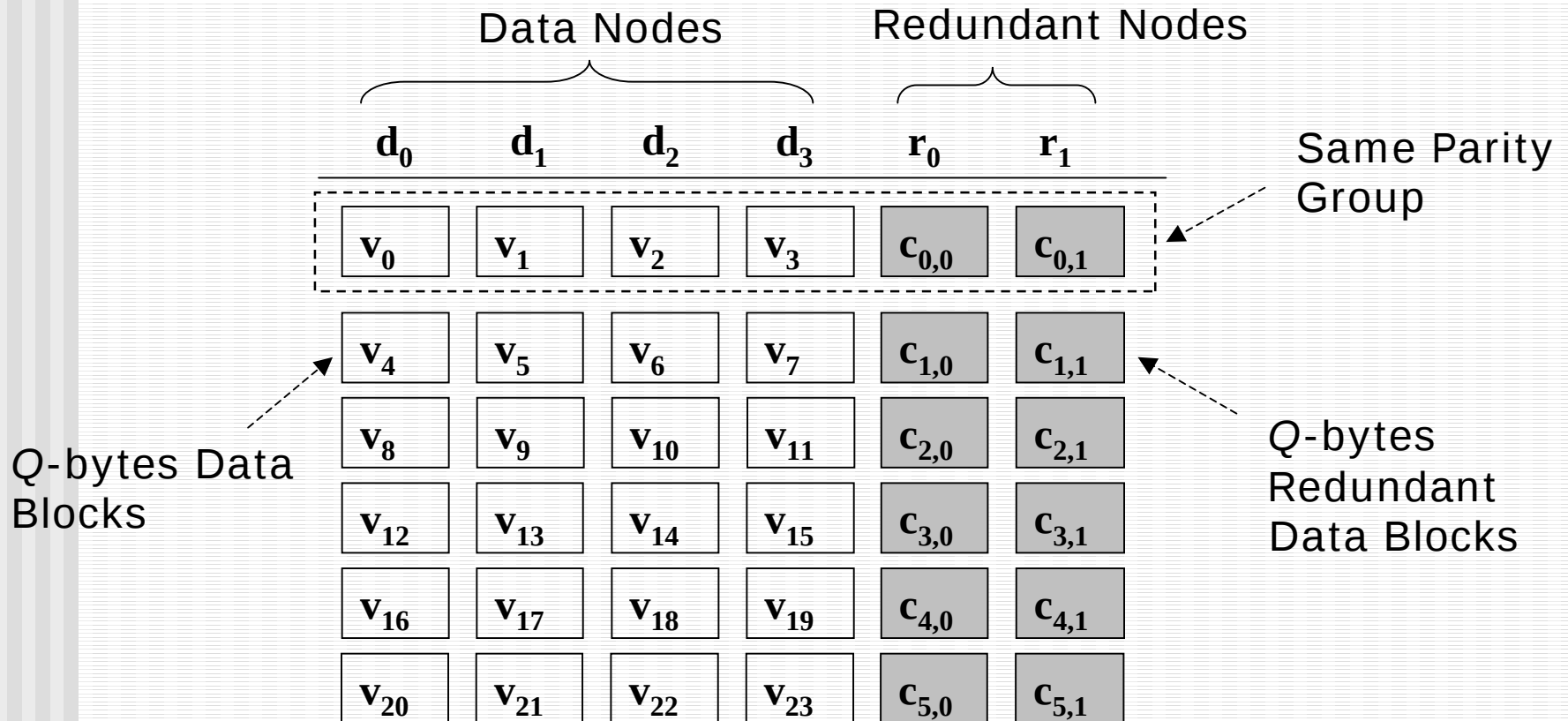
Background

- Server-less Video Streaming Systems[1]
 - Pool of user hosts, or call nodes
 - Each node acts as both sender and receiver
 - Data redundancy to achieve reliability



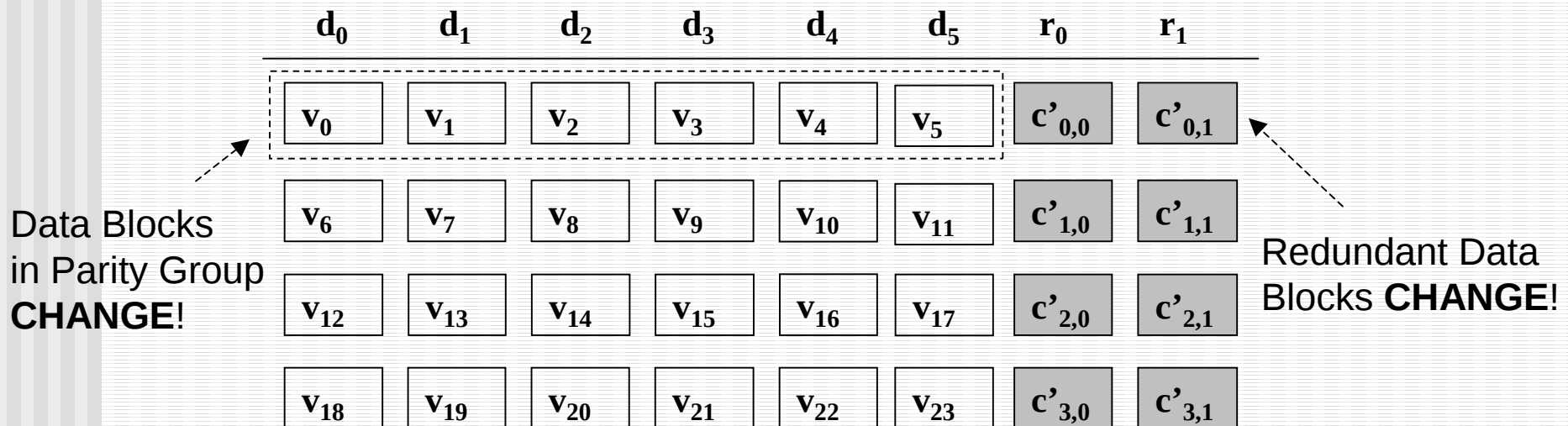
Background

■ Data Placement Policy



Background

- New nodes join the system
- Video data blocks are reorganized to utilize their storage and streaming capacity
- Video data blocks in the parity group change
- Redundant data blocks need updating
- Transmitting video data blocks to redundant nodes

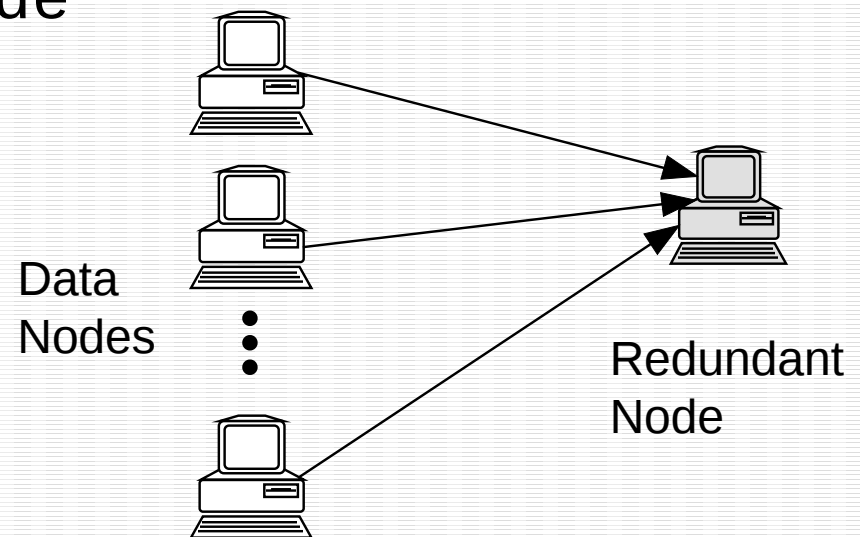


Previous Works

■ Redundant Data Regeneration

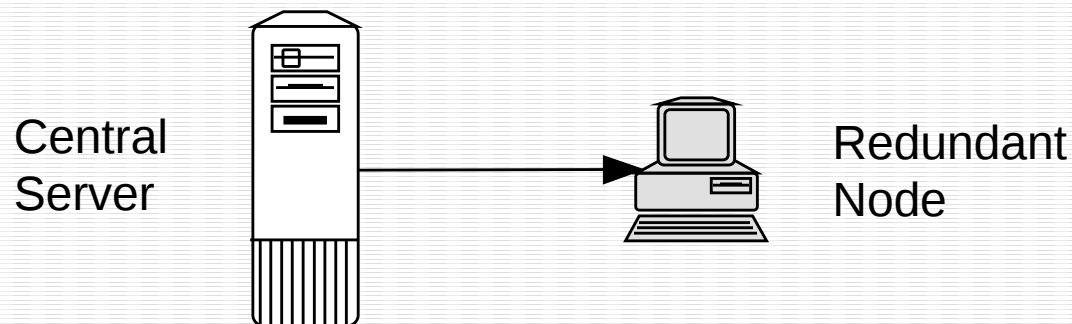
■ Data blocks are fully distributed

- Transmit all data blocks to redundant node
- Compute the new redundant data in redundant node
- Overhead is too high



Previous Works

- Redundant Data Regeneration
 - All data blocks stored in central server
 - Regenerate new redundant data in server
 - Transmit them to redundant node
 - Overhead is low
 - Costly for server, not desirable/ feasible



Previous Works

- Sequential Redundant Data Update (SRDU)
 - Old redundant blocks contain valuable information
 - Possible to reuse for linear code, e.g. RSE code
 - Vandermonde matrix
 - Number of nodes, N
 - Number of redundant nodes, h
 - Element at row i , column $j = j^{i-1}$

$$\begin{array}{c} \text{Redundant block} \\ \text{in redundant} \\ \text{node 0} \end{array} \begin{bmatrix} c_{i,0} \\ c_{i,1} \\ \vdots \\ c_{i,h-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & 2 & 3 & \dots & N-h \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & 2^{h-1} & 3^{h-1} & \dots & (N-h)^{h-1} \end{bmatrix} \begin{bmatrix} d_{i,0} \\ d_{i,1} \\ \vdots \\ d_{i,N-h-1} \end{bmatrix} \begin{array}{c} \text{block from} \\ \text{data node 0} \end{array}$$

Previous Works

■ Updating parity group 0

■ Before addition of nodes

d_0	d_1	d_2	d_3	r_0	r_1
v_0	v_1	v_2	v_3	$c_{0,0}$	$c_{0,1}$

$$c_{0,1} = 1*v_0 + 2*v_1 + 3*v_2 + 4*v_3$$

■ After addition of two nodes

d_0	d_1	d_2	d_3	d_4	d_5	r_0	r_1
v_0	v_1	v_2	v_3	v_4	v_5	$c'_{0,0}$	$c'_{0,1}$

$$c'_{0,1} = c_{0,1} + 5*v_4 + 6*v_5$$

$$\begin{bmatrix} c_{0,0} \\ c_{0,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \end{bmatrix}$$

$$\begin{bmatrix} c'_{0,0} \\ c'_{0,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \end{bmatrix}$$

Only need to send v_4, v_5

Previous Works

■ Updating parity group 1

■ Before addition of nodes

d_0	d_1	d_2	d_3	r_0	r_1
v_8	v_9	v_{10}	v_{11}	$c_{2,0}$	$c_{2,1}$

$$\begin{bmatrix} c_{2,0} \\ c_{2,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 \end{bmatrix} \begin{bmatrix} v_8 \\ v_9 \\ v_{10} \\ v_{11} \end{bmatrix}$$

$$c_{2,1} = 1*v_8 + 2*v_9 + 3*v_{10} + 4*v_{11}$$

■ After addition of two nodes

d_0	d_1	d_2	d_3	d_4	d_5	r_0	r_1
v_6	v_7	v_8	v_9	v_{10}	v_{11}	$c'_{1,0}$	$c'_{1,1}$

$$\begin{bmatrix} c'_{1,0} \\ c'_{1,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} v_8 \\ v_9 \\ v_{10} \\ v_{11} \\ v_6 \\ v_7 \end{bmatrix}$$

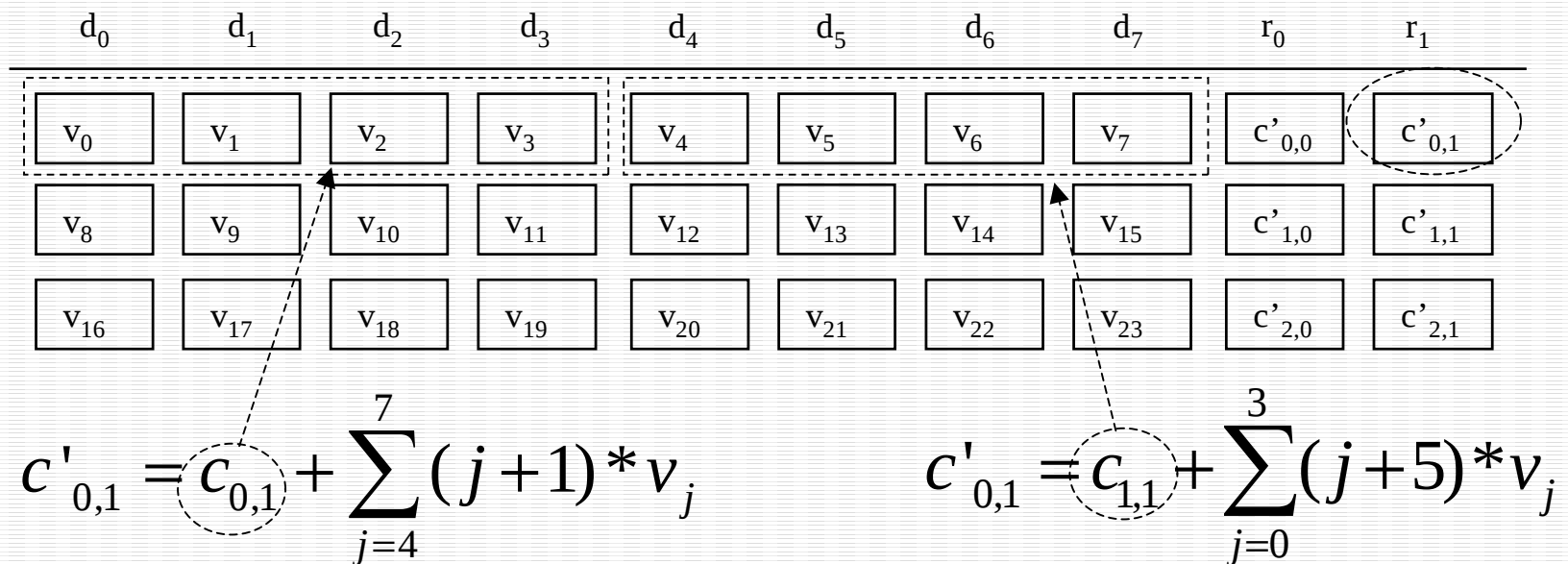
$$c'_{1,1} = c_{2,1} + 5*v_6 + 6*v_7$$

Only need to send v_6, v_7

Previous Works

■ Problem in SRDU

- Reusing of old redundant block is limited
- $c'_{0,1}$ can only be in term of one of $c_{0,1}$ and $c_{1,1}$
- Both $c_{0,1}$ and $c_{1,1}$ are constructed by multiplying 1 to 4 with the data blocks



Transpositional Redundant Data Update

- Compute redundant block using transposed coefficients
- Vandermonde matrix
 - $(N_{\max}-h)$ columns
 - $N_{\max}$ is max system size, irrespective of current size N

$$\begin{bmatrix} c_{i,0} \\ c_{i,1} \\ \vdots \\ c_{i,h-1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & \dots & 1 \\ 1 & 2 & 3 & \dots & N_{\max} - h \\ \vdots & \vdots & \vdots & & \vdots \\ 1 & 2^{h-1} & 3^{h-1} & \dots & (N_{\max} - h)^{h-1} \end{bmatrix} \begin{bmatrix} d_{i,0} \\ d_{i,1} \\ \vdots \\ d_{i,N_{\max}-h-1} \end{bmatrix}$$

Transpositional Redundant Data Update

- For parity group i , the starting position is shifted by $(i(N-h) \bmod (N_{max}-h))$
- All other elements are zeroed
- Example
 - Let $(N_{max}-h)$ be 10
 - Parity group 0

d_0	d_1	d_2	d_3	r_0	r_1
v_0	v_1	v_2	v_3	$c_{0,0}$	$c_{0,1}$
v_4	v_5	v_6	v_7	$c_{1,0}$	$c_{1,1}$
v_8	v_9	v_{10}	v_{11}	$c_{2,0}$	$c_{2,1}$

$$\begin{bmatrix} c_{0,0} \\ c_{0,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & \dots & 1 \\ 1 & 2 & 3 & 4 & 5 & \dots & 10 \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

$$c_{0,1} = 1*v_0 + 2*v_1 + 3*v_2 + 4*v_3$$

Transpositional Redundant Data Update

■ Parity group 1 and 2

d_0	d_1	d_2	d_3	r_0	r_1
v_0	v_1	v_2	v_3	$c_{0,0}$	$c_{0,1}$
v_4	v_5	v_6	v_7	$c_{1,0}$	$c_{1,1}$
v_8	v_9	v_{10}	v_{11}	$c_{2,0}$	$c_{2,1}$

$$c_{1,1} = 5*v_4 + 6*v_5 + 7*v_6 + 8*v_7$$

$$c_{2,1} = 9*v_8 + 10*v_9 + 1*v_{10} + 2*v_{11}$$

- Repeat coefficient in $c_{2,1}$
- Max size of 10 prevents v_0 and v_{10} in residing in the same parity group

$$\begin{bmatrix} 0 \\ 0 \\ 0 \\ 0 \\ v_4 \\ \vdots \\ v_7 \\ 0 \\ 0 \end{bmatrix}$$

$$\begin{bmatrix} v_{10} \\ v_{11} \\ 0 \\ \vdots \\ 0 \\ v_8 \\ v_9 \end{bmatrix}$$

Transpositional Redundant Data Update

■ Two nodes are added

■ Updating parity group 0

d_0	d_1	d_2	d_3	d_4	d_5	r_0	r_1
v_0	v_1	v_2	v_3	v_4	v_5	$c'_{0,0}$	$c'_{0,1}$
v_6	v_7	v_8	v_9	v_{10}	v_{11}	$c'_{1,0}$	$c'_{1,1}$

$$\begin{aligned}
 c'_{0,1} &= 1*v_0 + 2*v_1 + 3*v_2 + 4*v_3 + 5*v_4 + 6*v_5 \\
 &= c_{0,1} + 5*v_4 + 6*v_5
 \end{aligned}$$

$$\begin{bmatrix} c'_{0,0} \\ c'_{0,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & \dots & 1 \\ 1 & 2 & 3 & 4 & 5 & \dots & 10 \end{bmatrix} \begin{bmatrix} v_0 \\ v_1 \\ v_2 \\ v_3 \\ v_4 \\ v_5 \\ 0 \\ \vdots \\ 0 \end{bmatrix}$$

Need to send v_4, v_5

Transpositional Redundant Data Update

■ Updating parity group 1

d_0	d_1	d_2	d_3	d_4	d_5	r_0	r_1
v_0	v_1	v_2	v_3	v_4	v_5	$c'_{0,0}$	$c'_{0,1}$
v_6	v_7	v_8	v_9	v_{10}	v_{11}	$c'_{1,0}$	$c'_{1,1}$

$$\begin{bmatrix} c'_{1,0} \\ c'_{1,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & \dots & 1 \\ 1 & 2 & 3 & 4 & 5 & \dots & 10 \end{bmatrix} \begin{bmatrix} v_{10} \\ v_{11} \\ 0 \\ \vdots \\ 0 \\ v_6 \\ v_7 \\ v_8 \\ v_9 \end{bmatrix}$$

$$c'_{1,1} = (7*v_6 + 8*v_7) + (9*v_8 + 10*v_9 + 1*v_{10} + 2*v_{11})$$

$$= (c_{1,1} - 5*v_4 - 6*v_5) + c_{2,1}$$

Cached in previous update

No need to send

- This equation is not allowed in SRDU, as v_6 shares the same coefficient with v_{10}

Transpositional Redundant Data Update

- In SRDU

- Before addition of nodes

$$c_{1,1} = 1*v_4 + 2*v_5 + 3*v_6 + 4*v_7$$

$$c_{2,1} = 1*v_8 + 2*v_9 + 3*v_{10} + 4*v_{11}$$

- After addition of two nodes

$$\begin{bmatrix} c'_{1,0} \\ c'_{1,1} \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1 & 1 & 1 \\ 1 & 2 & 3 & 4 & 5 & 6 \end{bmatrix} \begin{bmatrix} v_8 \\ v_9 \\ v_{10} \\ v_{11} \\ v_6 \\ v_7 \end{bmatrix}$$

$$\begin{aligned} c'_{1,1} &= (1*v_8 + 2*v_9 + 3*v_{10} + 4*v_{11}) + (5*v_6 + 6*v_7) \\ &= c_{2,1} + 5*v_6 + 6*v_7 \end{aligned}$$

Transpositional Redundant Data Update

- Zero overhead point
 - Number of additional nodes equals integral multiples of original system size

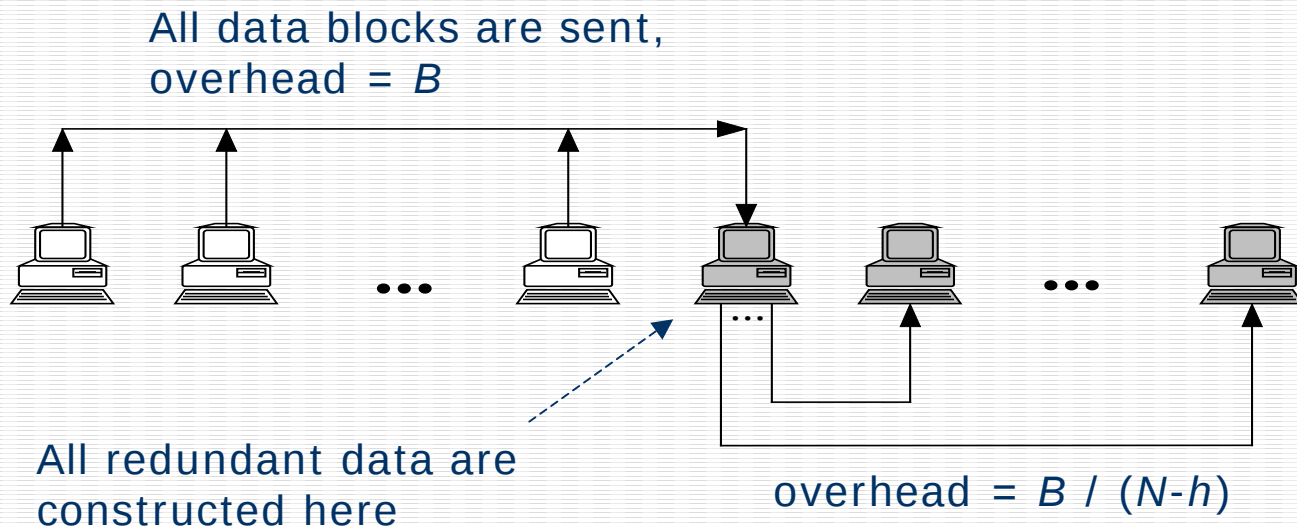
d_0	d_1	d_2	d_3	d_4	d_5	d_6	d_7	r_0	r_1
v_0	v_1	v_2	v_3	v_4	v_5	v_6	v_7	$c'_{0,0}$	$c'_{0,1}$

$$c'_{0,1} = c_{0,1} + c_{1,1}$$

- Tradeoffs
 - Specify the max system size N_{max}
 - Larger Vandermonde matrix increases the computational complexity in decoding

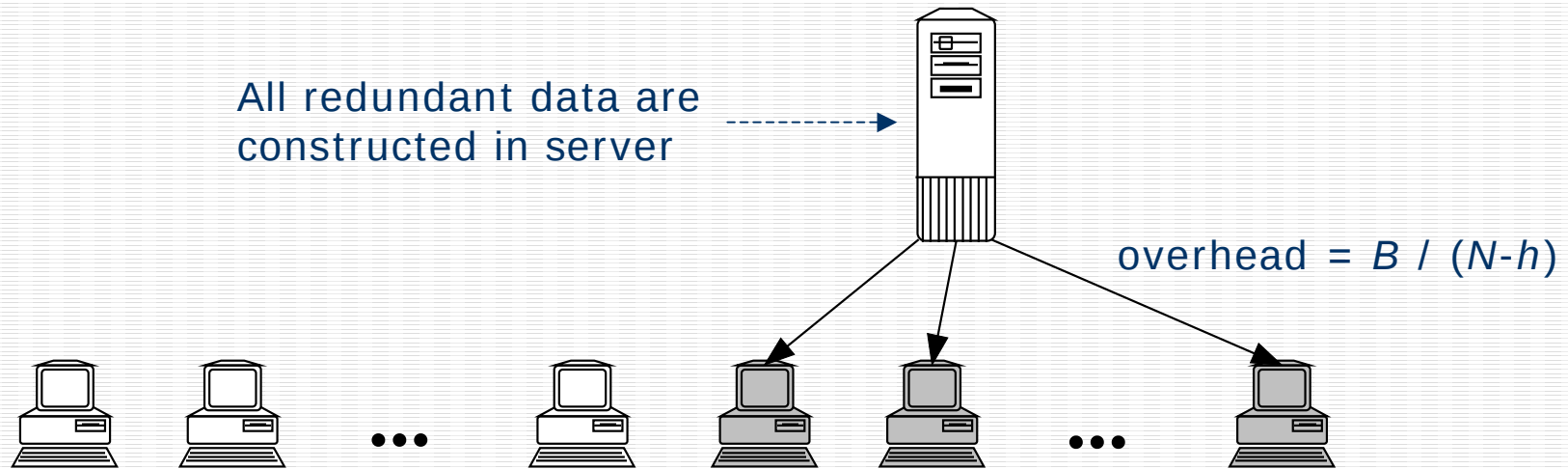
Multiple Redundant Nodes

- Total number of data blocks, B
- Redundant Data Regeneration
 - Fully distributed data blocks
 - Total overhead = $B + (h-1)(B/(N-h))$



Multiple Redundant Nodes

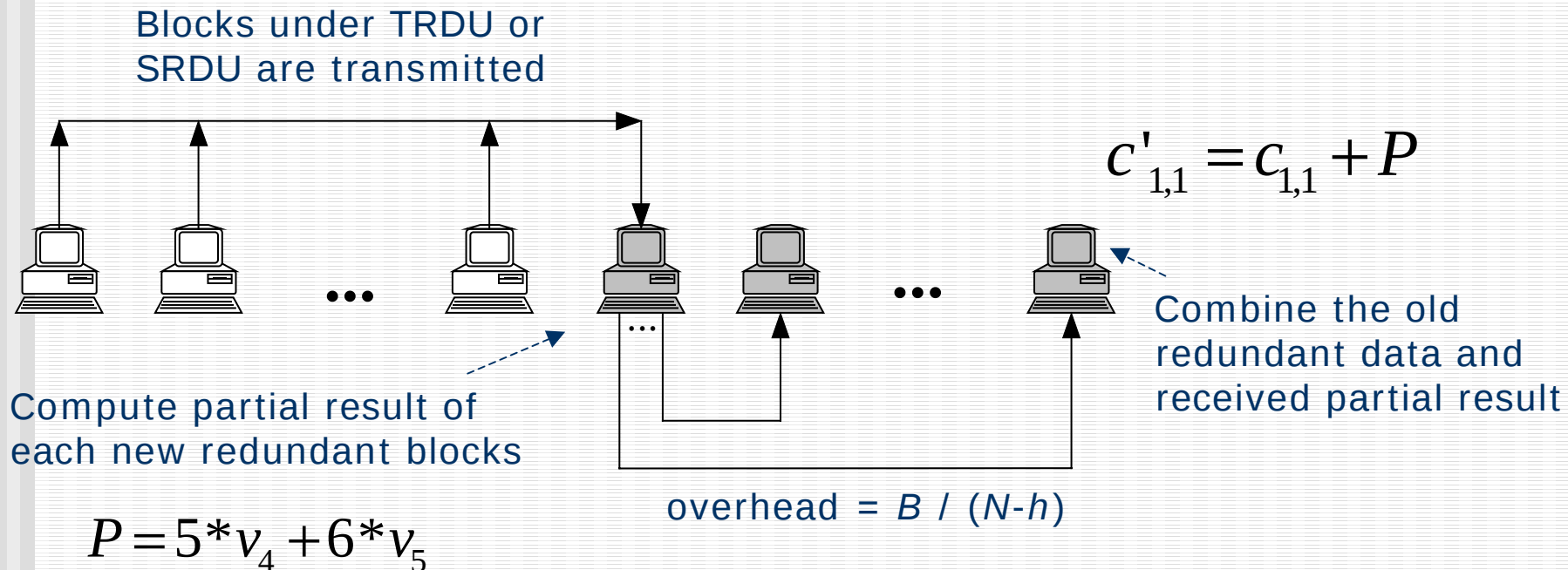
- Data blocks are stored in central server
 - Total overhead = $h * B / (N-h)$



Multiple Redundant Nodes

■ SRDU/TRDU

- Total overhead = blocks under SRDU/TRDU + $(h-1)(B/(N-h))$



Multiple Redundant Nodes

Redundant Data Regeneration	$B + (h-1)(B/(N-h))$
Regeneration by archive server	$B/(N-h) +$ $(h-1)(B/(N-h))$
Sequential Redundant Data Update (SRDU)	Block movement under SRDU + $(h-1)(B/(N-h))$
Transpositional Redundant Data Update (TRDU)	Block movement under TRDU + $(h-1)(B/(N-h))$

- Overhead is dominated by updating the first redundant node

Performance Evaluation

- Simulation Details

- One redundant node
- One video title
- 40,000 data blocks

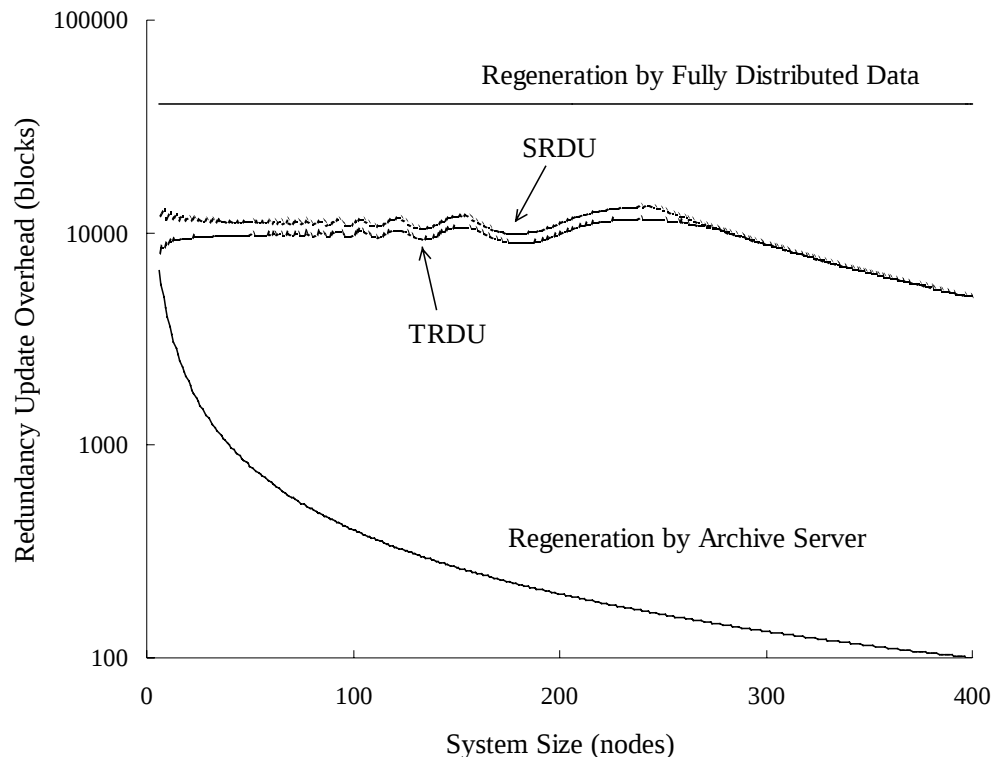
- Metric

- Redundancy Update Overhead

- Number of video data blocks needed to transmit for generating the new redundant data

Performance Evaluation

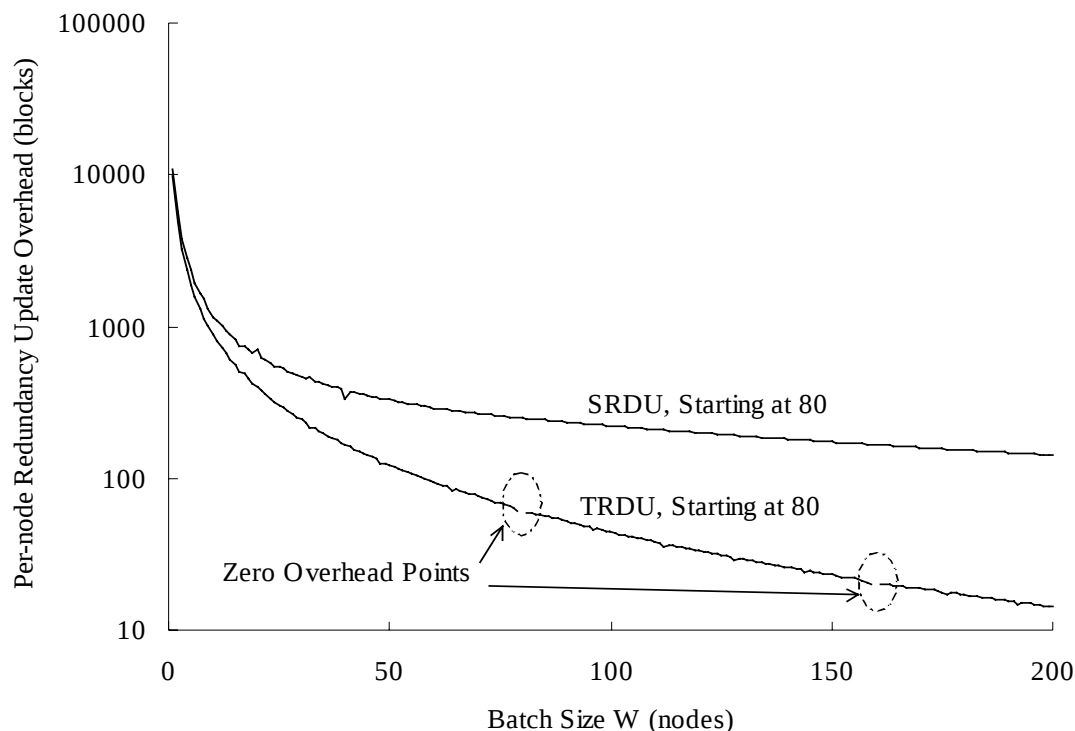
- Continuous system growth
 - Grow from 1 node to 400 nodes
 - One node added each time



Performance Evaluation

■ Batched redundancy update

- Defer update until a fixed number of nodes, W
- Initial system size = 80, W ranges from 1 to 200



Conclusion

- Reduce the redundancy update overhead significantly by
 - TRDU
 - Batched update
- Overhead in multiple redundant nodes is investigated
 - Additional overhead is insignificant

Future Works

- Node Removal
- Addition of redundant nodes
- Scheduling problem
- Optimal batch size

Thank you

- Q&A Section