#### Improving Gaussian Elimination on Multi-Core Systems

Marwa A. Al-Shandawely PDC/KTH

## Agenda

- Algorithm overview.
- Trivial parallelization.
- Problems.
- Sequential optimization
- Proposed solutions.
- Experimental results.
- Conclusions and future work.

### **Overview of forward elimination**

```
for i=1 to n-1
  find pivotPos in column i
   if pivotPos \neq i
     exchange rows(pivotPos,i)
   end if
   for j=i+1 to n
     A(i,j) = A(i,j)/A(i,i)
   end for j
  !$omp parallel do private ( i ,j )
   for j=i+1 to n+1
     for k=i+1 to n
         A(k,j) = A(k,j) - A(k,i) \times A(i,j)
      end for k
   end for j
end for i
```



### **Trivial OMP Speed up**



### Problems

- Poor data locality
- Pivoting is done by master thread
- Overheads of creating and destroying threads at each iteration
- Sequential optimization

### Sequential optimization

- Replace division by the constant pivot
- Avoid loop invariant access in the inner most loop
- Eliminate the check for pivot changing position
- Make use of fortran array notation



## **Cyclic Column distribution**

- Pivots array
- Locks array
- Pivot holder
  - Eliminate (i) on column(i+1)
  - Search (i+1)
  - Store pivot (i+1) position
  - Prepare colmn (i+1)
  - Free lock (i+1)
  - Eliminate (i) on rest of scope



Locks

# Cyclic Column distribution speed up



### What went wrong?!

- The original algorithm requires pivot columns to be prepared in order while the whole matrix is accessed for each pivot column.
- For large input sizes; the cache is evicted many times for each iteration and there is no reuse of data in the cache.
- False sharing on pivots and locks array.

Improving!

- Double elimination on pivot holders.
  - Knowledge of two pivots allow data reuse.
- Each column is an accumulation of eliminations using previous columns!
  - Make more pivots available each step and eliminate each column using several pivots while it is in the cache.

## **Cyclic Block distribution**

- Block of pivots
- Increase work/iter.
- Increase locality
- Less locks
- Load balancing?!



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### Speed up for block distribution

Original ----C=1 -----C=2  $\rightarrow$  C=3 **–\_\_**C=4 -C=5 

N = 2000

N = 5000

### Speed up as C=25



### **Conclusions and future work**

- Scalable performance on multicores is highly dependent on application implementation, data layout and access patterns.
- Cache and memory access optimization techniques is vital for performance despite the loss of readability.
- Future work:
  - Adaptive blocking scheme that changes the block size as a function of the matrix size, cache settings, and number of cores.

