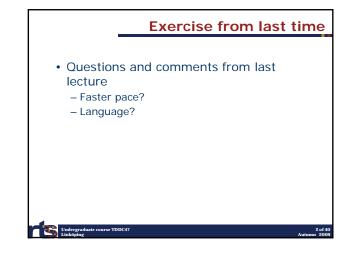
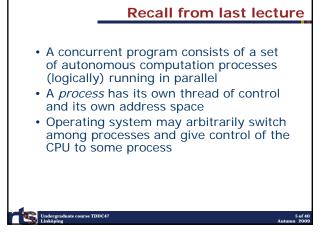
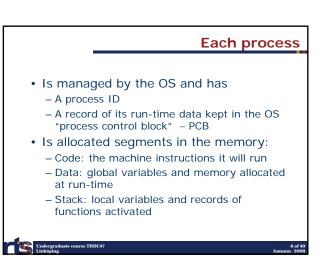
TDDC47 Real-time and Concurrent Programming Lecture 2: Processes and shared resources Simin Nadjm-Tehrani Real-time Systems Laboratory Department of Computer and Information Science Linköping university

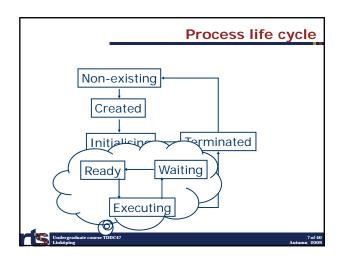


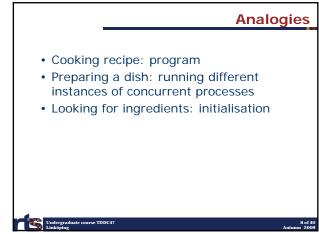




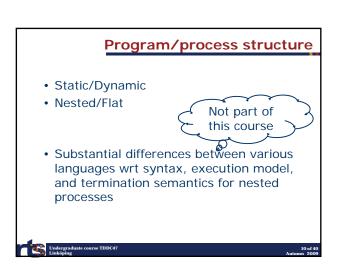


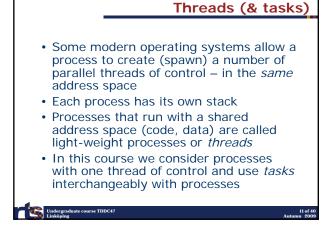


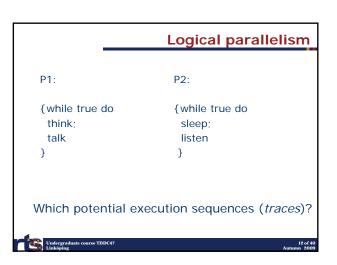




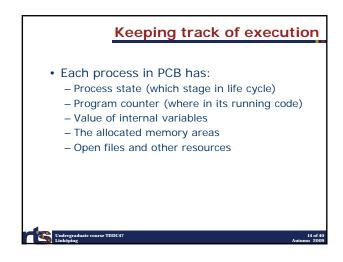
Programming for processes Typical real-time systems: Assembler, C Need support from OS to create, schedule and terminate tasks Languages with support for concurrent programming: Java, Ada Have their own run-time system and can explicitly create processes

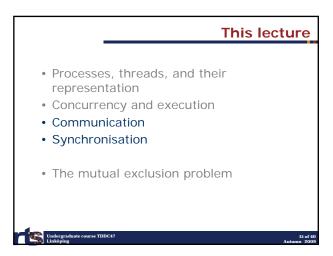


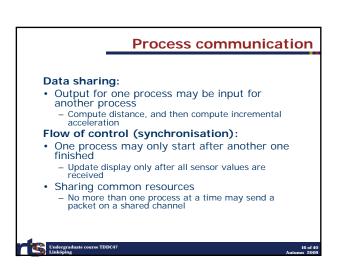


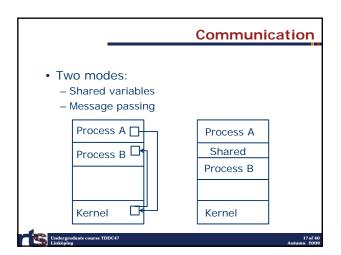


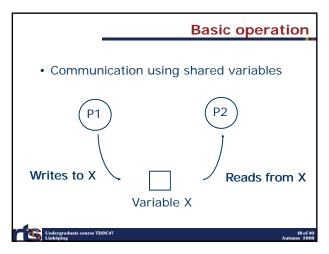
Context Switch Consider a program that consists of processes P1,..., P4 An execution of the concurrent program may look like: P2 P1 P4 P3 Context switch time Lindspan of the concurrent program may look like:











Problems?

- No! Since hardware memory can support atomic memory update, so that only one writes at a time
- But...
- Creates problems for more complex shared data structures
 - Update date, time and stock value
- One process may write at a faster rate than the other process reads
 - Register a call to a telecom server before serving it
 - Is the call on the register the earliest unserved one? Even if server is overloaded?



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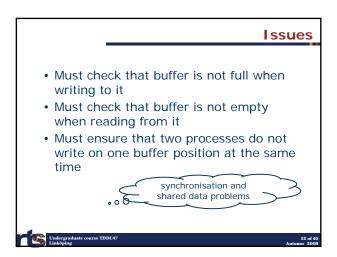
Race condition

- Consider two processes P1 and P2 that are allowed to write to a shared data structure
- If the order of updating the data structure by respective processes can affect the outcome of the computation then the system suffers from a *race condition*
 - Analogy: Deposit 5000kr in the account, calculate accrued interest
- Process synchronisation is used to avoid race conditions

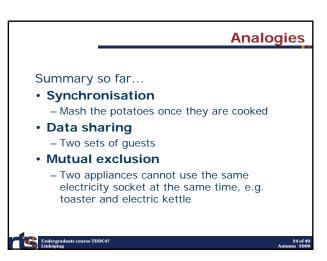
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• Finite buffers P1 Writes to buffer Finite buffer



Conditional action Examples: Compute the interest when all transactions have been processed Check that seats are available before booking Mutual exclusion Example: Two customers shall not be booked on the same seat



This lecture

- Processes, threads, and their representation
- · Concurrency and execution
- Communication
- Synchronisation
- The mutual exclusion problem

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Machine instructions

LD R, x // load register R from x INC R // increment register R ST R, x // store register R to x

• The program may then be compiled into many different interleavings

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PO: LD R, x PO: INC R P1: LD R, x P1: LD R, x P1: INC R P0: ST R, x

What is the value of x after this trace?

ST: R, x

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Atomic update

 To ensure single process update to a shared data area the application needs to manage the mutual exclusion problem!

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Mutual exclusion

 Consider n processes that need to exclude concurrent execution of some parts of their code

Fundamental problem to design entry and exit protocols for critical sections

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First attempt process P1 process P2 loop loop flag1 = up flag2 = up while flag2 == up do while flag1 == up do nothing nothing (* busy waiting *) (* busy waiting *) critical-section critical-section flag1 = down flag2 = down non-critical-section non-critical-section end [Dijkstra 1965]

```
Second attempt
process P1
                         process P2
                         loop
loop
  while flag2 == up do
                            while flag1 == up do
     nothing
                               nothing
     (* busy waiting *)
                               (* busy waiting *)
  flag1 = up
                            flag2 = up
  critical-section
                            critical-section
  flag1 = down
                            flag2 = down
  non-critical-section
                            non-critical-section
```

Third attempt process P2 process P1 loop loop while turn == 2 do while turn == 1 do nothing nothing (*busy waiting*) (*busy waiting*) critical-section critical-section turn = 2 turn = 1 non-critical non-critical section section end end

```
Peterson's algorithm

process P1
loop
flag1 = up
turn = 2
while flag2 == up and turn == 2 do
nothing
end
critical-section
flag1 = down
non-critical-section
end

timesping

Linksping

Peterson's algorithm

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```

Programming language support

- Implementing synchronisation and concurrency with shared variables, using only sequential programming constructs, is difficult and error prone
- Java: Early versions used Suspend/Resume constructs that led to race condition!
- Ada: built-in run-time support with explicit task synchronisation entry points (Rendezvous)
- Both have some support for defining concurrent processes but none has support for real-time in the core language

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Ada tasks: example procedure Morning is task body Take_Shower is task Get_Breakfast; task Take_Shower; begin Use_Shower; task body Get_Breakfast is Dry_Hair; end Take_Shower; begin Make_Coffee; Make_Toast; begin -- Morning Boil_Egg; null; end Morning; Eat_Breakfast; end Get_Breakfast;

```
public class Prepare Extends Thread
{
  private int items;
  public Prepare(int: Breakfast_items)
  {
    items = Breakfast_items
  }
  public void run()
  {
    while(true)
    {
       Cooking.Make(items);
    }
}
```

```
final int eggs = 1;
final int toast = 2;
final int coffee = 1;
Prepare P1 = new Prepare(eggs);
Prepare P2 = new Prepare(toast);
Prepare P3 = new Prepare(coffee);
. . .
P1.start();
P2.start();
P3.start();
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```

Further reading?

- An equivalent reading material to book chapters posted on the web can be found in an electronically available book from LiU Library through the ebrary service
- It uses Java syntax to describe similar code snippets
- Check out for the link on the literature page on the course web if interested!



