# Advanced Algorithmic Problem Solving Le 3 – Arithmetic

Fredrik Heintz

Dept of Computer and Information Science

Linköping University

## Overview



- Arithmetic
- Integer multiplication Karatsuba's algorithm
- Multiplication of polynomials Fast Fourier Transform
- Systems of linear equations Naïve Gaussian Elimination

### **Arithmetic**



- Range of default integer data types (C++)
  - unsigned int = unsigned long: 2<sup>32</sup> (9-10 digits)
  - unsigned long long: 2<sup>64</sup> (19-20 digits)
- How to represent 777!
- Operations on Big Integer
  - Basic: add, subtract, multiply, divide, etc
  - Use "high school method"

#### **Arithmetic**



- Greatest Common Divisor (Euclidean Algorithm)
  - GCD(a, o) = a
  - GCD(a, b) = GCD(b, a mod b)
  - int gcd(int a, int b) { return (b == o ? a : gcd(b, a % b)); }
- Least Common Multiplier
  - LCM(a, b) = a\*b / GCD(a, b)
  - int lcm(int a, int b) { return (a / gcd(a, b) \* b); }
    - // Q: why we write the lcm code this way?
- GCD/LCM of more than 2 numbers:
  - GCD(a, b, c) = GCD(a, GCD(b, c))
- Find d, x, y such that d = ax + by and d = GCD(a,b) (Extended Euclidean Algorithm)
  - EGCD(a,o) = (a,1,o)
  - EGCD(a,b)
    - (d',x',y') = EGCD(b, a mod b)
    - (d,x,y) = (d',y',x' a/b\*y')

#### **Arithmetic**



- Representing rational numbers.
  - Pairs of integers a,b where GCD(a,b)=1.
- Representing rational numbers modulo m.
  - The only difficult operation is inverse,  $ax = 1 \pmod{m}$ , where an inverse exists if and only if a and m are co-prime (gcd(a,m)=1).
  - Can be found using the Extended Euclidean Algorithm ax = 1 (mod m) => ax 1 = qm => ax qm = 1 (d, x, y) = EGCD(a,m) => x is the solution iff d = 1.

# Karatsuba's algorithm



- Using the classical pen and paper algorithm two n digit integers can be multiplied in O(n²) operations.
   Karatsuba came up with a faster algorithm.
- Let A and B be two integers with

• 
$$A = A_1 10^k + A_0, A_0 < 10^k$$

$$B = B_1 10^k + B_0, B_0 < 10^k$$

$$C = A*B = (A_1 10^k + A_0)(B_1 10^k + B_0)$$
$$= A_1 B_1 10^{2k} + (A_1 B_0 + A_0 B_1) 10^k + A_0 B_0$$

Instead this can be computed with 3 multiplications

$$T_o = A_o B_o$$

$$T_1 = (A_1 + A_0)(B_1 + B_0)$$

$$T_2 = A_1 B_1$$

• 
$$C = T_2 10^{2k} + (T_1 - T_0 - T_2) 10^k + T_0$$

#### Complexity of Karatsuba's Algorithm



 Let T(n) be the time to compute the product of two n-digit numbers using Karatsuba's algorithm.

Assume 
$$n = 2^k$$
.  $T(n) = \Theta(n^{\lg(3)})$ ,  $\lg(3) \approx 1.58$ 

■ 
$$T(n) \le 3T(n/2) + cn$$
  
 $\le 3(3T(n/4) + c(n/2)) + cn = 3^2T(n/2^2) + cn(3/2 + 1)$   
 $\le 3^2(3T(n/2^3) + c(n/4)) + cn(3/2 + 1)$   
 $= 3^3T(n/2^3) + cn(3^2/2^2 + 3/2 + 1)$   
...  
 $\le 3^iT(n/2^i) + cn(3^{i-1}/2^{i-1} + ... + 3/2 + 1)$   
...  
 $\le c3^k + cn[((3/2)^k - 1)/(3/2 - 1)]$  --- Assuming  $T(1) \le c$   
 $\le c3^k + 2c(3^k - 2^k) \le 3c3^{lg(n)} = 3cn^{lg(3)}$ 

# **Fast Fourier Transform**



See separate presentation

# Systems of Linear Equations



A system of linear equations can be presented in different forms

Standard form

Matrix form

# Solutions of Linear Equations (10)



$$\begin{vmatrix} x_1 \\ x_2 \end{vmatrix} = \begin{vmatrix} 1 \\ 2 \end{vmatrix}$$
 is a solution to the following equations:

$$x_1 + x_2 = 3$$

$$x_1 + 2x_2 = 5$$

# Solutions of Linear Equations



A set of equations is inconsistent if there exists no solution to the system of equations:

$$x_1 + 2x_2 = 3$$

$$2x_1 + 4x_2 = 5$$

These equations are inconsistent

# **Solutions of Linear Equations**



Some systems of equations may have infinite number of solutions

$$x_1 + 2x_2 = 3$$

$$2x_1 + 4x_2 = 6$$

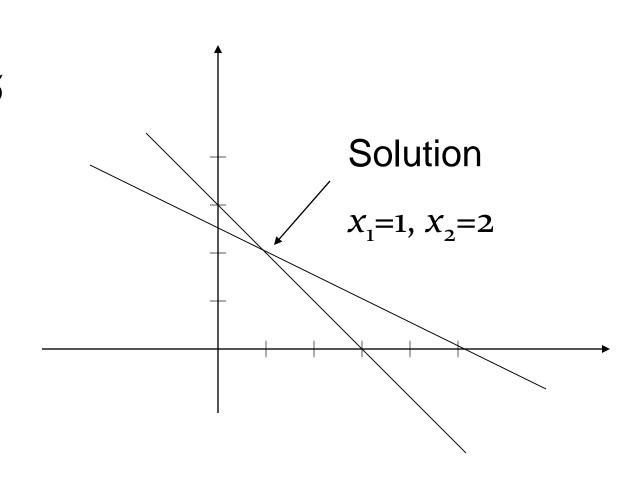
have infinite number of solutions

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} a \\ 0.5(3-a) \end{bmatrix}$$
 is a solution for all  $a$ 

#### **Graphical Solution of Systems of Linear Equations**



$$x_1 + x_2 = 3$$
$$x_1 + 2x_2 = 5$$



# Cramer's Rule is Not Practical



Cramer's Rule can be used to solve the system

$$x_{1} = \frac{\begin{vmatrix} 3 & 1 \\ 5 & 2 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 1, \quad x_{2} = \frac{\begin{vmatrix} 1 & 3 \\ 1 & 5 \end{vmatrix}}{\begin{vmatrix} 1 & 1 \\ 1 & 2 \end{vmatrix}} = 2$$

Cramer's Rule is not practical for large systems.

To solve N by N system requires (N + 1)(N - 1)N! multiplications.

To solve a 30 by 30 system,  $2.38 \times 10^{35}$  multiplications are needed.

It can be used if the determinants are computed in efficient way

# **Naive Gaussian Elimination**



- The method consists of two steps:
  - **Forward Elimination**: the system is reduced to **upper triangular form**. A sequence of **elementary operations** is used.
  - **Backward Substitution**: Solve the system starting from the last variable.

$$\begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \Rightarrow \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ 0 & a_{22}' & a_{23}' \\ 0 & 0 & a_{33}' \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} b_1 \\ b_2' \\ b_3' \end{bmatrix}$$

# **Elementary Row Operations**



- Adding a multiple of one row to another
- Multiply any row by a non-zero constant

# **Example:** Forward Elimination



$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 12 & -8 & 6 & 10 \\ 3 & -13 & 9 & 3 \\ -6 & 4 & 1 & -18 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ 26 \\ -19 \\ -34 \end{bmatrix}$$

Part 1: Forward Elimination

Step 1: Eliminate  $x_1$  from equations 2, 3, 4

$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 0 & -4 & 2 & 2 \\ 0 & -12 & 8 & 1 \\ 0 & 2 & 3 & -14 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ -6 \\ -27 \\ -18 \end{bmatrix}$$

# **Example:** Forward Elimination



Step2: Eliminate  $x_2$  from equations 3, 4

$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 0 & -4 & 2 & 2 \\ 0 & 0 & 2 & -5 \\ 0 & 0 & 4 & -13 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ -6 \\ -9 \\ -21 \end{bmatrix}$$

Step3: Eliminate  $x_3$  from equation 4

$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 0 & -4 & 2 & 2 \\ 0 & 0 & 2 & -5 \\ 0 & 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ -6 \\ -9 \\ -3 \end{bmatrix}$$

# **Example:** Forward Elimination



Summary of the Forward Elimination:

$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 12 & -8 & 6 & 10 \\ 3 & -13 & 9 & 3 \\ -6 & 4 & 1 & -18 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ 26 \\ -19 \\ -34 \end{bmatrix} \Rightarrow \begin{bmatrix} 6 & -2 & 2 & 4 \\ 0 & -4 & 2 & 2 \\ 0 & 0 & 2 & -5 \\ 0 & 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ -6 \\ -9 \\ -3 \end{bmatrix}$$

# **Example:** Backward Substitution



$$\begin{bmatrix} 6 & -2 & 2 & 4 \\ 0 & -4 & 2 & 2 \\ 0 & 0 & 2 & -5 \\ 0 & 0 & 0 & -3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 16 \\ -6 \\ -9 \\ -3 \end{bmatrix}$$

Solve for  $x_4$ , then solve for  $x_3$ ,...solve for  $x_1$ 

$$x_4 = \frac{-3}{-3} = 1,$$
  $x_3 = \frac{-9+5}{2} = -2$   
 $x_2 = \frac{-6-2(-2)-2(1)}{-4} = 1,$   $x_1 = \frac{16+2(1)-2(-2)-4(1)}{6} = 3$ 

### **Forward Elimination**



To eliminate  $x_1$ 

$$a_{ij} \leftarrow a_{ij} - \left(\frac{a_{i1}}{a_{11}}\right) a_{1j} \quad (1 \le j \le n)$$

$$b_i \leftarrow b_i - \left(\frac{a_{i1}}{a_{11}}\right) b_1$$

$$2 \le i \le n$$

To eliminate  $x_2$ 

$$a_{ij} \leftarrow a_{ij} - \left(\frac{a_{i2}}{a_{22}}\right) a_{2j} \quad (2 \le j \le n)$$

$$b_i \leftarrow b_i - \left(\frac{a_{i2}}{a_{22}}\right) b_2$$

$$3 \le i \le n$$

## **Forward Elimination**



To eliminate 
$$x_k$$

$$a_{ij} \leftarrow a_{ij} - \left(\frac{a_{ik}}{a_{kk}}\right) a_{kj} \quad (k \le j \le n)$$

$$b_i \leftarrow b_i - \left(\frac{a_{ik}}{a_{kk}}\right) b_k$$

$$k + 1 \le i \le n$$

Continue until  $x_{n-1}$  is eliminated.

## **Backward Substitution**



$$x_{n} = \frac{b_{n}}{a_{n,n}}$$

$$x_{n-1} = \frac{b_{n-1} - a_{n-1,n} x_{n}}{a_{n-1,n-1}}$$

$$x_{n-2} = \frac{b_{n-2} - a_{n-2,n} x_{n} - a_{n-2,n-1} x_{n-1}}{a_{n-2,n-2}}$$

$$b_{i} - \sum_{j=i+1}^{n} a_{i,j} x_{j}$$

$$x_{i} = \frac{a_{i,j} x_{j}}{a_{i,i}}$$

#### **Determinant**



The elementary operations do not affect the determinant Example:

$$A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 3 & 2 \\ 3 & 1 & 2 \end{bmatrix} \xrightarrow{\text{Elementary operations}} A' = \begin{bmatrix} 1 & 2 & 3 \\ 0 & -1 & -4 \\ 0 & 0 & 13 \end{bmatrix}$$

$$\det(A) = \det(A') = -13$$

# How Many Solutions Does a System of Equations AX=B Have?



Unique  $det(A) \neq 0$ reduced matrix has no zero rows

No solution det(A) = 0reduced matrix has one or more zero rows corresponding B elements  $\neq 0$ 

Infinite det(A) = 0reduced matrix has one or more zero rows corresponding B elements = 0

# Examples



#### Unique

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} X = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & -2 \end{bmatrix} X = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \quad \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} X = \begin{bmatrix} 2 \\ -1 \end{bmatrix} \quad \begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} X = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

solution:

$$X = \begin{bmatrix} 0 \\ 0.5 \end{bmatrix}$$

No solution

$$\begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix} X = \begin{bmatrix} 1 \\ 2 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} X = \begin{bmatrix} 2 \\ 3 \end{bmatrix} \qquad \begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} X = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} X = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

No solution

$$0 = -1 impossible!$$

infinte # of solutions

$$\begin{bmatrix} 1 & 2 \\ 2 & 4 \end{bmatrix} X = \begin{bmatrix} 2 \\ 4 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 \\ 0 & 0 \end{bmatrix} X = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$

Infinite# solutions

$$0 = -1 \text{ impossible!} \quad X = \begin{bmatrix} \alpha \\ 1 - .5 \alpha \end{bmatrix}$$

# **Pseudo-Code: Forward Elimination**



```
do k = 1 to n-1
   do i = k+1 to n
       factor = a_{i,k} / a_{k,k}
       do j = k+1 to n
                a_{i,i} = a_{i,i} - factor * a_{k,i}
       end do
       b_i = b_i - factor * b_k
   end do
end do
```

# Pseudo-Code: Back Substitution



```
x_n = b_n / a_{n,n}

do i = n-1 downto 1

sum = b_i

do j = i+1 to n

sum = sum - a_{i,j} * x_j

end do

x_i = sum / a_{i,i}

end do
```

#### **Problems with Naive Gaussian Elimination**



The Naive Gaussian Elimination may fail for very simple cases.
 (The pivoting element is zero).

$$\begin{bmatrix} 0 & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

Very small pivoting element may result in serious computation errors

$$\begin{bmatrix} 10^{-10} & 1 \\ 1 & 1 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} 1 \\ 2 \end{bmatrix}$$

### **How Do We Know If a Solution is Good or Not**



#### Given AX=B

X is a solution if AX-B=o

Compute the residual vector R= AX-B

Due to rounding error, R may not be zero

The solution is acceptable if  $\max_{i} |r_i| \le \varepsilon$ 

## **How Good is the Solution?**



$$\begin{bmatrix} 1 & -1 & 2 & 1 \\ 3 & 2 & 1 & 4 \\ 5 & -8 & 6 & 3 \\ 4 & 2 & 5 & 3 \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 1 \\ 1 \\ 1 \\ -1 \end{bmatrix}$$
 solution 
$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} -1.8673 \\ -0.3469 \\ 0.3980 \\ 1.7245 \end{bmatrix}$$

Residues: 
$$R = \begin{bmatrix} 0.005 \\ 0.002 \\ 0.003 \\ 0.001 \end{bmatrix}$$

# Summary



- Arithmetic
- Integer multiplication Karatsuba's algorithm
- Multiplication of polynomials Fast Fourier Transform
- Systems of linear equations Naïve Gaussian Elimination