Lecture 7

An extensible array, amortised analysis, common pitfalls

TDDD86: DALP

Utskriftsversion av Lecture in *Data Structures, Algorithms and Programming Paradigms* September 19th, 2023

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1 An extensible array

1.1 Dynamic memory

Fields/array

type name[length];

- a fix field; can not be resized

- type* name = new type[length];
 - a dynamically allocated array;
 - assignment can be done later, to change the array size
 - memory allocated dynamically must be freed manually otherwise there will be *memory leaks* in the program
- · there are other differences between the two syntax
 - the objects are stored in different part of the memory; the first syntax uses the *stack* while the other use the *heap*

Free memory

- delete[] name;
 - Free the memory associated with the pointer
 - Must be called for all fields created with **new** type[]
 - * Otherwise, the program has a memory leak (No garbage collector unlike in Java)
 - * Leaked memory is freed when the program exit, but for applications with long running time a memory leak can lead to exhausting the computer memory

7.3

7.1

```
int * a = new int[3];
a[0] = 42;
a[1] = -5;
a[2] = 17;
for (int i = 0; i < 3; i++) {
    cout << i << ":_" << a[i] << endl;
}
...
delete[] a;
```

1.2 ArrayList

Example

- Write a class that implements an array of integers
 - We call it ArrayList
 - Behavior:

```
add(value) insert(index, value)
get(index) set(index, value)
size() isEmpty()
remove(index)
indexOf(value) contains(value)
toString()
...
```

- The size of the list will be the number of elements inserted so far
 - The actual length of the array (capacity) can be larger. Start with a size of 10 by default.

1.3 Destructor

Destructor

- // ClassName.h // ClassName.cpp ~ClassName(); ClassName::~ClassName() { ...
 - Called when the object is destroyed by the program (when the object goes out of scope or delete is used)
 - Can be useful to:
 - * free temporary resources
 - * free dynamically allocated memory used by the members
- Does ArrayList need a destructor? What should it do?
 - Yes; to free the memory associated with storing elements

1.4 Increase capacity

Increase capacity

index	0	1	2	3	4	5	6	7	8	9
value	3	8	9	7	5	12	4	8	1	6
size	10	capacity		10						

• What if the users wants to add more than ten elements?

list.add(75) //add a 11th element

index	0	1	2	3	4	5	6	7	8	9	10	11	12	13	14	15	16	17	18	19
value	3	8	9	7	5	12	4	8	1	6	75	0	0	0	0	0	0	0	0	0
size	11	С	ара	acit	y	20														

• Answer: double the size of the field

7.4

7.5

- Do not forget to release the memory used by the old array!

```
- int* a = new int[10];
int* b = new int[20];
std::copy(a, a+10, b); // Do not use memcpy(b, a, 10 * sizeof(int))!
a = b;
delete[] a;
std::copy(first, after, output);
```

7.8

7.9

2 Amortised analysis

An extensible array

We want a new type of array that automatically increase available size when full (when the number of ellements n is same as the capacity N). Suppose the array always insert new element in the first free position:

- Allocate a new array *B* with capacity 2*N*
- Copy A[i] to B[i], for i = 0, ..., N-1
- Lets A = B, we let B take over the role A had.

In term of effectiveness, expanding the array is slow. But the algorithmic complexity is:

- O(1) most of the time
- O(n) for copying *n* element and O(1) for inserting after reallocation.

Amortised analyse

Using *amortisation* we can show that a sequence of insertion of element to our expandable array is effective:

Proposition 1. Let *S* be a table implemented using an extensible array *A*, as previous. The total time to insert *n* element in *S*, starting with an empty table *S* (which means that *A* has capacity N = 1) is O(n).

3 Common C++ mistakes and pitfalls

delete vs delete[]

- Memory allocated with **new** must be freed with **delete**. Memory allocated with **new**[] must be freed with **delete**[]
- Using **delete** for memory allocated with **new**[] means only one destructor is called and it leads to a crash
- can be tested with memory tracking tools, e.g., valgrind

int* q = new int; delete q;

int* p = new int[20]; delete[] p;

Dynamic memory

- Common error is to forget to free
- Solution:
 - Memory model, with parent/child hierarchy
 - Smart pointers (based on the principle of resource acquisition is initialisation)

#include <memory>

```
using namespace std;
shared_ptr<int> foo(shared_ptr<int> ptr) {
    shared_ptr<int> lptr = ptr;
    if(lptr)
      ++(*lptr);
    return lptr;
}
```

```
int main() {
    shared_ptr<int> aptr = make_shared<int>(41);
    shared_ptr<int> bptr = foo(aptr);
    cout << "answer_is_" << *bptr << endl;
    return 0;
}</pre>
```

```
Returning a reference to a temporary
```

int& f()
{
 int a;
 return a;
}

Throwing exception from destructor

```
class A
{
public:
     ~A() { throw 0; }
};
void f()
{
    A a;
    throw 0;
}
int main()
{
    try { f(); }
    catch(int ) { }
    return 0;
}
```

• C++ does not know what to do when two exceptions are thrown in parallel!

Using Invalidated Iterators and Pointers

- When modifing a container, assume the old iterator is not valid anymore!
- For instance when removing elements:

```
std::vector<int> v{3,4,12,-1,4,5};
 for(auto it = v.begin(); it != v.end(); ++it)
 {
   if(*it == 4) { v.erase(it); } // it invalid after the erase!
 }
 Instead:
 std::vector<int> v{3,4,12,-1,4,5};
 for(auto it = v.begin(); it != v.end(); )
   if (*it == 4) { it = v.erase(it); } // new it is valid after the erase!
   else { ++it; }
 }
· Or adding elements:
 std::vector<int> v{3,4,12,-1,4,5};
 auto it = v.begin();
 int * first = &v[0];
 v.push_back(2);
 //it and first are not valid because of the push_back
 std::cout << *it << "_" << *first << std::endl; //bad</pre>
```

7.14

7.11

7.12

Use C++ library as much as possible instead of the the C standard library

- Most C functions have C++ equivalents and are safer to use:
- For instance use std::copy and not memcpy:

```
memcpy(dst, src, length * sizeof(int));
std::copy(src, src + length, dst);
```

• Use std::string and not C-strings:

```
const char* s1 = "hello";
const char* s2 = "hello";
if(s1 == s2)
{
  std::cout << "Never_shown!" << std::endl;
}
```

• Use ifstream or ofstream and not fopen, printf, fclose

Conversion

- C++ automatically convert most numbers without warning
- Integer division even though saving into float:

int nX = 7; int nY = 2; float fValue = nX / nY; // fValue = 3 (not 3.5!)

Fixed with:

```
float fValue = static_cast<float>(nX) / nY; // fValue = 3.5
```

· mixing signed and unsigned integers

```
unsigned u = 10;
int i = -42;
cout << i + i << endl; // -84
cout << u + i << endl; // 4294967265</pre>
```

Side effects

• Should the following print 25, 30 or 36?

```
void multiply(int x, int y)
{
    using namespace std;
    cout << x * y << endl;
}
int main()
{
    int x = 5;
    multiply(x, ++x);
}</pre>
```

• order of evaluation of arguments is undefined!

Switch statements without break

```
switch(v)
{
    case 1:
        str = "one";
    case 2:
        str = "two";
    case 1:
        str = "three";
    ...
};
```

7.17

7.16

• The correct way is:

```
switch(v)
{
    case 1:
        str = "one";
    break;
    case 2:
        str = "two";
    break;
    case 1:
        str = "three";
    break;
    ...
};
```

4 vector vs dequeue

push_back: vector and dequeue

```
// Vector test code
vector<int> v;
// v.reserve(N); // Preallocate
// Insert at the start of the vector
for (int i = 0; i < N; i++)
    v.push_back(i);
// Clear by using pop_front (erase)
for (int i = 0; i < N; i++)
    v.pop_back();
// Deque test code
deque<int> d;
// Insert elements using push_front
for (int i = 0; i < N; i++)</pre>
```

d.push_back(i);
// Clear by using pop_front
for (int i = 0; i < N; i++)
 d.pop_back();</pre>

	<vector></vector>	<vector> reserve</vector>	<deque></deque>
N = 10000	30	30	50
N = 100000	180	180	333
N = 1000000	1712	1723	3.136
N = 10000000	17114	17051	33419

push_front: vector and dequeue

// Vector test code vector<int> v; // Insert at the start of the vector for (int i = 0; i < N; i++) v.insert(v.begin(), i); // Clear by using pop_front (erase) for (int i = 0; i < N; i++) v.erase(v.begin()); // Deque test code deque<int> d; // Insert elements using push_front for (int i = 0; i < N; i++) d.push_front(i); // Clear by using pop_front

for (int i = 0; i < N; i++)
d.pop_front();</pre>

7.19

	<vector></vector>	<deque></deque>
N = 10000	4974	117
N = 100000	937467	463
N = 1000000	ТО	6275
N = 10000000	ТО	34810