

## Auto-tunable Multi-Backend Skeleton Programming Library for Multi-GPU Systems

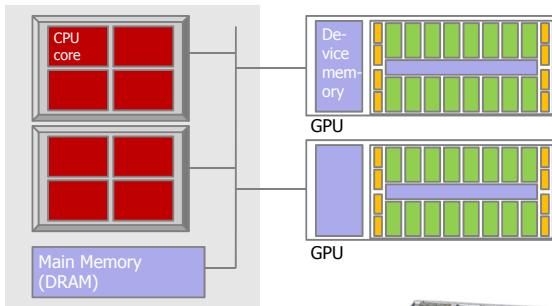
Usman Dastgeer

Johan Enmyren

Christoph Kessler

Linköping University, Sweden

### Multi-GPU Systems



### Challenges

- Portability
- Programmability
- Performance portability

OpenCL™ ? Portable but low-level code...

### Solution: Skeleton Programming

*Skeletons* are pre-defined, reusable, parameterizable generic components with well defined semantics, for which efficient parallel or accelerator-specific implementations may be available.

- Higher-order functions
- for frequent algorithmic (control and data flow) patterns e.g. map, reduce, scan, farm, pipe, DC, ...
- parameterized in sequential user code, programmer interface is sequential
- encapsulate all parallelism and platform-specific implementation details
- well suited for internal autotuning
- enforce well structured code

### SkePU Example: Dot product

```
#include <iostream>
#include "skepu/vector.h"
#include "skepu/mapreduce.h"

BINARY_FUNC(plus, double, a, b,
    return a+b;
)

BINARY_FUNC(mult, double, a, b,
    return a*b;
)
....
```

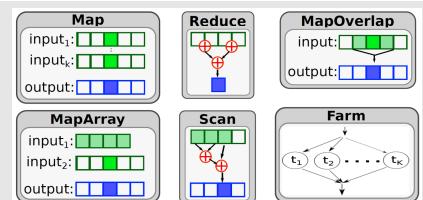
Create a skeleton instance

```
int main()
{
    skepu::MapReduce<mult, plus>
        dotProduct(new mult, new plus);
    skepu::Vector<double> v0(...);
    skepu::Vector<double> v1(...);
    double r = dotProduct( v0, v1 );
    std::cout << "Result: " << r << "\n";
    return 0;
}
```

Platform-specific code for user-defined functions generated from such macros

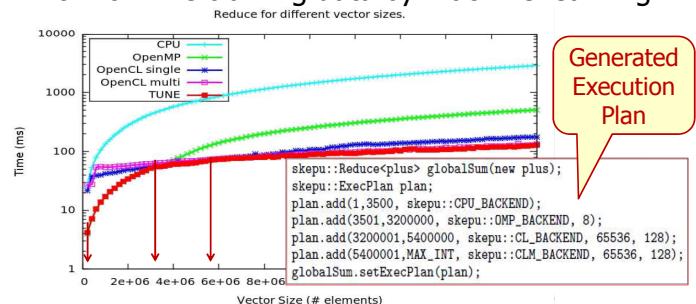
### SkePU

- C++ template library
- 6 data-parallel skeletons
  - map, reduce, scan, mapreduce, maparray, mapoverlap (stencil)
- 1 task-parallel skeleton: farm
  - All skeleton calls execute asynchronously, synchronized automatically by operand data flow
- Smart containers for operand data: Vector, Matrix, ...
  - Software caching of sub-arrays in device memories, sequentially consistent
  - Optimizing PCIe communication and memory management at runtime
- Generation of platform-specific user functions
- Back-ends for C, OpenMP, OpenCL, CUDA, StarPU, (MPI)
- Multi-GPU support
- Overhead below 10%
- Tunable



### Offline-tunable selection

- Expected best back-end + tunable parameters: #threads, #thread blocks, tiling factor, ...
- Execution plan for each skeleton, generated from off-line training data by machine learning

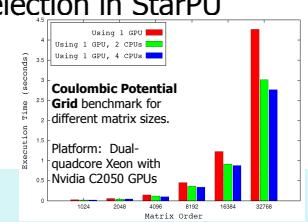


### On-line tunable selection

- Using the history-guided selection in StarPU

### Hybrid execution

- CPUs + GPUs in parallel



### Selected publications

- J. Enmyren, C. Kessler: **SkePU: A Multi-Backend Skeleton Programming Library for Multi-GPU Systems.** Proc. 4th Int. Worksh. on High-Level Parallel Progr. and Applications (HLPP-2010), Baltimore, USA, Sep. 2010. ACM.
- U. Dastgeer, J. Enmyren, C. Kessler: **Auto-tuning SkePU: A Multi-Backend Skeleton Programming Framework for Multi-GPU Systems.** Proc. IWMSE-2011, Hawaii, USA, May 2011, ACM.
- U. Dastgeer, C. Kessler, S. Thibault. **Flexible runtime support for efficient skeleton programming on hybrid systems.** ParCo'11: Int. Conf. on Parallel Computing. Ghent, Belgium, 2011.
- U. Dastgeer, C. Kessler: **Smart Containers and Skeleton Programming for GPU-based systems.** HLPP'14, Amsterdam, NL, July 2014.