

Dynamic Optimization of Modelica Models – Language Extensions and Tools

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Content

- Background
- Dynamic optimization
- Software tools
- Optimica

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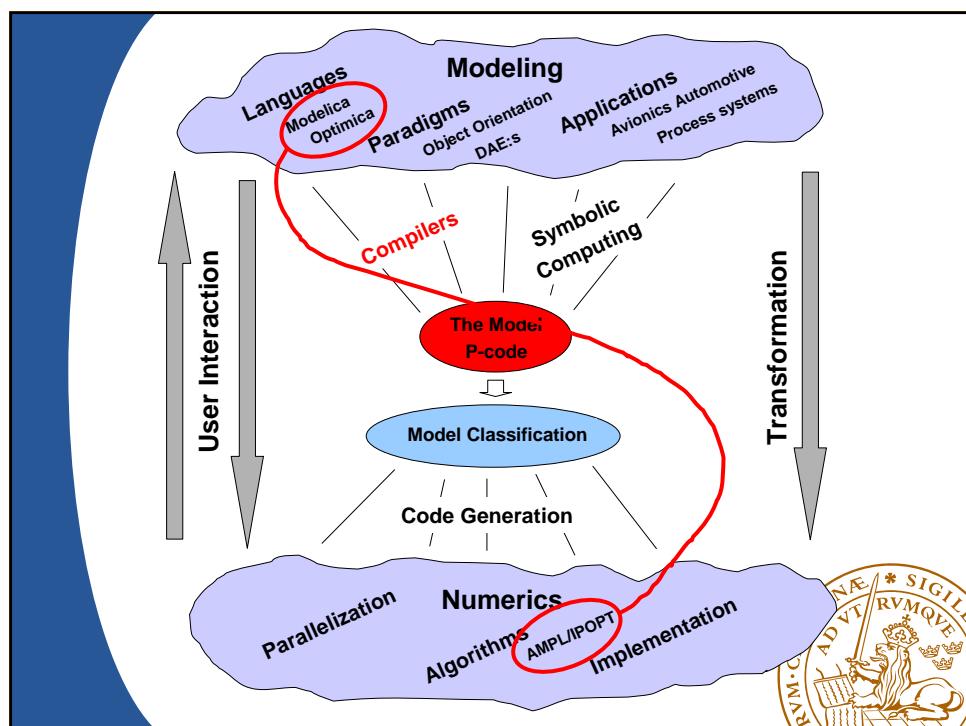


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Background

- Modelica is increasingly used in industry
 - Expert knowledge
 - Capital \$\$\$
- Usages so far
 - Simulation (mainly)
- Other usages emerge
 - Sensitivity analysis
 - Optimization
 - Model reduction
 - System identification
 - Control design
- Usages reported so far
 - Cope with software interfaces designed for simulation...

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Dynamic Optimization

- New abstractions
 - Cost (objectives), constraints, optimization of parameters and functions, cases
 - Initial guesses
 - Transcription method (discretization)
- Requirements
 - Sensitivities
 - Derivatives
 - Jacobians
 - Hessians
 - Sparsity patterns

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JModelica – Project Objectives

- Shift focus:
 - from **encoding** optimization problem
 - to **problem formulation**
- Enable dynamic optimization of Modelica models
 - State of the art numerical algorithms
- Develop a high level description language for optimization problems
 - Extension of the Modelica language
- Develop prototype tools
 - JModelica and The Optimica Compiler
- Case study
 - Plate reactor start-up optimization (see paper)

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A Dynamic Optimization Problem

$$\min_{u,p} J(x, u, p, t_f) = \min_{u,p} \left\{ \int_0^{t_f} L(x, u, p) dt + \phi(x_f) \right\}$$

subject to

$$F(\dot{x}, x, u, p) = 0, \quad (\text{DAE dynamics})$$

$$g_0(x_0) = 0 \quad (\text{initial conditions})$$

$$g_f(x_f) = 0 \quad (\text{terminal constraint})$$

$$r_i(x(t), u(t)) \leq 0 \quad (\text{inequality path constraints})$$

$$r_e(x(t), u(t)) = 0 \quad (\text{equality path constraints})$$

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Dynamic Optimization

- Many algorithms
 - Applicability highly model-dependent (ODE, DAE, PDE, hybrid...)
 - Active area of research
- User must specify additional information
 - Discretization mesh
 - Discretization scheme
- Heavy programming burden to use numerical algorithms
- Engineering need for high-level descriptions
 - Extend Modelica to support dynamic optimization

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Key Abstractions in Optimization

- Optimization parameters
- Cost – what to minimize
- Objectives (multi-objective optimization)
- Cases
- Bounds on variables
 - Not a generalization of Modelica's chi-jack attributes
- Constraints
- Initialization information

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Software – Motivation

- Code generation requires syntax trees
 - *"The final syntax tree before code generation"*
 - Dymola – not available
 - OpenModelica – August 2005: RML...?
- Subset of Modelica sufficient initially
 - No “hybrid” constructs
 - Start in small scale
- Java
 - Safe language
 - Rapid development
 - Standard library
 - Not so slow...
- JastAdd
 - Compiler construction framework

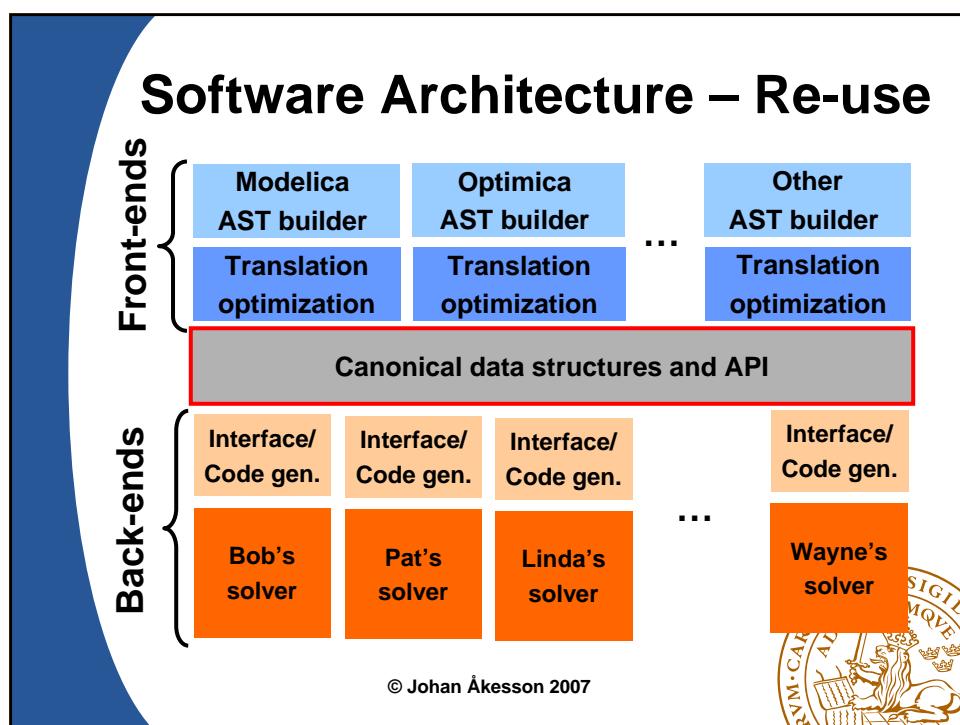
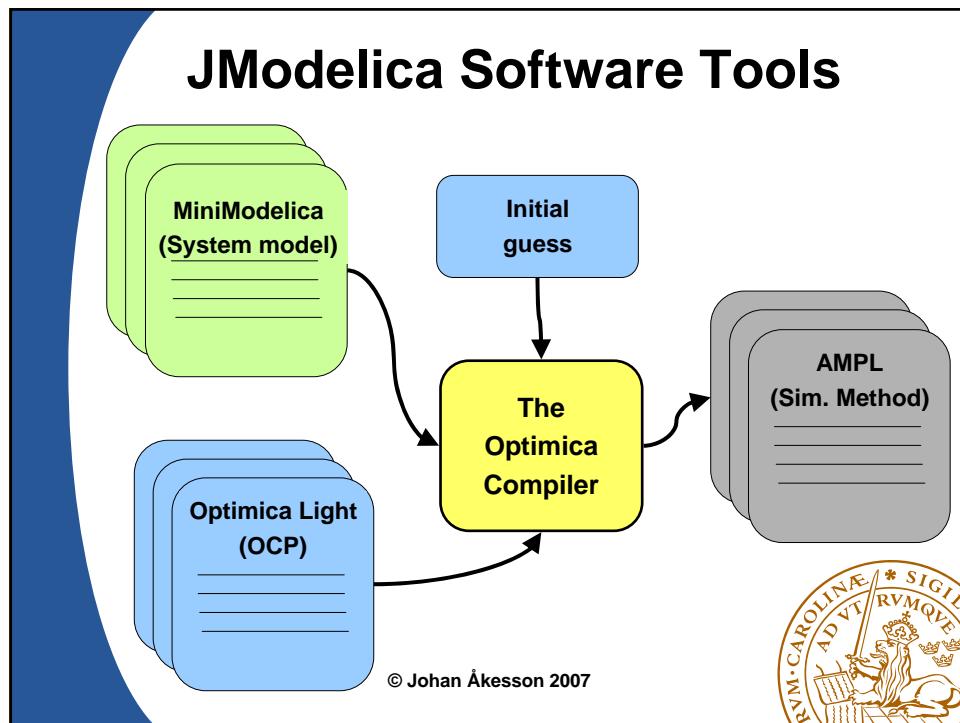
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The JModelica Project – Status

- Parsing of full Modelica 2.2
 - Standard library (2.2) parsed in approx 15 s
 - Name and type lookup + error check: 5 s
 - Improved error message generation
 - Dude, don't use if-clauses. It is not good for ya...
- *Partial support* for instantiation
 - Classes, components, connections, modifications...
 - Partial support for arrays
 - Smoothing of discontinuities (min, max)
- Testing based on JUnit framework
- Prototype specification of Optimica
 - Description of an optimization problem
 - The Optimica Compiler: Code generation to AMPL/IPOPT
- Applications
 - Extensively used for start-up optimization of plate reactor
 - Two master's thesis projects spring 2007: vehicle dynamics

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Language Extension Objections

- Use annotations?
 - Optimization problems have a rich structure – need for efficient language constructs
 - Annotations cannot be modified
- Language maintenance?
 - Modularization of specification
 - Modularization of implementation
 - JastAdd
 - Natural evolution of Modelica
 - Simulation → Optimization

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Extension Concepts

- Enhanced class: `optmodel`
- Superimpose information on elements
 - Introduce new attributes for `Real`
 - New built-in package `Optimica`
 - Concept from aspect orientation
- New sections
 - `optimization`
 - Superimpose information
 - Meshes and discretization
 - `subject to`
 - Constraints
- New built-in functions
 - `minimize`: cost function
 - `integrate`: integration
 - `instantValue`: Instant time values of variables $x(t_i)$

Optimica – Basic Constructs

$$\begin{aligned}\dot{x} &= v \quad x(0) = 0 \\ \dot{v} &= u \quad v(0) = 0\end{aligned}$$

Modelica

```
model DoubleIntegrator
  Real u;
  Real x(start=0);
  Real v(start=0);
equation
  der(x) = v;
  der(v)=u;
end DoubleIntegrator
```

$$\begin{aligned}x(1) &= 1 & u \leq 1, & \int_0^t 1 dt \\ v(1) &= 0 & u \geq -1 &\end{aligned}$$

Optimica

```
optmodel OCP
  DoubleIntegrator di;
  optimization
    di.u(lowerBound=1,
          upperBound=-1);
  equation
    minimize(integrate(1));
  subject to
    terminal di.x=1;
    terminal di.v=0;
  end DoubleIntegrator
```

Optimica – Specification of Discretization Scheme

```
package Optimica
  record Mesh
    Real meshPoints [:];
    ...
  end Mesh;
  package Collocation
    record LagrangeCollocation
      Real collocationPoints [:];
      ...
    end LagrangeCollocation;
    record DiscretizationSpec
      Mesh mesh;
      LagrangeCollocation lc;
    end DiscretizationSpec;
  end Collocation;
end Optimica
```

- Built-in package Optimica
 - Mesh
 - Collocation
- Essential information
 - Closer to algorithms
- Data structures
- Similar to annotations



Optimica – Specification of Discretization Scheme: Example

```
optmodel OCP
  DoubleIntegrator di;
  Optimica.Mesh mesh(...);
  Optimica.LagrangeCollocation lc(...);
optimization
  di.u(lowerBound=1,
        upperBound=-1);
  extends Optimica.Collocation.
    DiscretizationScheme(mesh=mesh,
                         lc=lc);
equation
  minimize(integrate(1));
subject to
  terminal di.x=1;
  terminal di.v=0;
end DoubleIntegrator
```

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Summary

- JModelica and The Optimica Compiler
 - Extensible compiler
 - Front-end supporting subset of Modelica
 - Back-end for code generation to AMPL
- Optimica
 - Extension of Modelica for optimization
- Case study
 - See paper

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Thank you!
Questions?

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