Electronic Transactions on Artificial Intelligence
Vol. 4 (2000), Section A: pp. *23-43*
http://www.ep.liu.se/ej/etai/2000/003/

Refereed Article

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Interleaving Planning and Execution in a Multiagent Team Planning Environment

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Abstract: *Agents in a multiagent system may need to share information and services. For this, they need to be able to interleave deliberative planning with execution of actions. The deliberative planning is needed to decide which actions to perform to achieve an objective, whereas execution of some of the actions is needed to make a more informed decision on the other actions and to access services provided by other agents.*

HITaP is a planner that interleaves planning and execution: using HITaP an agent can, during planning, gather information by either direct inspection of the domain or by firing queries to other agents and recording their answers. Interleaving planning and execution, as provided by HITaP, plays a crucial role in an agent's ability to construct shared plans with other agents and to manage the negotiation process that leads to agreement with the agent's teammates on these plans.

HITaP is implemented and currently used as planning module for agents in the RETSINA multiagent system. These agents cooperate to solve problems in different domains that range from portfolio management to command and control decision support systems.

Publication and review history

1. First version *received* by the research area "Planning and Scheduling" of the Electronic Transactions on Artificial Intelligence, posted on its web site, and advertised in its Newsletter on 15.3.2000.

2. First version *published* by Linköping University Electronic Press on 21.12.2000 and permanently available at
   http://www.ep.liu.se/ea/cis/2000/018/

3. Publicly *discussed* in the ETAI area of Planning and Scheduling during March-July, 2000. The discussion protocol is available and will be retained in the Article Interaction Page at
   http://www.etaij.org/ra/pas/006/

4. First version conditionally *accepted* after due refereeing and according to scientific journal standards by the Electronic Transactions on Artificial Intelligence (ETAI) on 15.12.2001.

5. Revised version, with minor corrections according to the suggestions of the referees, *published* by Linköping University Electronic Press on 20.3.2001 and permanently available at
   http://www.ep.liu.se/ea/cis/2000/018/
   under the label "Revised publication 2001-03-20".

6. Revised version *accepted* on 30.1.2001.

7. Revised version appears in Electronic Transactions on Artificial Intellligence, Volume 4 (2000), section A, pages 23–43. The section and the annual volume are made permanently available at
   http://www.ep.liu.se/ej/etai/2000/

8. Paper editions of the ETAI issue and the ETAI volume containing this artice *republished* by the Royal Swedish Academy of Sciences.

The review policy and the quality requirements for acceptance are documented at http://www.etaij.org/info/

Article maintenance

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Besides the publication and review history, it contains links for contacting the author(s), as well as to amendments and other related information for the article. It is intended to keep these links up-to-date in the future.

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